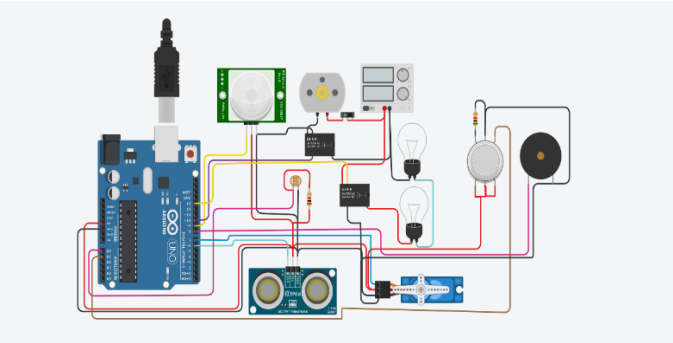
DEPARTMENT OF INFORMATION TECHNOLOGY

IOT-ASSIGNMENT-1

Name: Dhanushkodi k



include <Servo.h>

int output1Value = 0;

int sen1Value = 0;

int sen2Value = 0;

int const gas_sensor = A1;

int const LDR = A0;

int limit = 400;

long readUltrasonicDistance(int triggerPin, int echoPin)

{

  pinMode(triggerPin, OUTPUT);

  digitalWrite(triggerPin, LOW);

  delayMicroseconds(2);

// Sets the trigger pin to HIGH state for 10 microseconds

  digitalWrite(triggerPin, HIGH);

  delayMicroseconds(10);

  digitalWrite(triggerPin, LOW);

```
  pinMode(echoPin, INPUT);
  return pulseIn(echoPin, HIGH);
}

Servo servo_7;

void setup()
{
   Serial.begin(9600);
  pinMode(A0, INPUT)
  pinMode(A1,INPUT);
  pinMode(13, OUTPUT);
  servo_7.attach(7, 500, 2500);

  pinMode(8,OUTPUT);
  pinMode(9, INPUT);
  pinMode(10, OUTPUT);
  pinMode(4, OUTPUT);
  pinMode(3, OUTPUT);

}

void loop()
{

int val1 = analogRead(LDR);
  if (val1 > 500)
```

```
 {
          digitalWrite(13, LOW);
   Serial.print("Bulb ON = ");
   Serial.print(val1)
}
 else
{
   digitalWrite(13, HIGH);
    Serial.print("Bulb OFF = ");
   Serial.print(val1);
}

sen2Value = digitalRead(9);
 if (sen2Value == 0)
 {
   digitalWrite(10, LOW);
   digitalWrite(4, HIGH);
   digitalWrite(3, LOW);
   Serial.print("     || NO Motion Detected    " );
 }

 if (sen2Value == 1)
 {
    digitalWrite(10, HIGH);
   delay(3000);
   digitalWrite(4, LOW);
   digitalWrite(3, HIGH);
```

```
    Serial.print("              || Motion Detected!      " );
  }
  delay(300);

      // ------- Gas Sensor --------//
int val = analogRead(gas_sensor);
  Serial.print("|| Gas Sensor Value = ");
  Serial.print(val);
//val = map(val, 300, 750, 0, 100);
  if (val > limit)
  {
    tone(8, 650);
  }
 delay(300);
 noTone(8);
   sen1Value = 0.01723 * readUltrasonicDistance(6, 6);

  if (sen1Value < 100)
  {
    servo_7.write(90);
    Serial.print("              || Door Open!  ; Distance = ");
    Serial.print(sen1Value);
   Serial.print("\n");

  }
  else
  {
```

```
    servo_7.write(0);
    Serial.print("              || Door Closed! ; Distance =  ");
    Serial.print(sen1Value);
    Serial.print("\n");
  }
  delay(10);
}
```