# Assignment-4

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Project Name	Project -Smart farmer-IOT enabled smart Farming Application		

## Question:

Write code and connections in wokwi for ultrasonic sensor.

Whenever distance is less than 100cm send "alert" to IBM cloud and display in device recent events. Upload document with wokwi share link and images of IBM cloud.

## CODE:

```
#include <WiFi.h>
#include <WiFiClient.h>
#include <PubSubClient.h>
#define ORG "171sro"
#define DEVICE_TYPE "MyDeviceType"
#define DEVICE ID "12345"
#define TOKEN "GkatKdiUS?UVHKvnAD"
char server[] = ORG
".messaging.internetofthings.ibmcloud.com"; char pubTopic1[] =
"iot-2/evt/SURYA PRAKASH J /fmt/json"; char pubTopic2[] =
"iot-2/evt/status2/fmt/json"; char authMethod[] = "use-
tokenauth"; char token[] = TOKEN; char clientId[] = "d:" ORG
":" DEVICE_TYPE ":" DEVICE_ID; const int DHT_PIN = 15;
WiFiClient wifiClient;
PubSubClient client(server, 1883, NULL, wifiClient);
#define ECHO PIN 12
#define TRIG_PIN 13
float readDistanceCM();
void setup() {
  Serial.begin(115200);
pinMode(15, OUTPUT);
pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);
  Serial.println();
    Serial.print("Connecting to ");
    WiFi.begin("Wokwi-GUEST", "", 6);
```

```
while (WiFi.status() != WL_CONNECTED) {
                                                delay(50);
     Serial.print(".");
   Serial.println("");
   Serial.print("WiFi connected, IP address: ");
   Serial.println(WiFi.localIP());
   if (!client.connected()) {
       Serial.print("Reconnecting client to ");
Serial.println(server);
                                while
(!client.connect(clientId, authMethod, token))
             Serial.print(".");
                                            delay(500);
       Serial.println("Bluemix connected");
  float
readDistanceCM()
   digitalWrite(TRIG_PIN, LOW);
delayMicroseconds(2); digitalWrite(TRIG_PIN,
HIGH); delayMicroseconds(10);
digitalWrite(TRIG_PIN, LOW); int duration =
pulseIn(ECHO_PIN, HIGH); return duration *
0.034 / 2;
} long lastMsg = 0; void loop() { float distance = readDistanceCM();
isNearby = distance < 100;//checking whether the distance is less than 100</pre>
digitalWrite(15, isNearby);
 Serial.print("Measured distance: ");
 Serial.println(readDistanceCM());
                if(isNearby)//Whenever the distance is less than 100 cms send an "alert"
  delay(100);
                         client.loop(); long now = millis(); if (now - lastMsg >
3000) {
               lastMsg = now;
      String payload = "{\"distance\":";
```

```
payload
+= distance;
payload
+= "}";

Serial.print("Sending payload: ");
Serial.println(payload);

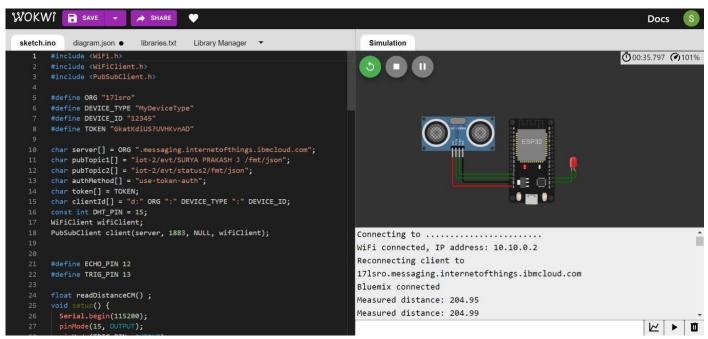
if (client.publish(pubTopic1, (char*) payload.c_str())) {
    Serial.println("Publish ok");
} else {
    Serial.println("Publish failed");
}

}
}
```

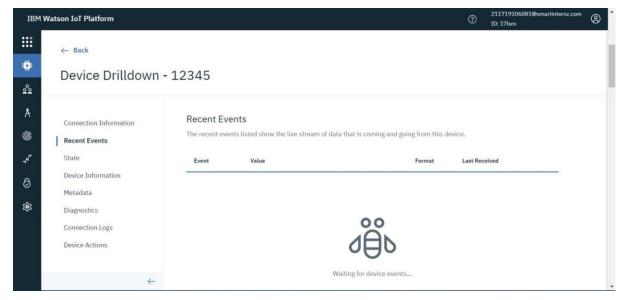
#### **OUTPUT:**

# Case: 1

When Distance Is Above 100 Cm



#### Data Is Not Send to IBM IOT PLATFORM If Distance Is Above 100 Cm



### Case:2

When Distance Is Below 100 Cm

