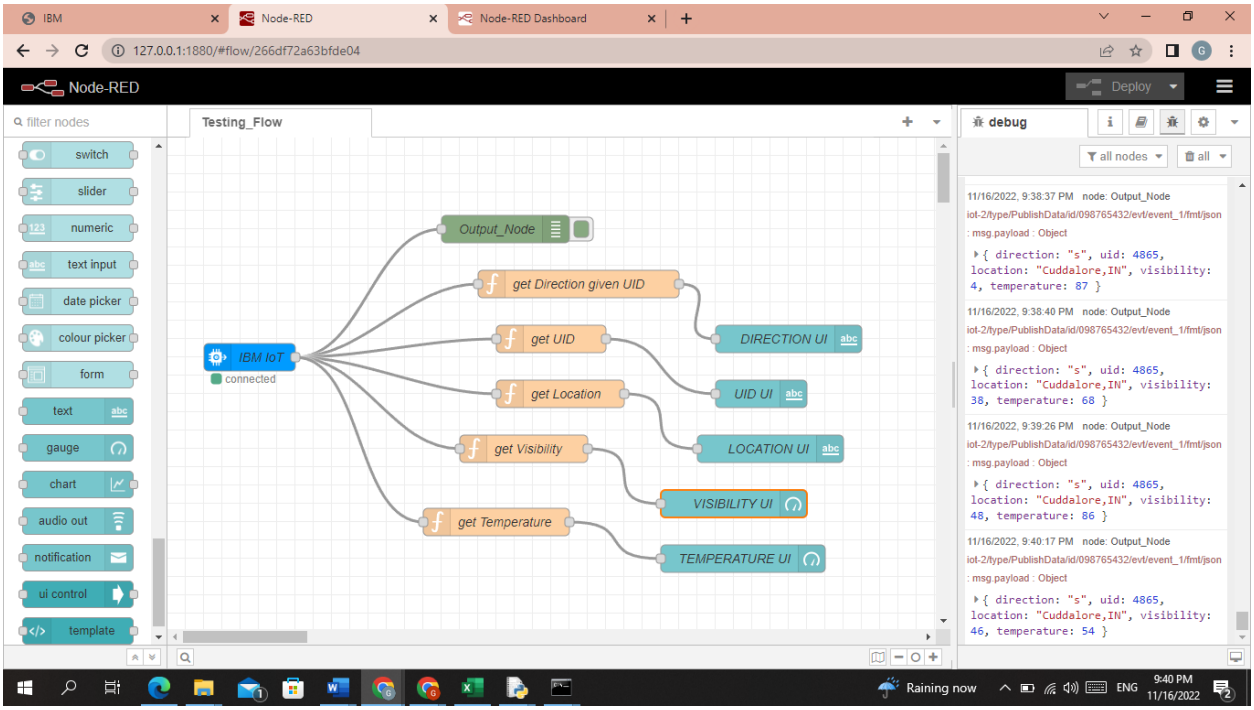
SPRINT 4

TEAM ID: PNT2022TMID38788

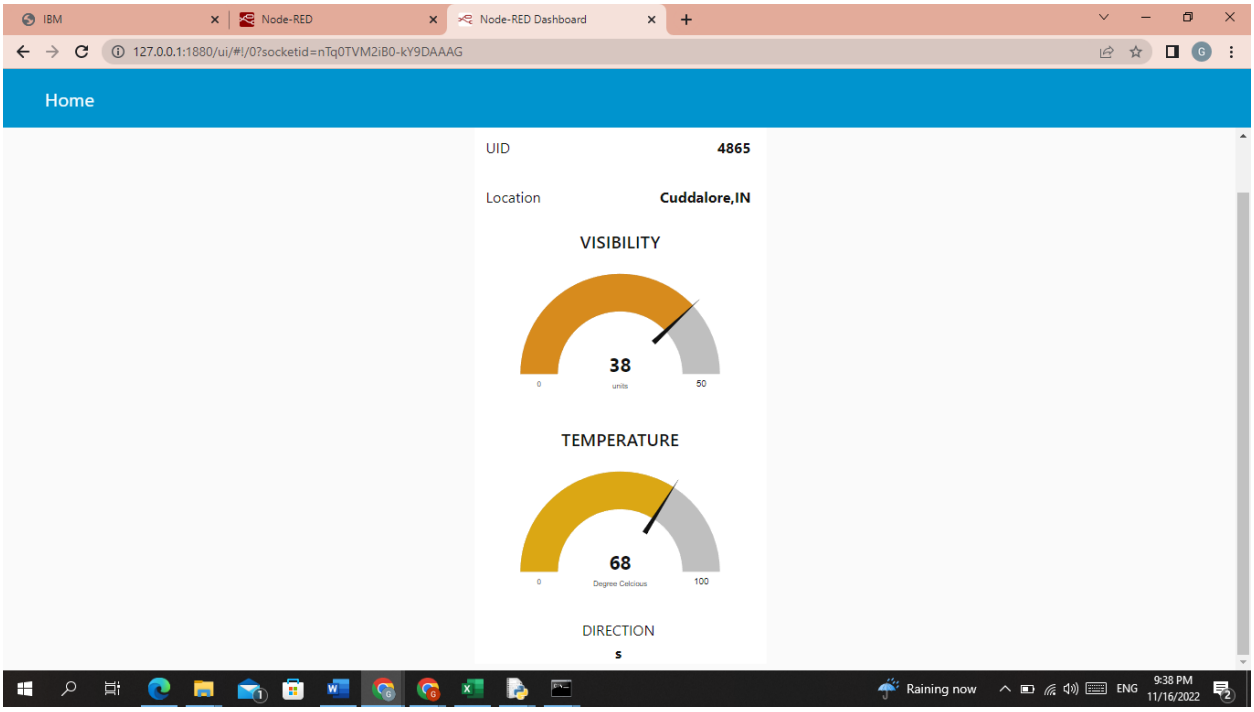
Node RED UI flow:



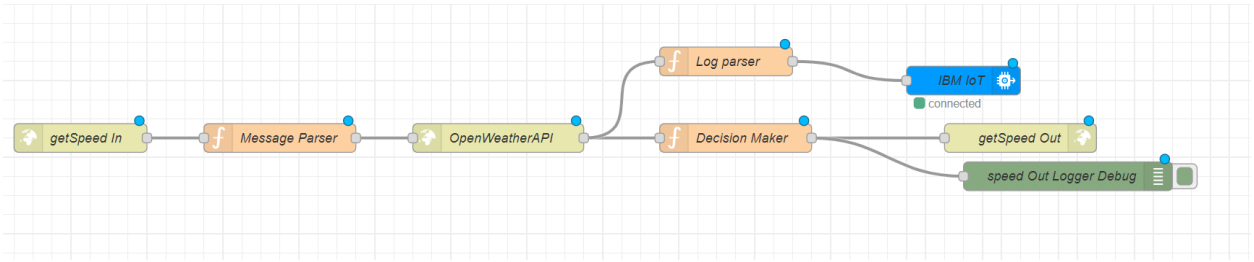
CODE:

```
// get Direction given UID
msg.payload = global.get(String(msg.payload.uid));
return msg;

// get UID
msg.payload = msg.payload.uid;
return msg;

// get Location
msg.payload = msg.payload.location;
return msg;

// get Visibility
msg.payload = msg.payload.visibility;
return msg;

// get Temperature
msg.payload = msg.payload.temperature;
return msg;
```

OUTPUT:



Get Speed API flow:



CODE:

1. **"getSpeed In"** node is an http end point. It accepts parameters like microcontroller UID, location, school & hospital zones info.

2. **"Message Parser"** node parses the data and passes on only required information to the next node

```
global.set("data",msg.payload);
```

```
msg.payload.q = msg.payload.location;
msg.payload.appid = "9cd610e5fd400c74212074c7ace0d62c";
return msg;
```

3. **"OpenWeatherAPI"** node is a http request node which calls the OpenWeather API and send the data to the next node.

4. **"Log Parser"** node extracts specific parameters from the weather data and and sends it to the next node.

```
weatherObj = JSON.parse(JSON.stringify(msg.payload));
localityObj = global.get("data");

var suggestedSpeedPercentage = 100;

var preciseObject = {
    temperature : weatherObj.main.temp - 273.15,
    location : localityObj.location,
    visibility : weatherObj.visibility/100,
    uid : localityObj.uid,
    direction : global.get("direction")
};

msg.payload = preciseObject;

return msg;
```

5. **"IBM IoT"** node here (IBM IoT OUT)connects the **"IBM IoT"** node (IBM IoT IN) metioned in the **Node RED UI flow** which enables UI updation and logging.

