SPRINT 4

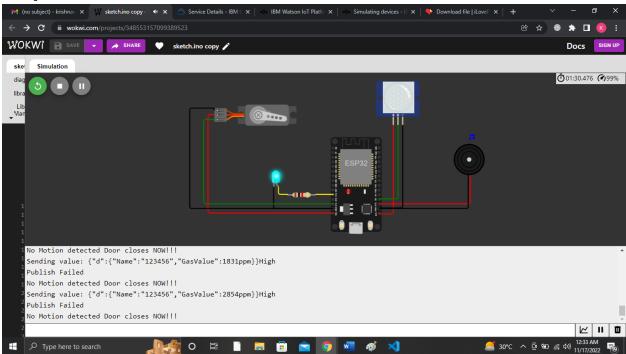
Program

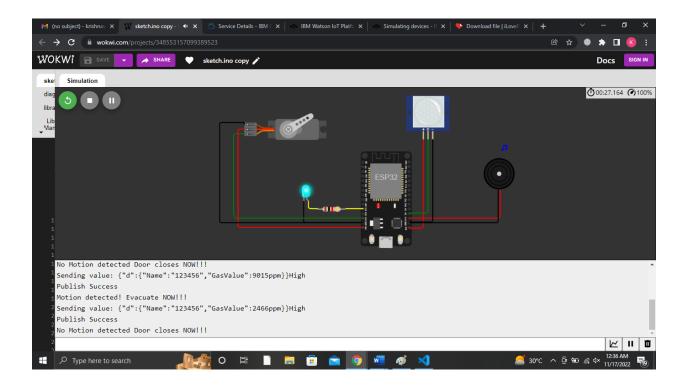
```
#include <WiFi.h>
#include <WiFiClient.h>
#include <PubSubClient.h>
#include <ESP32Servo.h>
const char* ssid = "Wokwi-GUEST";
const char* password = "";
#define ORG "oeng7r"
#define DEVICE_TYPE "DeviceType"
#define DEVICE ID "123456"
#define TOKEN "Ch!y&Xu6G(OJiwg08B"
#define led 14
#define buzzer 15
#define pir 2
#define servoPin 13
Servo servo;
int sensor value=0;
int pirState=LOW;
int val=0;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char pubTopic[] = "iot-2/evt/status1/fmt/json";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, NULL, wifiClient);
void setup()
 Serial.begin(115200);
  pinMode(led, OUTPUT);
 pinMode(buzzer, OUTPUT);
  pinMode(pir, INPUT);
  servo.attach(servoPin,500,2400);
  Serial.print("Connecting to ");
 Serial.print(ssid);
 WiFi.begin(ssid, password);
 while (WiFi.status() != WL_CONNECTED)
```

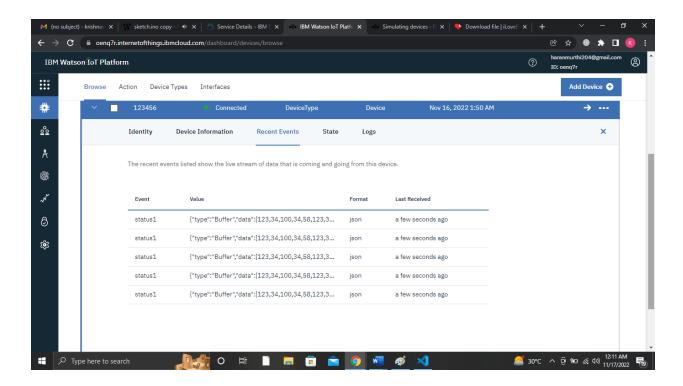
```
delay(500);
    Serial.print(".");
  Serial.println("");
  Serial.print("WiFi connected, IP address: ");
  Serial.println(WiFi.localIP());
 if (!client.connected())
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!client.connect(clientId, authMethod, token))
      Serial.print(".");
      delay(500);
   Serial.println("Bluemix connected");
int pos = 0;
void loop()
  sensor_value=random(300,10000);
 for (pos = 0; pos <=180; pos +=1){
   servo.write(pos);
   delay(15);
  String payload = "{\"d\":{\"Name\":\"" DEVICE_ID "\"";
  payload += ",\"GasValue\":";
  payload += sensor_value;
  payload += "ppm";
  payload += "}}";
 if(sensor_value>1000)
    digitalWrite(led, HIGH);
    delay(500);
    tone(buzzer,1000);
    delay(1000);
    payload += "High";
   val = digitalRead(pir);
    if (val == HIGH)
```

```
if (pirState == LOW)
      Serial.println("Motion detected! Evacuate NOW!!!");
  Serial.println("No Motion detected Door closes NOW!!!");
  for (pos =180; pos >=0; pos -=1){
    servo.write(pos);
    delay(15);
  }
Serial.print("Sending value: ");
Serial.println(payload);
if (client.publish(pubTopic, (char*) payload.c_str()))
  Serial.println("Publish Success");
  Serial.println("Publish Failed");
delay(100);
```

Output:







Event payload

Link:

https://wokwi.com/projects/348553157099389523