

# PROJECT DEVELOPMENT PHASE

## SPRINT-1

### IOT DEVICE

Team ID	PNT2022TMID11653
Project Name	IoT Based Safety Gadget for Child Safety Monitoring and Notification
Maximum Marks	10 marks

#### AIM:

To get the coordinates of the child using GPS & ESP32.

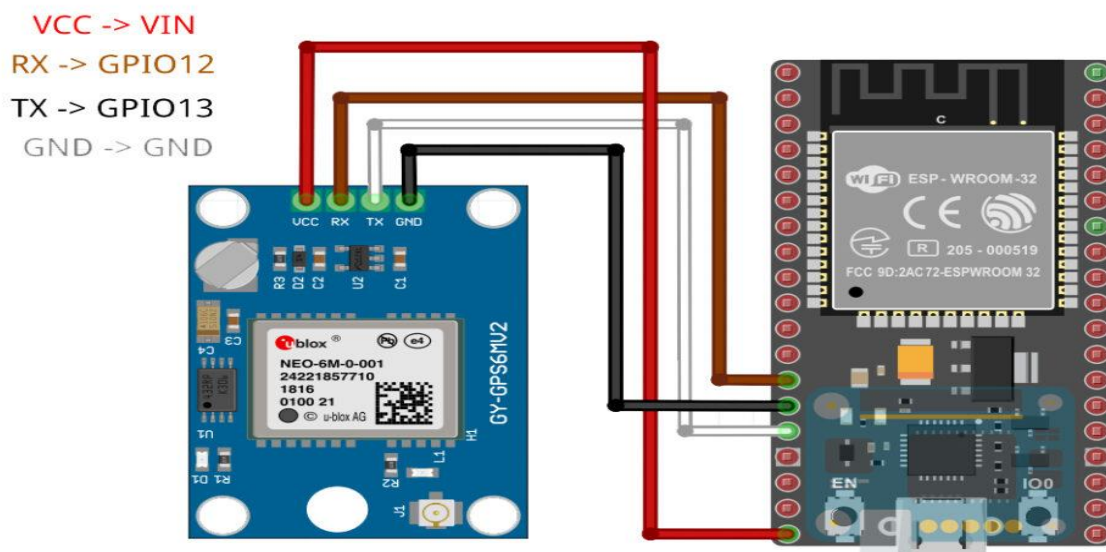
#### HARDWARE REQUIRED:

- ❖ ESP32-WROOM-32U
- ❖ NEO-6M GPS Module
- ❖ Micro-USB Cable
- ❖ Connecting wires

#### SOFTWARE REQUIRED:

- ❖ Arduino IDE to run the program.

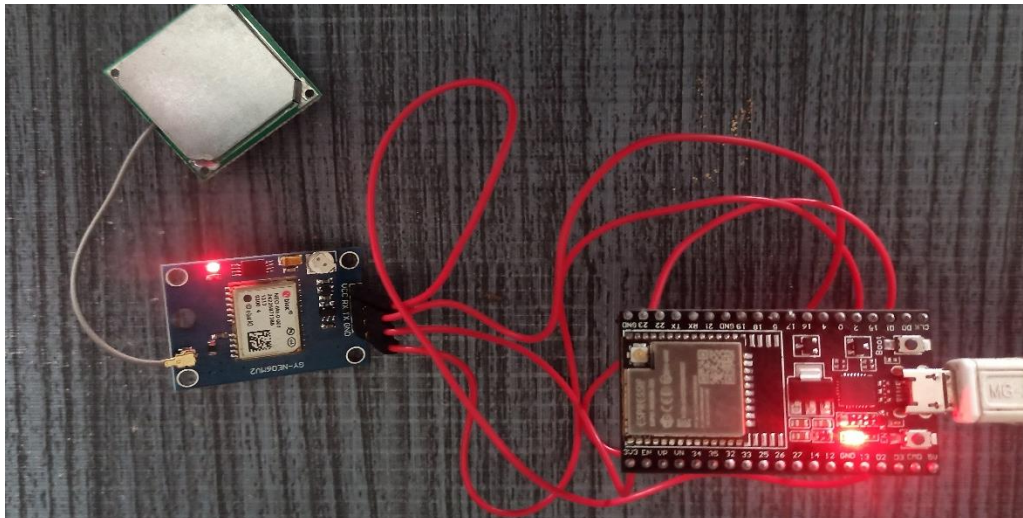
#### CIRCUIT DIAGRAM:



## PIN CONNECTION:

ESP32 board	NEO-6M Module
VCC = 5V	VCC
RX0	TX
TX0	RX
GND	GND

## WIRE CONNECTION:



## SOURCE CODE FOR COORDINATES:

```
#include <TinyGPSPlus.h>
TinyGPSPlus gps;
void setup()
{
    Serial.begin(9600);
    Serial2.begin(9600);
    delay(3000);
}
void loop()
{
    while (Serial2.available() > 0)
    if (gps.encode(Serial2.read()))
        displayInfo();
}
```

```

    if (millis() > 5000 && gps.charsProcessed() < 10)
    {
        Serial.println(F("No GPS detected: check wiring."));
        while (true);
    }
}

void displayInfo()
{
    Serial.print(F("Location: "));
    if (gps.location.isValid())
    {
        Serial.print("Lat: ");
        Serial.print(gps.location.lat(), 6);
        Serial.print(F(", "));
        Serial.print("Lng: ");
        Serial.print(gps.location.lng(), 6);
        Serial.println();
    }
    else
    {
        Serial.print(F("INVALID"));
    }
}

void updateSerial()
{
    delay(500);
    while (Serial.available())
    {
        Serial2.write(Serial.read()); //Forward what Serial received to Software Serial Port
    }
    while (Serial2.available())
    {
        Serial.write(Serial2.read()); //Forward what Software Serial received to Serial Port
    }
}

```

## Output:

gps\_demo | Arduino 1.8.19 (Windows Store 1.8.57.0)

File Edit Sketch Tools Help

```
gps_demo $  
#include <TinyGPSPlus.h>  
TinyGPSPlus gps;  
void setup() {  
  Serial2.begin(9600);  
  Serial2.begin(9600);  
  delay(3000);  
}  
void loop() {  
  while (Serial2.available() > 0)  
    if (gps.encode(Serial2.read()))  
      displayInfo();  
  if (millis() > 5000 && gps.charsProcessed() < 10)  
  {  
    Serial.println(F("No GPS detected: check wiring."));  
    while (true);  
  }  
}  
void displayInfo()  
{  
  Serial.print(F("Location: "));  
  if (gps.location.isValid()) {  
    Serial.print("Lat: ");  
    Serial.print(gps.location.lat(), 6);  
    Serial.print(F(", "));  
    Serial.print("Lng: ");  
    Serial.print(gps.location.lng(), 6);  
    Serial.println();  
  }  
  else  
  {  
    Serial.print(F("INVALID"));  
  }  
}  
void updateSerial()  
{  
  delay(500);  
  while (Serial2.available())  
  {  
    Serial2.read();  
  }  
}
```

COMS

13:51:01.420 -> Location: Lat: 10.908532,Lng: 76.979312  
13:51:02.447 -> Location: Lat: 10.908532,Lng: 76.979312  
13:51:03.425 -> Location: Lat: 10.908532,Lng: 76.979312  
13:51:04.428 -> Location: Lat: 10.908532,Lng: 76.979312  
13:51:05.445 -> Location: Lat: 10.908532,Lng: 76.979312  
13:51:06.449 -> Location: Lat: 10.908532,Lng: 76.979312  
13:51:07.449 -> Location: Lat: 10.908532,Lng: 76.979312  
13:51:08.461 -> Location: Lat: 10.908532,Lng: 76.979312  
13:51:09.460 -> Location: Lat: 10.908532,Lng: 76.979312  
13:51:10.418 -> Location: Lat: 10.908532,Lng: 76.979312

☒ Autoscroll ☒ Show timestamp Newline 115200 baud Clear output