6. **"Decision Maker"** node processes the weather data and other information from the micro controller to form the string that is to be displayed at the Sign Board

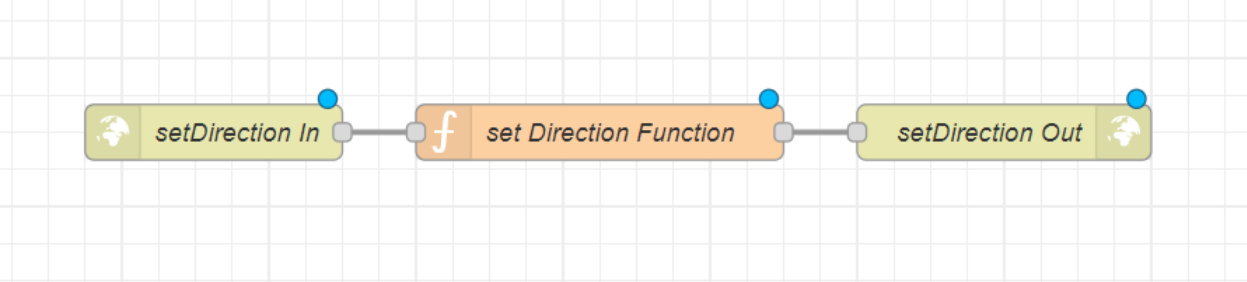
```
weatherObj = JSON.parse(JSON.stringify(msg.payload));
localityObj = global.get("data");

var suggestedSpeedPercentage = 100;

var preciseObject = {
    temperature : weatherObj.main.temp - 273.15,
    weather : weatherObj.weather.map(x=>x.id).filter(code => code<700),
    visibility : weatherObj.visibility/100
};

if(preciseObject.visibility<=40)
    suggestedSpeedPercentage -=30

switch(String(preciseObject.weather)[-1]) // https://openweathermap.org/weather-
conditions refer weather codes meaning here
{
    case "0" : suggestedSpeedPercentage -=10;break;
```

```
    case "1" : suggestedSpeedPercentage -=20;break;
    case "2" : suggestedSpeedPercentage -=30;break;
}

msg.payload = preciseObject;

var doNotHonk = 0;
if(localityObj.hospitalZone=="1"||localityObj.schoolZone=="1")
    doNotHonk = 1;

var returnObject = {
    suggestedSpeed : localityObj.usualSpeedLimit*(suggestedSpeedPercentage/100),
    doNotHonk : doNotHonk
}

msg.payload = String(returnObject.suggestedSpeed) + " kmph \n\n" +
(returnObject.doNotHonk==1?"Do Not Honk":"") + "$" +
global.get(String(localityObj.uid));

return msg;
```

7. **"getSpeed Out"** node returns a http response for the request at node **"getSpeed In"**.

8. **"speed Out Logger Debug"** logs the data for debugging.

setDirection API flow:



CODE:

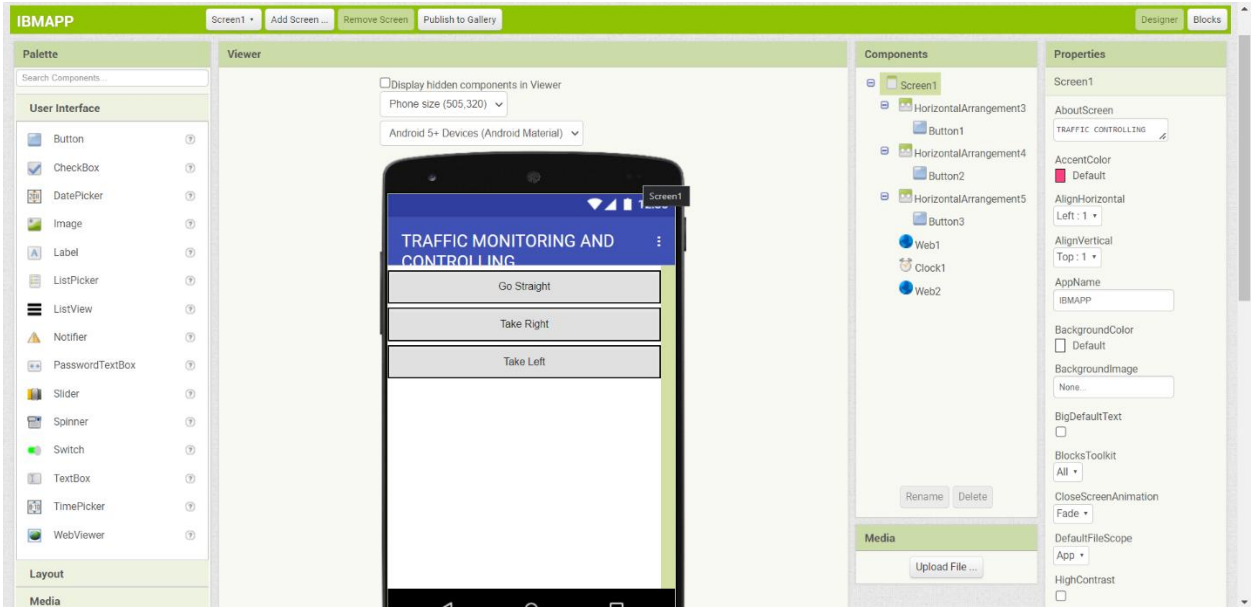
1. **"setDirection In"** node is an http end point. It accepts parameters like microcontroller UID & direction.

