

```
import
time

import RPi.GPIO as GPIO
GPIO.setmode(GPIO.BOARD)
GPIO.setup(11, GPIO.OUT)
GPIO.setup(12, GPIO.OUT)
GPIO.setup(13, GPIO.OUT)


while True:
    GPIO.output(11,True) ## Turn on redLed
    time.sleep(1)        ## Wait for one second
    GPIO.output(11,False) ## Turn off redLed
    time.sleep(1)        ## Wait for one second
    GPIO.output(12,True) ## Turn on yellowLed
    time.sleep(1)        ## Wait for one second
    GPIO.output(12,False) ## Turn off yellowLed
    time.sleep(1)        ## Wait for one second
    GPIO.output(13,True) ## Turn on greenLed
    time.sleep(1)        ## Wait for one second
    GPIO.output(13,False) ## Turn off greenLed
    time.sleep(1)        ## Wait for one second
```

21 lines (19 sloc) | 715 Bytes

RawBlame

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2  import RPi.GPIO as GPIO
3  GPIO.setmode(GPIO.BOARD)
4  GPIO.setup(11, GPIO.OUT)
5  GPIO.setup(12, GPIO.OUT)
6  GPIO.setup(13, GPIO.OUT)
7
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9  while True:
10     GPIO.output(11,True) ## Turn on redLed
11     time.sleep(1)        ## Wait for one second
12     GPIO.output(11,False) ## Turn off redLed
13     time.sleep(1)        ## Wait for one second
14     GPIO.output(12,True) ## Turn on yellowLed
15     time.sleep(1)        ## Wait for one second
16     GPIO.output(12,False) ## Turn off yellowLed
17     time.sleep(1)        ## Wait for one second
18     GPIO.output(13,True) ## Turn on greenLed
19     time.sleep(1)        ## Wait for one second
20     GPIO.output(13,False) ## Turn off greenLed
21     time.sleep(1)        ## Wait for one second
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