

ASSIGNMENT-4

STUDENT NAME	VIGNESH.V
TEAM ID	PNT2022TMID36746

Question:

write code and connection in wokwi for ultrasonic sensor. whenever distance is less 100cms send alert to ibm cloud and display in device recent events.

solution:

```
#include <WiFi.h>
#include <PubSubClient.h>

void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);

//-----credentials of IBM Accounts-----

#define ORG "qguokr"//IBM ORGANITION ID
#define DEVICE_TYPE "arduino_uno"//Device type mentioned in ibm watson IOT
Platform
#define DEVICE_ID "ultrasonic_sensor"//Device ID mentioned in ibm watson
IOT Platform
#define TOKEN "89101112" //Token
String data3;
float dist;
//----- Customise the above values -----
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server
Name
char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of
event perform and format in which data to be send
char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT
command type AND COMMAND IS TEST OF FORMAT STRING
```

```

char authMethod[] = "use-token-auth";// authentication method
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id

//-----
WiFiClient wifiClient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wifiClient); //calling the
predefined client id by passing parameter like server id,portand
wificredential

int LED = 4;
int trig = 5;
int echo = 18;
void setup()
{
  Serial.begin(115200);
  pinMode(trig,OUTPUT);
  pinMode(echo,INPUT);
  pinMode(LED, OUTPUT);
  delay(10);
  wificonnect();
  mqttconnect();
}
void loop()// Recursive Function
{
  digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur = pulseIn(echo,HIGH);
  float dist = (dur * 0.0343)/2;
  Serial.print ("Distancein cm");
  Serial.println(dist);

  PublishData(dist);
  delay(1000);
}

```

```

    if (!client.loop()) {
        mqttconnect();
    }
}

/*.....retrieving to
Cloud.....*/

void PublishData(float dist) {
    mqttconnect();//function call for connecting to ibm
    /*
        creating the String in in form JSon to update the data to ibm cloud
    */
    String object;
    if (dist <100)
    {
        digitalWrite(LED, HIGH);
        Serial.println("object is near");
        object = "Near";
    }
    else
    {
        digitalWrite(LED, LOW);
        Serial.println("no object found");
        object = "No";
    }
    String payload = "{\"distance\":";
    payload += dist;
    payload += ", \" \" \"object\":";
    payload += object;
    payload += "\"}\"";

    Serial.print("Sending payload: ");
    Serial.println(payload);

    if (client.publish(publishTopic, (char*) payload.c_str())) {

```

```
    Serial.println("Publish ok");// if it sucessfully upload data on the
cloud then it will print publish ok in Serial monitor or else it will
print publish failed
```

```
    } else
    {
        Serial.println("Publish failed");
    }
}

void mqttconnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        while (!!!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }
        initManagedDevice();
        Serial.println();
    }
}
```

```
void wificonnect() //function defination for wificonnect
```

```
{
    Serial.println();
    Serial.print("Connecting to ");
    WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to
establish the connection
```

```
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }

    Serial.println("");
    Serial.println("WiFi connected");
    Serial.println("IP address: ");
    Serial.println(WiFi.localIP());
}
```

```
void initManagedDevice() {
```

```

    if (client.subscribe(subscribetopic)) {
        Serial.println((subscribetopic));
        Serial.println("subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength)
{
    Serial.print("callback invoked for topic: ");
    Serial.println(subscribetopic);
    for (int i = 0; i < payloadLength; i++) {
        //Serial.print((char)payload[i]);
        data3 += (char)payload[i];
    }
    // Serial.println("data: "+ data3);
    // if(data3=="Near")
    // {
    // Serial.println(data3);
    // digitalWrite(LED, HIGH);
    // }
    // else
    // {
    // Serial.println(data3);
    // digitalWrite(LED, LOW);
    // }
    data3=" ";
}

```

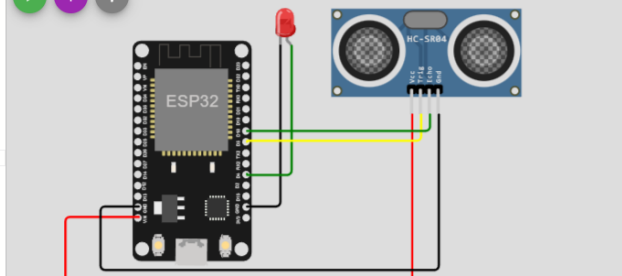
reference:<https://wokwi.com/projects/348038577746084435>

WOKWI

main.ino

```
132 Serial.println(subscribetopic);
133 Serial.println("subscribe to cmd OK");
134 } else {
135   Serial.println("subscribe to cmd FAILED");
136 }
137 }
138
139 void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
140 {
141   Serial.print("callback invoked for topic: ");
142   Serial.println(subscribetopic);
143   for (int i = 0; i < payloadLength; i++) {
144     //Serial.print((char)payload[i]);
145     data3 += (char)payload[i];
146   }
147   // Serial.println("data: " + data3);
148   // if(data3=="Near")
149   // {
150   //   // Serial.println(data3);
151   //   // digitalWrite(LED,HIGH);
152   // }
153   // }
154   // else
155   // {
156   //   // Serial.println(data3);
157   //   // digitalWrite(LED,LOW);
158   // }
159   // }
160   // }
```

Simulation



Connecting to ..
WiFi connected
IP address:
10.10.0.2
Reconnecting client to qguokr.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String

esp32-arduino.in...html
Canceled

esp32-arduino.in...html

Show all