2. **"set Direction Function"** node sets the direction for the given UID.

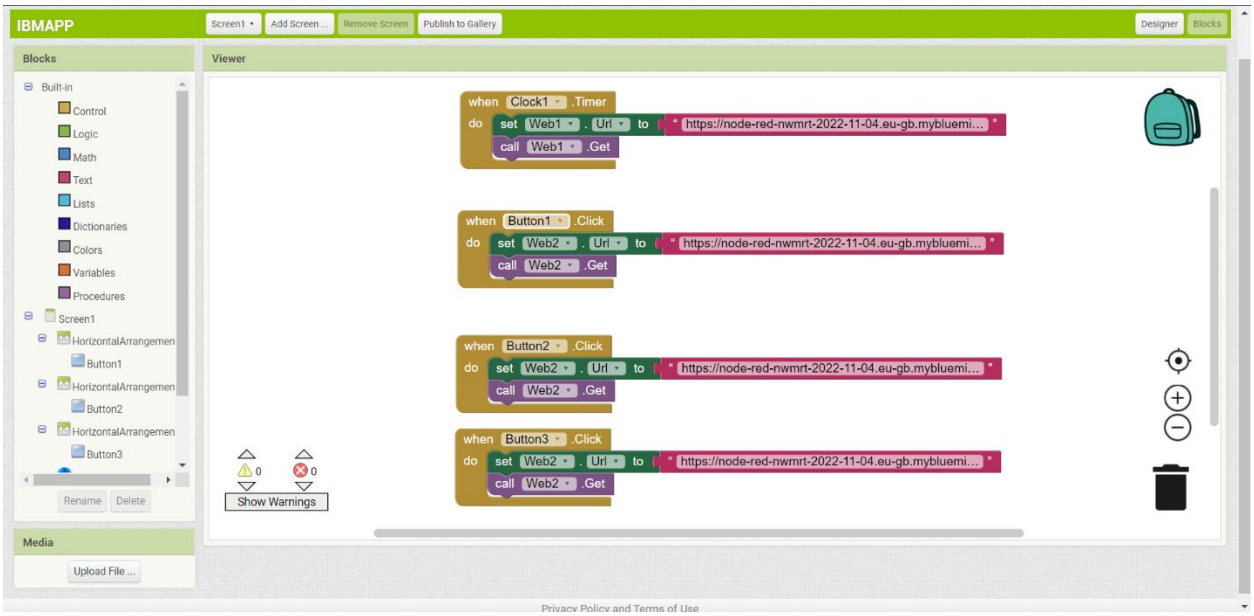
```
global.set(String(msg.payload.uid),msg.payload.dir);
return msg;
```

3. **"setDirection Out"** node returns a http response for the request at node **"setDirection In"**.

