Assignment -4 Wokwi & IBM Cloud

Assignment Date	28 October 2022
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Maximum Marks	2 Marks

Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever the distance is less than 100 cms sent "alert" to ibm cloud and display in device recent events.

Solution:

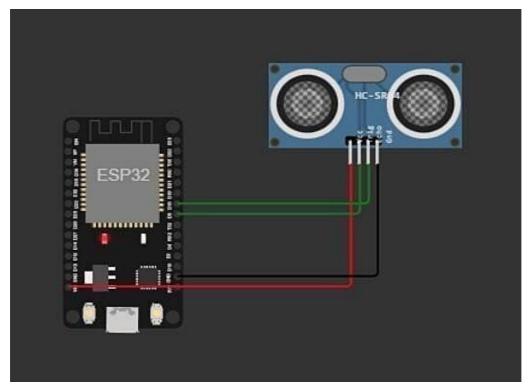
Code:

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "myox5t"
#define DEVICE_TYPE "usonic"
#define DEVICE_ID "ultrasonic"
#define TOKEN "8667393634"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/manimd/fmt/json";
char topic[] = "iot-2/cmd/led/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
  Serial.begin(115200);
 pinMode(led, OUTPUT);
```

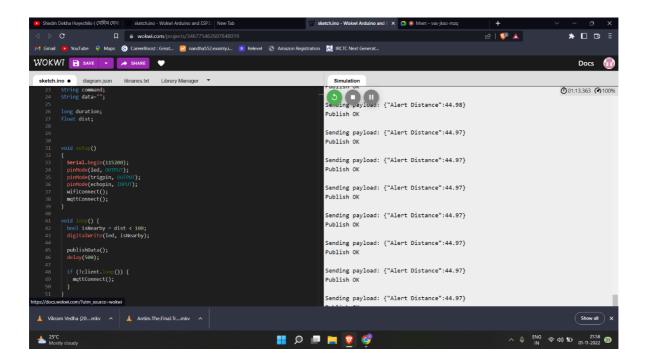
```
pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
 wifiConnect();
 mqttConnect();
void loop() {
 bool isNearby = dist < 100;</pre>
 digitalWrite(led, isNearby);
  publishData();
 delay(500);
  if (!client.loop()) {
   mqttConnect();
  }
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED) {
   delay(500);
    Serial.print(".");
  Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
void mqttConnect() {
 if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
   while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    initManagedDevice();
    Serial.println();
void initManagedDevice() {
 if (client.subscribe(topic)) {
   Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
void publishData()
  digitalWrite(trigpin, LOW);
```

```
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin, LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){</pre>
  String payload = "{\"Alert Distance\":";
 payload += dist;
 payload += "}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish OK");
}
  if(dist>100){
 String payload = "{\"Distance\":";
  payload += dist;
 payload += "}";
 Serial.print("\n");
  Serial.print("Sending payload: ");
 Serial.println(payload);
  if(client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish OK");
 }else {
   Serial.println("Publish FAILED");
 }
```

Connections:



Output:(wokwi):



Output:(IBM Cloud)

