ASSIGNMENT-4

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Question:

write code and connection in wokwi for ultrasonic sensor.whenever distance is less 100cms send alert to ibm cloud and display indevice recent events.

solution:

```
#include <WiFi.h>
#include <PubSubClient.h>


void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);

//-------credentials of IBM Accounts------

#define ORG "qguokr"//IBM ORGANITION ID
#define DEVICE_TYPE "arduino_uno"//Device type mentioned in ibm watson IOT
Platform
#define DEVICE_ID "ultrasonic_sensor"//Device ID mentioned in ibm watson
IOT Platform
#define TOKEN "89101112"     //Token String data3;
float dist;
//-------- Customise the above values -------- char server[] = ORG
".messaging.internetofthings.ibmcloud.com";// Server Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in which
data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd  REPRESENT command type AND COMMAND IS
TEST OF FORMAT STRING
char authMethod[] = "use-token-auth";// authentication method char token[] = TOKEN;
```

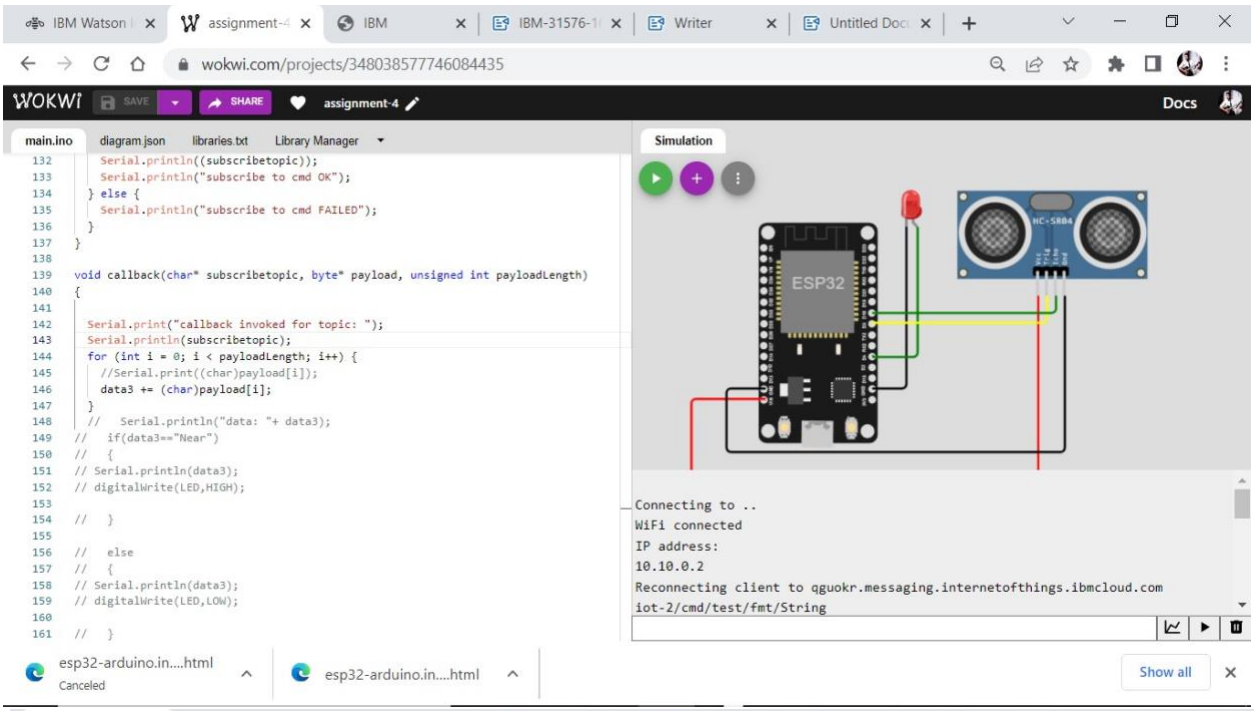
```
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id

//----------------------------------------
WiFiClient wifiClient; // creating the instance for wificlient PubSubClient client(server, 1883, callback
,wifiClient); //calling the predefined client id by passing parameter like server id,portand wificredential

int LED = 4; int trig = 5;
int echo = 18; void
setup()
{
Serial.begin(115200);
pinMode(trig,OUTPUT);
pinMode(echo,INPUT);
pinMode(LED, OUTPUT);
delay(10); wificonnect();
mqttconnect();
}
void loop()// Recursive Function
{
 digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);
  float dist = (dur * 0.0343)/2;
  Serial.print ("Distancein cm");
  Serial.println(dist);

  PublishData(dist);
  delay(1000);
  if (!client.loop()) {
    mqttconnect();
  }
}
```

```
/*.....retrieving to
Cloud.....*/

void PublishData(float dist) {
  mqttconnect();//function call for connecting to ibm
  /*
    creating the String in in form JSon to update the data to ibm cloud   */
  String object;   if (dist
<100)
  {
   digitalWrite(LED,HIGH);
   Serial.println("object is near");
   object = "Near";
  }
  else
  {
   digitalWrite(LED,LOW);
   Serial.println("no object found");
   object = "No";
  }
  String payload = "{\"distance\":";
  payload += dist;
  payload += "," "\"object\":\"";
  payload += object;
  payload += "\"}";

  Serial.print("Sending payload: ");
  Serial.println(payload);

  if (client.publish(publishTopic, (char*) payload.c_str())) {     Serial.println("Publish ok");// if it sucessfully
upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed
  } else
 {
```

```
    Serial.println("Publish failed");
  }
}
void mqttconnect() {   if
(!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    }
     initManagedDevice();
     Serial.println();
  }
}
void wificonnect() //function defination for wificonnect
{
  Serial.println();
  Serial.print("Connecting to ");
  WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");   }
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
}
 void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
```

```
  }
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
  }
  //   Serial.println("data: "+ data3);
//   if(data3=="Near")
//   {
// Serial.println(data3);
// digitalWrite(LED,HIGH);
//   }
//   else
//   {
// Serial.println(data3);
// digitalWrite(LED,LOW);
//   } data3="";
}
```

reference:https://wokwi.com/projects/348038577746084435




```
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{

  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
  }
  //   Serial.println("data: "+ data3);
//   if(data3=="Near")
//   {
// Serial.println(data3);
// digitalWrite(LED,HIGH);

//   }

//   else
//   {
// Serial.println(data3);
// digitalWrite(LED,LOW);

//   }
```