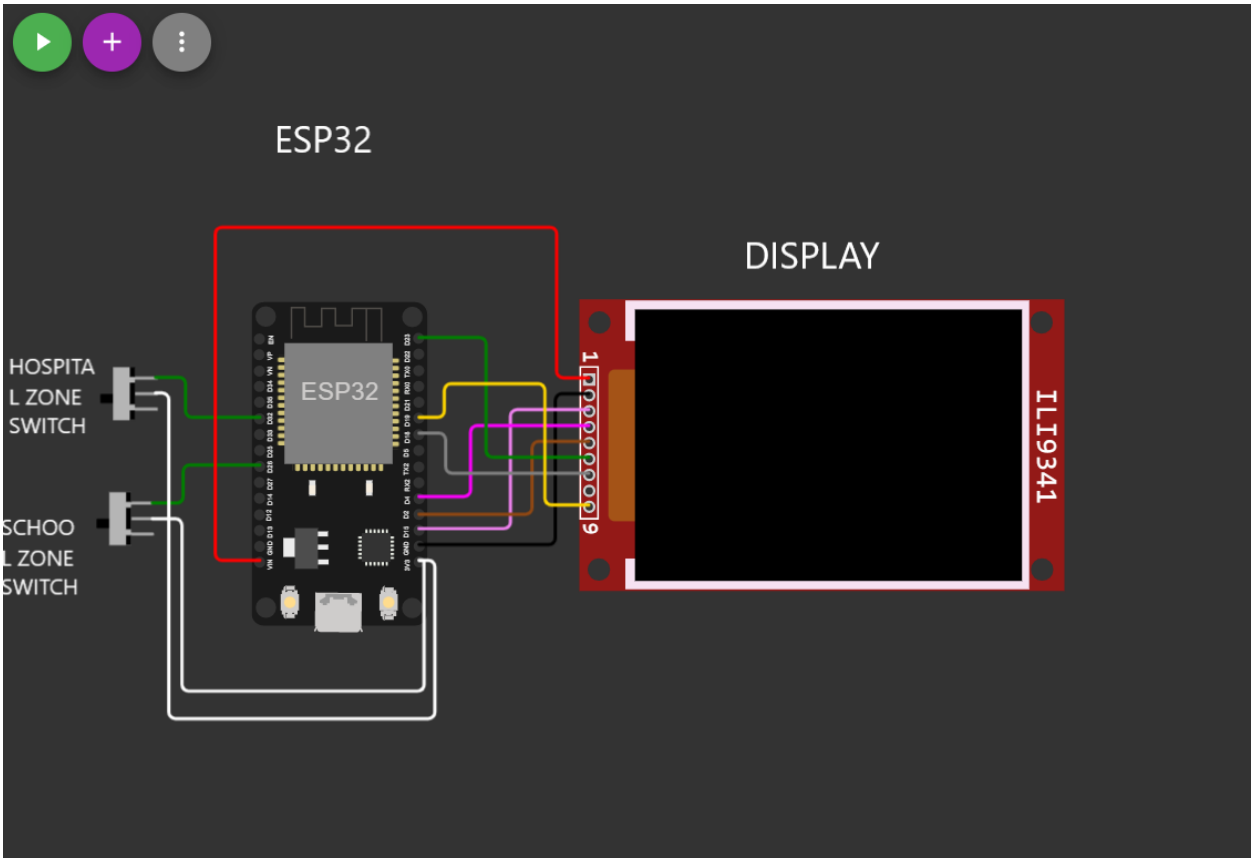
MIT APP UI:



MIT APP BLOCK CODE:



ESP32 CIRCUIT DIAGRAM



CODE:

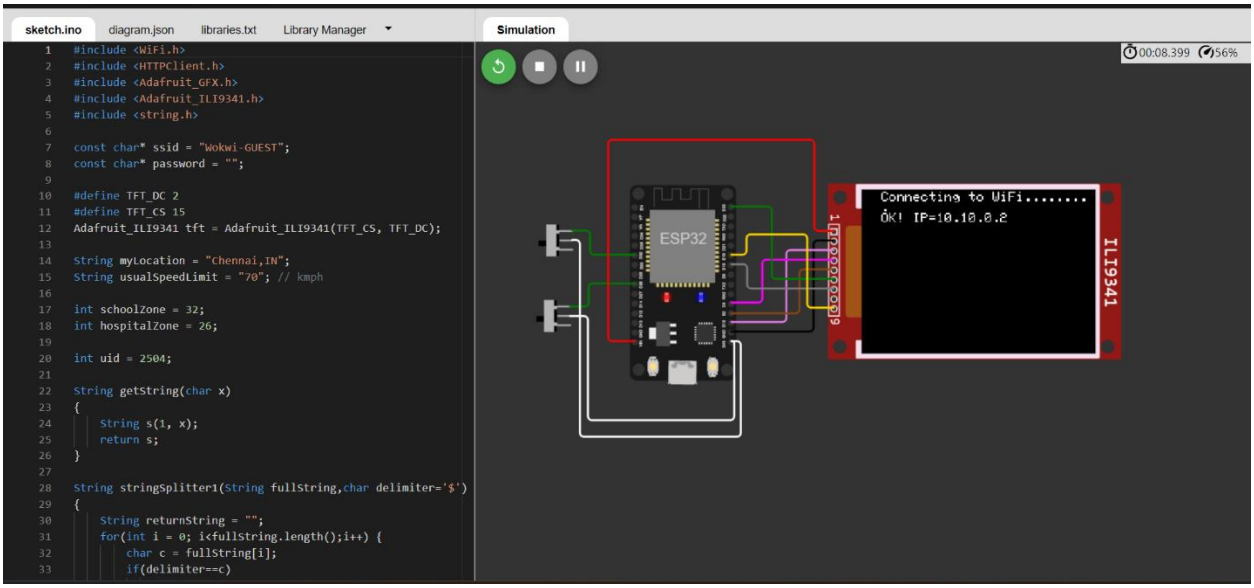
```
#include <WiFi.h>
#include <HTTPClient.h>
#include <Adafruit_GFX.h>
#include <Adafruit_ILI9341.h>
#include <string.h>

const char* ssid = "Wokwi-GUEST";
const char* password = "";

#define TFT_DC 2
#define TFT_CS 15
Adafruit_ILI9341 tft = Adafruit_ILI9341(TFT_CS, TFT_DC);

String myLocation = "Chennai,IN";
String usualSpeedLimit = "70"; // kmph

int schoolZone = 32;
int hospitalZone = 26;
```

