Assignment -1

Python Programming

Assignment Date	17 September 2022
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Maximum Marks	2 Marks

Question-1:

Make a smart home in tinkercad using 2 sensors, LED, Buzzer in single code and circuit.

Solution:

```
#include<Servo.h>
const int pingPin = 7;
int servoPin = 8
Servo servo1;
void setup() {
// initialize serial communication:
 Serial.begin(9600);
 servo1.attach(servoPin);
 pinMode(2,INPUT);
 pinMode(4,OUTPUT);
 pinMode(11,OUTPUT);
 pinMode(12,OUTPUT);
 pinMode(13,OUTPUT);
 pinMode(A0,INPUT);
 digitalWrite(2,LOW);
 digitalWrite(11,HIGH);
}
void loop() {
 long duration, inches, cm;
```

```
pinMode(pingPin, OUTPUT);
digitalWrite(pingPin, LOW);
delayMicroseconds(2);
digitalWrite(pingPin, HIGH);
delayMicroseconds(5);
digitalWrite(pingPin, LOW);
  pinMode(pingPin, INPUT);
  duration = pulseIn(pingPin, HIGH);
 // convert the time into a distance
  inches = microsecondsToInches(duration);
  cm = microsecondsToCentimeters(duration);
  servo1.write(0);
  if(cm < 40)
   servo1.write(90);
   delay(2000);
  }
  else
   servo1.write(0);
  }
```

```
// PIR with LED starts int
pir = digitalRead(2);
  if(pir == HIGH)
   digitalWrite(4,HIGH);
   delay(1000);
  else if(pir == LOW)
  {
   digitalWrite(4,LOW);
  }
 //temp with fan
  float value=analogRead(A0);
  float temperature=value*0.48;
  Serial.println("temperature");
  Serial.println(temperature);
  if(temperature > 20)
   digitalWrite(12,HIGH);
   digitalWrite(13,LOW);
  }
  else
   digitalWrite(12,LOW);
   digitalWrite(13,LOW);
```

```
}

long microsecondsToInches(long
  microseconds) {return microseconds / 74 / 2;
}

long microsecondsToCentimeters(long
  microseconds) {return microseconds / 29 / 2;
}
```

Output:

