## ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

Date	20 October 2022
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Maximum Marks	2 Marks

## Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

## **WOKWI LINK:**

https://wokwi.com/projects/305566932847821378

## CODE:

```
#include #i
```

```
esp32-blink.ino
                  diagram.json •
                                   libraries.txt ●
                                                  Library Manager *
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
creating the String in in form JSon to update the data to ibm cloud

//
String object;
if (dist <100)
{
    digitalWrite(LED,HIGH);
    Serial.println("object is near");
    object = "Near";
}
else
{
    digitalWrite(LED,LOW);
    Serial.println("no object found");
    object = "No";
}

String payload = "{\"distance\":";
    payload += dist;
    payload += "\""yobject\":\"";
    payload += "\""yobject\":\"";
    payload += "\"")";

Serial.print("Sending payload: ");
    Serial.println(payload);
</pre>
```

```
degram|son | Branestri | Etrary Manager |

if (client.publish(publishTopic, (char*) payload.e_str())) {

serial.println("Publish ok");// if it successfully upload data on the cloud then it will print publish ok in Serial monitor or else it will print publish failed");

serial.println("Publish failed");

}

void myttconnect() {

if (client.connected()) {

if (client.connected()) {

serial.println("Reconnecting client to ");

serial.println("cornecting clientid, authWethod, token)) {

serial.println(");

delay(see);

}

void wificonnect() / function defination for wificonnect

serial.println();

serial.println();

serial.println();

serial.println();

serial.println();

serial.println();

serial.println();

serial.println();

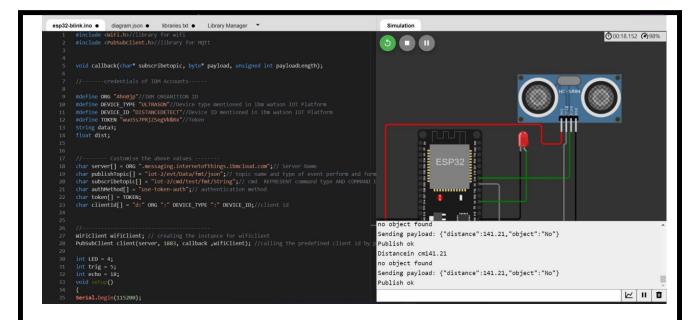
serial.println(");

serial.println("kifi.localip());
```

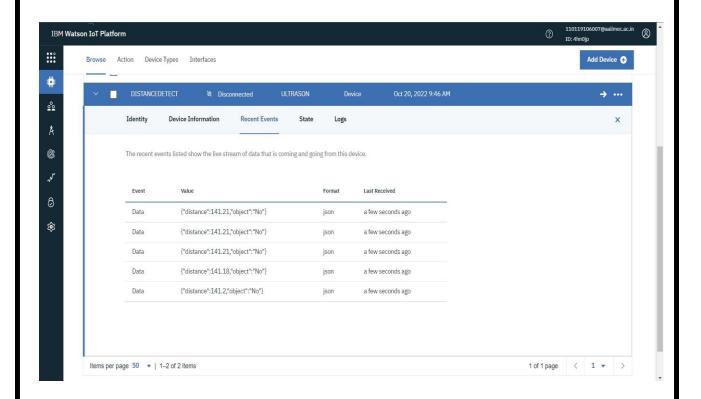
```
esp32-blink.ino •
                   diagram.json •
                                   libraries.txt ●
                                                  Library Manager
         WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
         while (WiFi.status() != WL_CONNECTED) {
           delay(500);
           Serial.print(".");
         Serial.println("");
         Serial.println("WiFi connected");
         Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
       void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
           Serial.println((subscribetopic));
           Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
 148
         Serial.println(subscribetopic);
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
```

```
esp32-blink.ino
                   diagram.json •
                                    libraries.txt ●
                                                    Library Manager
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
         Serial.print("callback invoked for topic: ");
         Serial.println(subscribetopic);
148
         for (int i = 0; i < payloadLength; i++) {</pre>
           data3 += (char)payload[i];
       data3="";
```

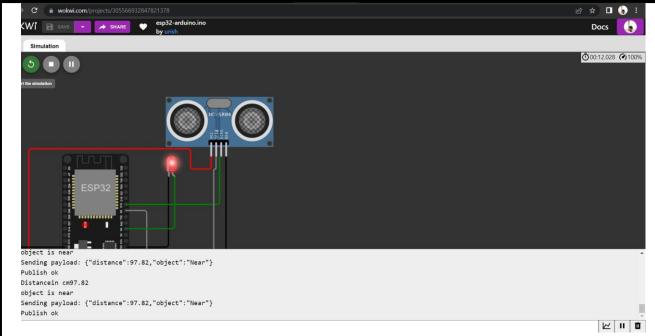
**OUTPUT:** 



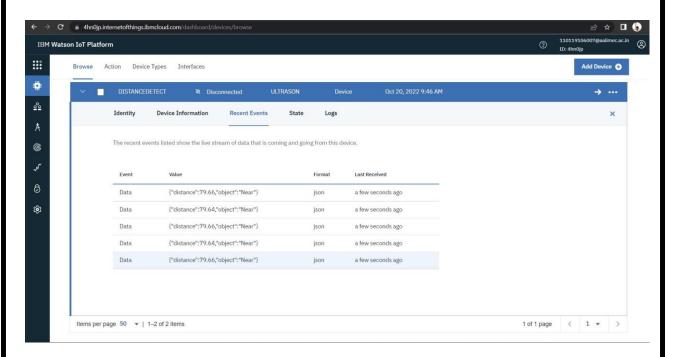
Data send to the IBM cloud device when the object is far



when object is near to the ultrasonic sensor



Data sent to the IBM Cloud Device when the object is near



https://wokwi.com/projects/305566932847821378