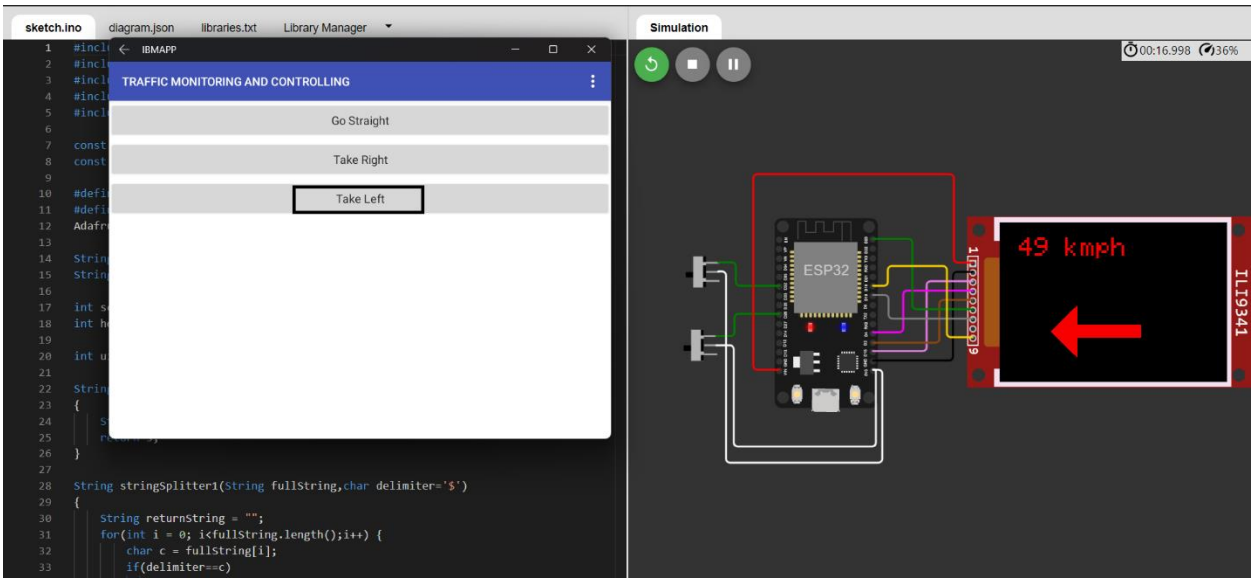
```
int uid = 2504;

String getString(char x)
{
    String s(1, x);
    return s;
}

String stringSplitter1(String fullString,char delimiter='$')
{
    String returnString = "";
    for(int i = 0; i<fullString.length();i++) {
        char c = fullString[i];
        if(delimiter==c)
            break;
        returnString+=String(c);
    }
    return(returnString);
}

String stringSplitter2(String fullString,char delimiter='$')
{
    String returnString = "";
    bool flag = false;
    for(int i = 0; i<fullString.length();i++) {
        char c = fullString[i];
        if(flag)
            returnString+=String(c);
        if(delimiter==c)
            flag = true;
    }
    return(returnString);
}

void rightArrow()
{
  int refX = 50;
  int refY = tft.getCursorY() + 40;

  tft.fillRect(refX,refY,100,20,ILI9341_RED);
  tft.fillTriangle(refX+100,refY-
30,refX+100,refY+50,refX+40+100,refY+10,ILI9341_RED);
}
```

