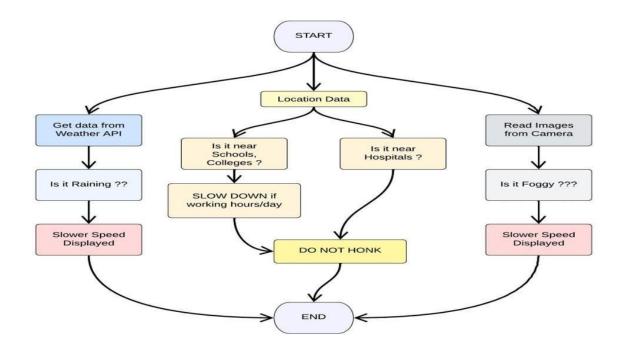
SPRINT 01

| Date | 06 November 2022 |
|--------------|--|
| Team ID | PNT2022TMID18923 |
| Project Name | Project – Signs with Smart Connectivity for Better Road Safety |

SPRINT GOALS:

- 1. Create and initialize accounts in various public APIs like OpenWeather API.
- 2. Write a Python program that outputs results given the inputs like weather and location.

CODE FLOW:



PROGRAM CODE:

Weather.py

This file is a utility function that fetches the weather from OpenWeatherAPI. Itreturns only certain required parameters of the API response.

```
# Python code
import requests as reqs
def
 get(myLocation,APIKE
 Y):apiURL =
f"https://api.openweathermap.org/data/2.5/weather?q={myLocation}&appi
d={API KEY}"
 responseJSON =
 (reqs.get(apiURL)).json()
 returnObject = {
   "temperature": responseJSON['main']['temp'] - 273.15,
    "weather": [responseJSON['weather'][ ]['main'].lower() for in
range(len(responseJSON['weather']))],
   "visibility": responseJSON['visibility']/100, # visibility in
percentage where 10km is 100% and 0km is 0%
 }
 if("rain" in responseJSON):
   returnObject["rain"] = [responseJSON["rain"][key]
for key inresponseJSON["rain"]]
 return(returnObject
```

brain.py

This file is a utility function that returns only essential information to be displayed at the hardware side and abstracts all the unnecessary details. This is where the code flow logic is implemented.

```
# Python code
# IMPORT SECTION STARTS
import weather
from datetime import datetime as dt
# IMPORT SECTION ENDS
# UTILITY LOGIC SECTION STARTS
def processConditions(myLocation,APIKEY,localityInfo):
  weatherData = weather.get(myLocation,APIKEY)
  finalSpeed = localityInfo["usualSpeedLimit"] if "rain" not in weatherData else
localityInfo["usualSpeedLimit"]/2
  finalSpeed = finalSpeed if weatherData["visibility"]>35 else finalSpeed/2
  if(localityInfo["hospitalsNearby"]):
    # hospital zone
    doNotHonk = True
  else:
    if(localityInfo["schools"]["schoolZone"]==False):
      # neither school nor hospital zone
```

```
doNotHonk = False
else:
    # school zone
    now = [dt.now().hour,dt.now().minute]
    activeTime = [list(map(int,_.split(":"))) for _ in
localityInfo["schools"]["activeTime"]]
    doNotHonk = activeTime[0][0]<=now[0]<=activeTime[1][0] and
activeTime[0][1]<=now[1]<=activeTime[1][1]

return({
    "speed" : finalSpeed,
    "doNotHonk" : doNotHonk
})

# UTILITY LOGIC SECTION ENDS</pre>
```

Main.py

The code that runs in a forever loop in the microcontroller. This calls all the util functions from other python files and based on the return value transduces changes in the output hardware display.

Python code

```
import brain
# IMPORT SECTION ENDS
#
# USER INPUT SECTION STARTS
myLocation = "Chennai,IN"
APIKEY = "bf4a8d480ee05c00952bf65b78ae826b"
localityInfo = {
 "schools": {
   "schoolZone": True,
   "activeTime" : ["7:00","17:30"] # schools active from 7 AM till 5:30 PM
   },
 "hospitalsNearby": False,
 "usualSpeedLimit": 40 # in km/hr
}
# USER INPUT SECTION ENDS
#
# MICRO-CONTROLLER CODE STARTS
print(brain.processConditions(myLocation,APIKEY,localityInfo))
```

MICRO CONTROLLER CODE WILL BE ADDED IN SPRINT 2 AS PER OUR PLANNED SPRINT SCHEDULE

111

MICRO-CONTROLLER CODE ENDS

OUTPUT:

Code Output

{'speed': 40, 'doNotHonk': False}

IMAGES:

```
A pycodepy-Cyberlygod/AppChal/Coal/Morporativ/Python/Python/11/pycode.py (3110)

File Edit Format Run Options Window Help

# EYRTHON COSE

# INFORT SECTION STARTS

# USER INFOUR SECTION STARTS

# USER INFORMATION TO PROMISE A PROMISE A
```