

```

int fsrPin = 0;
int fsrReading;
void setup()
{
  pinMode(13, OUTPUT);
  pinMode(12, OUTPUT);
  pinMode(11, OUTPUT);
  pinMode(10, OUTPUT);
  pinMode(9, OUTPUT);
  pinMode(6, INPUT);
  pinMode(5, INPUT);
  pinMode(7, OUTPUT);
  pinMode(8,OUTPUT);
  Serial.begin(9600);
}

void loop()
{
  int fsrPin = 0;
  int fsrReading;
  void setup()
  {
    pinMode(13, OUTPUT);
    pinMode(12, OUTPUT);
    pinMode(11, OUTPUT);
    pinMode(10, OUTPUT);
    pinMode(9, OUTPUT);
    pinMode(6, INPUT);
    pinMode(5, INPUT);
    pinMode(7, OUTPUT);
    pinMode(8,OUTPUT);
    Serial.begin(9600);
  }

  void loop()
  {
    int button = digitalRead(6);
    int button1 = digitalRead(5);
    fsrReading = analogRead(fsrPin);
    Serial.println(fsrReading);
    if(fsrReading>0){
      Serial.println(fsrReading);
      digitalWrite(8,HIGH);
      delay(5000);
    }
  }
}

```

```
    digitalWrite(8,LOW);
}
if (button1==HIGH){
    digitalWrite(7,HIGH);
    delay(2000);
}
else{
    digitalWrite(7,LOW);}
if(button == HIGH){
    digitalWrite(13, HIGH);
    delay(1000); // Wait for 1000 millisecond(s)
    digitalWrite(12, HIGH);
    delay(1000);
    digitalWrite(11, HIGH);
    delay(1000);
    digitalWrite(10, HIGH);
    delay(1000);
    digitalWrite(9, HIGH);
    delay(1000);}
else
{
    digitalWrite(13, LOW);
    digitalWrite(12, LOW);
    digitalWrite(11, LOW);
    digitalWrite(10, LOW);
    digitalWrite(9, LOW);}
}
```