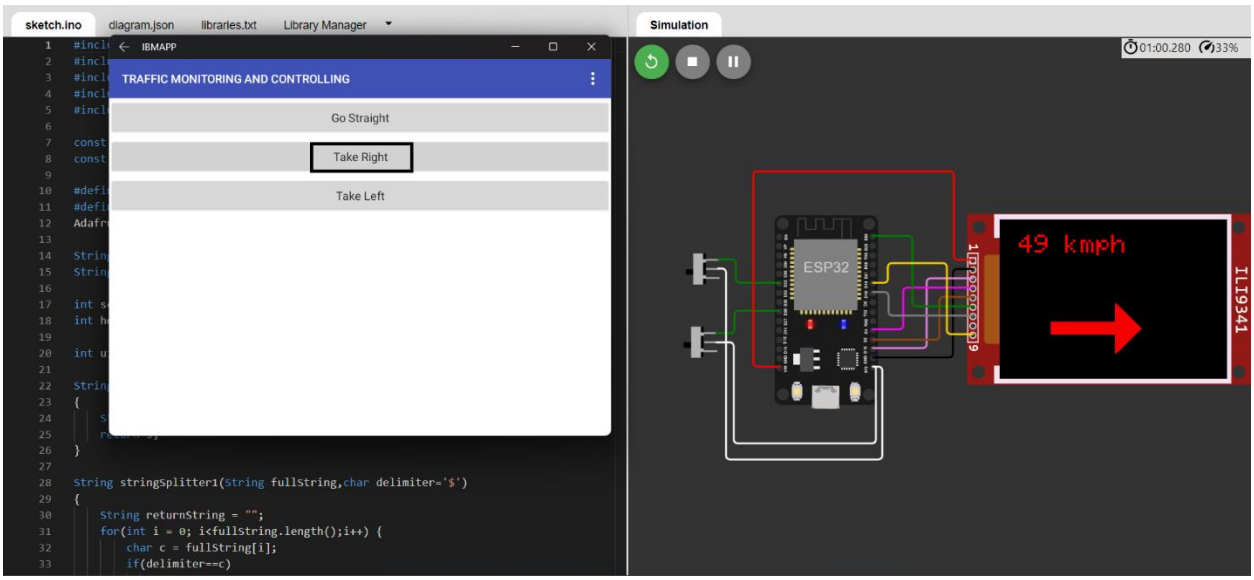
```
void leftArrow()
{
  int refX = 50;
  int refY = tft.getCursorY() + 40;

  tft.fillRect(refX+40,refY,100,20,ILI9341_RED);
  tft.fillTriangle(refX+40,refY-30,refX+40,refY+50,refX,refY+10,ILI9341_RED);
}

void upArrow()
{
  int refX = 125;
  int refY = tft.getCursorY() + 30;

  tft.fillTriangle(refX-40,refY+40,refX+40,refY+40,refX,refY,ILI9341_RED);
  tft.fillRect(refX-15,refY+40,30,20,ILI9341_RED);
}

String APICall() {
  HTTPClient http;

  String url = "https://node-red-nwmrt-2022-11-04.eu-gb.mybluemix.net/getSpeed?";
  url += "location="+myLocation+"&";
  url += "schoolZone="+(String)digitalRead(schoolZone)+(String)"&";
  url += "hospitalZone="+(String)digitalRead(hospitalZone)+(String)"&";
  url += "usualSpeedLimit="+(String)usualSpeedLimit+(String)"&";
  url += "uid="+(String)uid;
  http.begin(url.c_str());
  int httpResponseCode = http.GET();

  if (httpResponseCode>0) {
    String payload = http.getString();
    http.end();
    return(payload);
  }
  else {
    Serial.print("Error code: ");
    Serial.println(httpResponseCode);
  }
  http.end();
}

void myPrint(String contents) {
  tft.fillScreen(ILI9341_BLACK);
  tft.setCursor(0, 20);
```

