

ASSIGNMENT 4

ULTRASONIC SENSOR SIMULATION IN WOKWI AND IBM CLOUD

Assignment Date	18 October 2022
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Maximum Marks	2 Marks

QUESTION:

Write code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100 cm send an “alert” to the IBM cloud and display in the device recent events.

Solution:

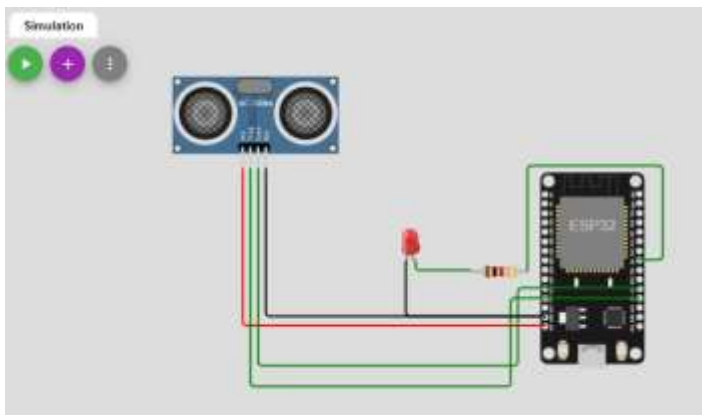
Introduction:

The HC-SR04 Ultrasonic Distance Sensor is connected to ESP32 and has 4 pins namely

Name	Description	Connection to ESP32
VCC	Voltage supply (5V)	Vin
TRIG	Pulse to start the measurement	D2
ECHO	Measure the high pulse length to get the distance	D4
GND	Ground	GND2

The distance is monitored by the ultrasonic sensor and if the distance is less than 100 cm, an “Alert Message” is sent to the IBM cloud. A led is made to glow if the distance is less than 100 cm.

Connection Diagram:



Code:

```
#include <WiFi.h>
#include <PubSubClient.h>
#include "Ultrasonic.h"
#define PIN_TRIG 2
#define PIN_ECHO 4
#define LED 5

void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);

#define ORG "iyxgzn"
#define DEVICE_TYPE "SensorNodes"
#define DEVICE_ID "97909150"
#define TOKEN "SEyIW0A(jsESMgHBaM"
String data3;

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;

WiFiClient wifiClient;
PubSubClient client(server, 1883, callback ,wifiClient);

void setup()
{
    Serial.begin(115200);
    Serial.println("Distance Sensor");
    pinMode(PIN_TRIG, OUTPUT);
    pinMode(PIN_ECHO, INPUT);
    pinMode(LED, OUTPUT);
    wificonnect();
    mqttconnect();
}

float readDistanceCM() {
    digitalWrite(PIN_TRIG, LOW);
    delayMicroseconds(2);
    digitalWrite(PIN_TRIG, HIGH);
    delayMicroseconds(10);
    digitalWrite(PIN_TRIG, LOW);
    int duration = pulseIn(PIN_ECHO, HIGH);
```

```

    return duration * 0.034 / 2;
}

void loop()
{
    float distance = readDistanceCM();

    bool isNearby;
    if( distance < 100){
        digitalWrite(LED, HIGH);
    }
    else{
        digitalWrite(LED, LOW);
    }
    PublishData(distance);
    delay(1000);
    if (!client.loop()) {
        mqttconnect();
    }
    Serial.print("Measured distance: ");
    Serial.println(readDistanceCM());
    delay(100);
}

void PublishData(float dist) {
    mqttconnect();
    if(dist<100)
    {
        String payload = "{\"Distance\":\"";
        payload += dist;
        payload += "\",\"Alert Message\":\"\" \"The distance is less than 100 cm\"";
        payload += "}";
        Serial.print("Sending payload: ");
        Serial.println(payload);
        if (client.publish(publishTopic, (char*) payload.c_str())) {
            Serial.println("Publish ok");
        }
        else {
            Serial.println("Publish failed");
        }
    }
    else
    {
        String payload = "{\"Distance\":\"";
        payload += dist;
        payload += "}";
        Serial.print("Sending payload: ");
        Serial.println(payload);
        if (client.publish(publishTopic, (char*) payload.c_str())) {

```

```

        Serial.println("Publish ok");
    }
    else {
        Serial.println("Publish failed");
    }
}

}

void mqttconnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting client to ");
        Serial.println(server);
        while (!!!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }

        initManagedDevice();
        Serial.println();
    }
}

void wificonnect()
{
    Serial.println();
    Serial.print("Connecting to ");

    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.println("");
    Serial.println("WiFi connected");
    Serial.println("IP address: ");
    Serial.println(WiFi.localIP());
}

void initManagedDevice() {
    if (client.subscribe(subscribetopic)) {
        Serial.println((subscribetopic));
        Serial.println("subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{

```

```

Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {
  //Serial.print((char)payload[i]);
  data3 += (char)payload[i];
}

Serial.println("data: " + data3);
if(data3=="lighton")
{
Serial.println(data3);
digitalWrite(LED,HIGH);

}

else
{
Serial.println(data3);
digitalWrite(LED,LOW);

}
data3="";
}

```

Simulated output from Wokwi :

```

Distance Sensor

Connecting to .....
WiFi connected
IP address:
10.10.0.2
Reconnecting client to iyxgzs.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String
subscribe to cmd OK

Sending payload: {"Distance":258.96}
Publish ok
Measured distance: 258.94
Sending payload: {"Distance":258.93}
Publish ok
Measured distance: 258.94
Sending payload: {"Distance":258.93}
Publish ok

```

Activate W
Go to Settings

Measured distance: 96.97

Sending payload: {"Distance":96.97,"Alert Message":"The distance is less than 100 cm"}

Publish ok

Measured distance: 96.97

Sending payload: {"Distance":96.97,"Alert Message":"The distance is less than 100 cm"}

Publish ok

Measured distance: 96.97

Sending payload: {"Distance":96.97,"Alert Message":"The distance is less than 100 cm"}

Publish ok

Measured distance: 96.97

Sending payload: {"Distance":96.97,"Alert Message":"The distance is less than 100 cm"}

Publish ok

Measured distance: 214.00

Sending payload: {"Distance":213.98}

Publish ok

Measured distance: 213.95

Sending payload: {"Distance":213.98}

Publish ok

Activate Windows

Go to Settings to activate Windows.

Measured distance: 68.99

Sending payload: {"Distance":68.99,"Alert Message":"The distance is less than 100 cm"}

Publish ok

Measured distance: 68.99

Sending payload: {"Distance":68.99,"Alert Message":"The distance is less than 100 cm"}

Publish ok

Measured distance: 68.99

Sending payload: {"Distance":68.95,"Alert Message":"The distance is less than 100 cm"}

Publish ok

Measured distance: 68.99

Sending payload: {"Distance":68.99,"Alert Message":"The distance is less than 100 cm"}

Publish ok

Simulated output from IBM Cloud :

The screenshot shows the IBM Watson IoT Platform interface. At the top, the header displays 'IBM Watson IoT Platform' and a user profile for 'angelynsweetie@gmail.com' with the ID 'ipygr'. Below the header, there's a navigation bar with 'Browse', 'Action', 'Device Types', and 'Interfaces'. A sidebar on the left contains various icons for navigation. The main content area shows a table of devices with columns: Device ID, Status, Device Type, Class ID, and Date Added. Two devices are listed: 765438 (Disconnected, SensorNodes, Device, Oct 23, 2022 8:31 PM) and 97909150 (Disconnected, SensorNodes, Device, Oct 23, 2022 8:28 PM). The second device is selected, and its details are shown below. The details view has tabs for 'Identity', 'Device Information', 'Recent Events', 'State', and 'Logs'. The 'Recent Events' tab is active, showing a list of events with columns: Event, Value, Format, and Last Received. The events are JSON payloads containing distance and alert message data, all received 'a minute ago'. An 'Activate Windows' watermark is visible in the bottom right corner.

Device ID	Status	Device Type	Class ID	Date Added
765438	Disconnected	SensorNodes	Device	Oct 23, 2022 8:31 PM
97909150	Disconnected	SensorNodes	Device	Oct 23, 2022 8:28 PM

Event	Value	Format	Last Received
Data	{"Distance":68.99,"Alert Message":"The distance..."}	json	a minute ago
Data	{"Distance":68.99,"Alert Message":"The distance..."}	json	a minute ago
Data	{"Distance":68.99,"Alert Message":"The distance..."}	json	a minute ago
Data	{"Distance":68.99,"Alert Message":"The distance..."}	json	a minute ago
Data	{"Distance":68.99,"Alert Message":"The distance..."}	json	a minute ago

Event Payload

Event Name Data

Time Received Oct 23, 2022 10:49 PM

```
1 {  
2   "Distance": 68.99,  
3   "Alert Message": "The distance is less than 100 cm"  
4 }
```

The screenshot shows the IBM Watson IoT Platform interface. At the top, there's a header with the platform name and user information. Below the header, there's a navigation bar with tabs for 'Browse', 'Action', 'Device Types', and 'Interfaces'. A sidebar on the left contains various icons for navigation. The main content area displays a table of devices. One device, with ID 97909150, is selected and its details are shown in a sub-panel below. This sub-panel has tabs for 'Identity', 'Device Information', 'Recent Events', 'State', and 'Logs'. The 'Recent Events' tab is active, showing a list of events with columns for 'Event', 'Value', 'Format', and 'Last Received'. The events listed are 'Data' events with a value of '{"Distance":234.97}' in 'json' format, received 'a few seconds ago'.

Device ID	Status	Device Type	Class ID	Date Added
765438	Disconnected	SensorNodes	Device	Oct 23, 2022 8:31 PM
97909150	Connected	SensorNodes	Device	Oct 23, 2022 8:28 PM

Event	Value	Format	Last Received
Data	{"Distance":234.97}	json	a few seconds ago
Data	{"Distance":234.97}	json	a few seconds ago
Data	{"Distance":234.97}	json	a few seconds ago
Data	{"Distance":241.93}	json	a few seconds ago
Data	{"Distance":241.94}	json	a few sec

Event Payload

Event Name Data

Time Received Oct 23, 2022 10:52 PM

1	{
2	"Distance": 234.97
3	}

Simulation Link:

<https://wokwi.com/projects/346235585019511379>