

(DIVYA T)

IBM-Assignment 1-MAKE A SAMRT HOME IN TINKERCAD,USING 2+ SENSORS LEDS BUZZER IN SINGLE CODE AND CIRCUIT

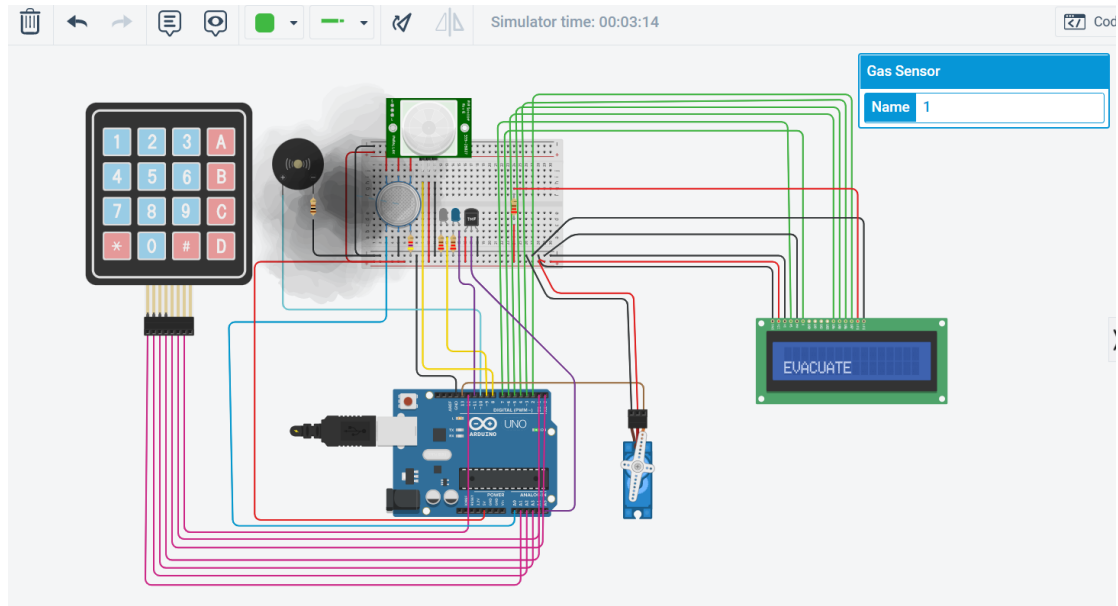
Project Title:

Real-Time River Water Quality Monitoring And Control System

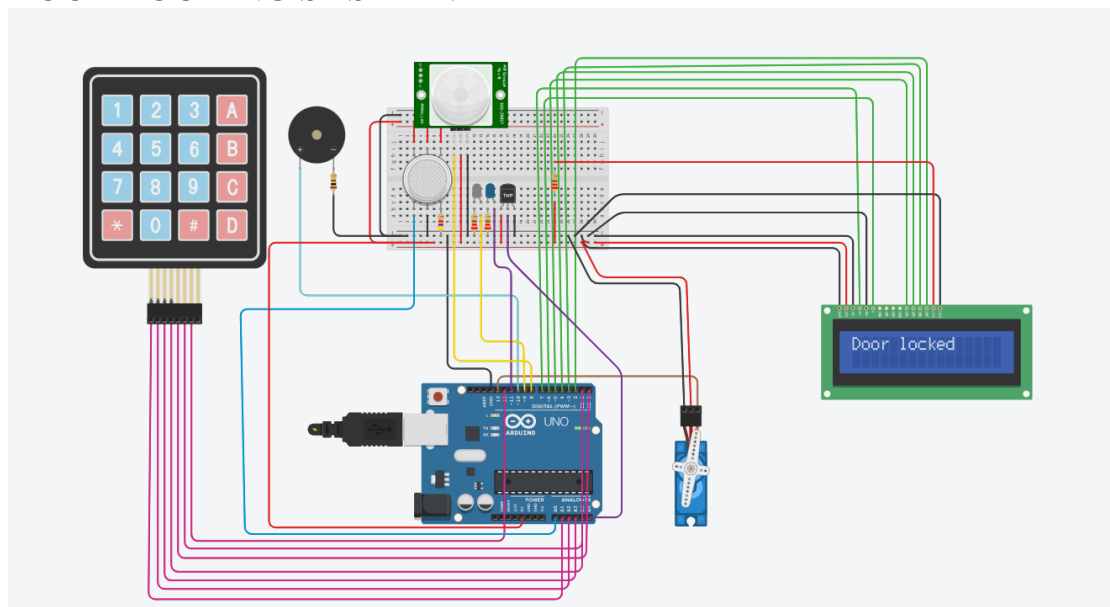
Team ID:PNT2022TMID29879

Circuit:

GAS LEAKAGE DETECTION:



DOOR LOCKING SYSTEM:



```

#include <Servo.h>
#include <Keypad.h>
// include the library code:
#include <LiquidCrystal.h>

const byte rows=4; //initializing 4 rows
const byte cols=3; //initializing 3 columns

// initialize the library by associating any needed LCD interface pin
// with the arduino pin number it is connected to
const int rs = 7, en = 6, d4 = 5, d5 = 4, d6 = 3, d7 = 2;
LiquidCrystal lcd(rs, en, d4, d5, d6, d7); //defines pin numbers for LCD
char key[rows][cols]={
  {'1','2','3'},
  {'4','5','6'},
  {'7','8','9'},
  {'*','0','#'}
};
byte rowPins[rows]={ A1,A2,A3,A4 }; //defines pin number for rows
byte colPins[cols]={0,1,2}; //defines pin numbers for columns
Keypad keypad= Keypad(makeKeymap(key),rowPins,colPins,rows,cols);

int counter = 0;
int buzzer = 10;
int gasSensor=A0;
int sensorThresh= 400;
String password = "4567"; //declaring the password as 4567
String pressed = ""; // checks the pressed password
Servo servo1; //defining servo motor
int currentposition=1;

int PIRsensor = 0;

int tmpPin = A5;
int reading = 0;
float vout = 0;
float temperature = 0;
int AC =11;
int idealTemperature=25;

void setup() {
  pinMode (buzzer,OUTPUT);

```

```

pinMode (gasSensor,INPUT);
servo1.attach(13); //defines pin number for servo
lcd.begin(16,2); //specifying the LCD size in columns and rows

pinMode(8, INPUT);
pinMode(AC, OUTPUT);
pinMode(9, OUTPUT);
pinMode(tmpPin, INPUT);

servo1.write(0); //Door closed initially

}

void loop() {
  reading = analogRead(tmpPin);
  vout = reading*5.0/1023;
  temperature = (vout-0.5)*100;
  if(temperature>idealTemperature)
  {digitalWrite(AC, HIGH);
  lcd.clear();
  lcd.setCursor(0,0);
  lcd.print("AC is turned on");
  delay(1000);
  lcd.clear();}
  else
  {digitalWrite(AC, LOW);}

  // read the state of the sensor/digital input
  PIRsensor = digitalRead(8);
  // check if sensor pin is HIGH. if it is, set the
  // LED on.

  if (PIRsensor == HIGH) {

    digitalWrite(9, HIGH);
    lcd.clear();
    lcd.setCursor(0,0);
    lcd.print("Motion detected!");
    delay(1000);
    lcd.clear();
  } else {
    digitalWrite(9, LOW);
  }
}

```

```
}
```

```
delay(10); // Delay a little bit to improve simulation performance
```

```
char key = keypad.getKey();//read key pressed on keypad and assign it  
to the variable char key
```

```
if(int(key)!=0) //checks whether any input is pressed
```

```
{
```

```
  if(key=='0'){
```

```
    reset();
```

```
    initializeLcd();
```

```
  }
```

```
  else if (key=='*')//check if key is equal to *
```

```
  {
```

```
    checkPassword();
```

```
  }
```

```
  else if(key=='#')//check if key is equal to #
```

```
  {
```

```
    lockDoor();//user-defined function
```

```
  }
```

```
  else
```

```
  {
```

```
    pressed.concat(key);//string concatenation
```

```
    lcd.setCursor(currentposition,1);
```

```
    lcd.print("*");//prints * on LCD display
```

```
    currentposition++;
```

```
    if(currentposition==5)
```

```
      currentposition=1;
```

```
  }
```

```
}
```

```
int analogValue = analogRead (gasSensor);
```

```
if (analogValue>sensorThresh )
```

```
{tone(buzzer,1000,6000);
```

```
  lcd.clear();
```

```
  lcd.setCursor(0,0);
```

```
  lcd.print("ALERT");
```

```
  lcd.setCursor(0,1);
```

```
  lcd.print("Gas detected");
```

```
  delay(1000);
```

```
  lcd.clear();
```

```

    lcd.setCursor(0,1);
    lcd.print("EVACUATE");
    delay(1000);
    lcd.clear();
}
else
{
    noTone(buzzer);

}
}

```

```

void initializeLcd(){
    lcd.clear();
    lcd.print("PASSWORD:");
    lcd.setCursor(1,1);//setting cursor to row 2,column 2
    servo1.write(0);//Door closed initially
}

```

```

void checkPassword()
{
    if (pressed==password){//check if the pressed key matches with the
actual password
    lcd.clear();
    lcd.setCursor(0,0);
    lcd.print("Access Granted!");
    servo1.write(90); //Door opened
    }
    else{
    lcd.clear();
    lcd.setCursor(0,0);
    lcd.print("Access denied!");
    servo1.write(180); //Door closed
    }
}

```

```

void lockDoor(){
    lcd.clear();
    lcd.setCursor(0,0);
    lcd.print("Door locked");
    servo1.write(180); //Door closed
}

```

```
void reset()
{
  pressed=""; //clear pressed password
  lcd.clear();
  lcd.setCursor(0,0);
  lcd.print("Resetting...");
  delay(500); //displays Resetting for half a second
}
```

```
void incorrect()
{
  delay(500);
  lcd.clear();
  lcd.setCursor(1,0);
  lcd.print("CODE");
  lcd.setCursor(6,0);
  lcd.print("INCORRECT");
  lcd.setCursor(15,1);
  lcd.println(" ");
  lcd.setCursor(4,1);
  lcd.println("GET AWAY!!!");
}
```