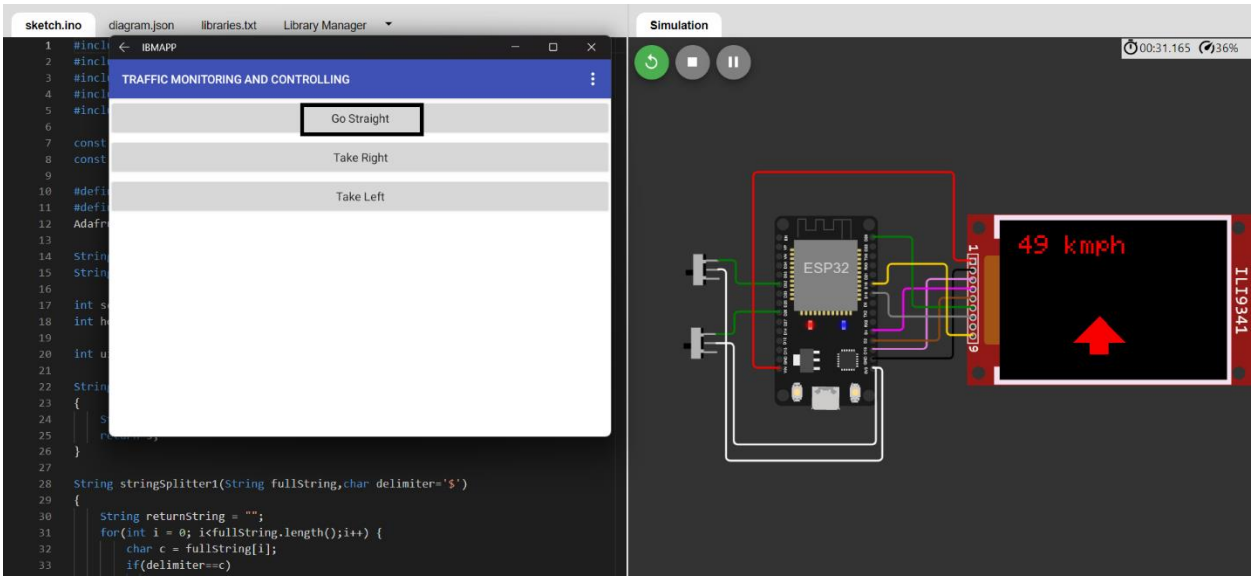
```
  tft.setTextSize(4);
  tft.setTextColor(ILI9341_RED);
  //tft.println(contents);

  tft.println(stringSplitter1(contents));
  String c2 = stringSplitter2(contents);
  if(c2=="s") // represents Straight
  {
    upArrow();
  }
  if(c2=="l") // represents left
  {
    leftArrow();
  }
  if(c2=="r") // represents right
  {
    rightArrow();
  }
}

void setup() {
  WiFi.begin(ssid, password, 6);

  tft.begin();
  tft.setRotation(1);

  tft.setTextColor(ILI9341_WHITE);
  tft.setTextSize(2);
  tft.print("Connecting to WiFi");

  while (WiFi.status() != WL_CONNECTED) {
    delay(100);
    tft.print(".");
  }

  tft.print("\nOK! IP=");
  tft.println(WiFi.localIP());
}

void loop() {

  myPrint(APICall());

  delay(100);
}
```

OUTPUT:


sketch.ino
diagram.json
libraries.txt
Library Manager
Simulation
00:08.399
56%
#include <WiFi.h>
#include <HTTPClient.h>
#include <Adafruit_GFX.h>
#include <Adafruit_ILI9341.h>
#include <string.h>
const char* ssid = "Wokwi-GUEST";
const char* password = "";
#define TFT_DC 2
#define TFT_CS 15
Adafruit_ILI9341 tft = Adafruit_ILI9341(TFT_CS, TFT_DC);
String myLocation = "chennai,IN";
String usualSpeedLimit = "70"; // kmph
int schoolZone = 32;
int hospitalZone = 26;
int uid = 2504;
String getString(char x)
{
String s(1, x);
return s;
}
String stringSplitter1(String fullString,char delimiter='$')
{
String returnString = "";
for(int i = 0; i<fullString.length();i++) {
char c = fullString[i];
if(delimiter==c)
ESP32
Connecting to WiFi.....
OK! IP=10.10.0.2
ILI9341


sketch.ino
diagram.json
libraries.txt
Library Manager
Simulation
00:16.998
36%
IBMAPP
TRAFFIC MONITORING AND CONTROLLING
Go Straight
Take Right
Take Left
ESP32
49 kmph
ILI9341


sketch.ino
diagram.json
libraries.txt
Library Manager
IBMAPP
TRAFFIC MONITORING AND CONTROLLING
Go Straight
Take Right
Take Left
Simulation
01:00.280
33%
ESP32
49 kmph
ILI9341


sketch.ino
diagram.json
libraries.txt
Library Manager
IBMAPP
TRAFFIC MONITORING AND CONTROLLING
Go Straight
Take Right
Take Left
Simulation
00:31.165
36%
ESP32
49 kmph
ILI9341