# ASSIGNMENT-4 DISTANCE DETECTION USING ULTRASONIC SENSOR

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Maximum Marks	2 Marks

#### Question1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.

```
### sinclude c#Fi.by/library for wifi
### sinclude c### subscribetopic, byte* payload, unsigned int payloadLength);

### void callback(char* subscribetopic, byte* payload, unsigned int payloadLength);

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### define ORG "Ahnejp"/IBM ORGANITION ID
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### define DEVICE INTE "DUTRASON"/Device type mentioned in ibm watson IOT Platform
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### define DEVICE INTE "DUTRASON"/Device ID mentioned in ibm watson IOT Platform
### define DEVICE INTE "DUTRASON"/Token
### string datas;
### float dist;

### float dist;

### char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name
### char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in which data to be send
### char subscribetopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in which data to be send
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### char subscribetopic [] = "iot-2/evt/Data/fmt/json";// authentication method
### char subscribetopic
### char subscribetopic;
###
```

#### CODE:

```
esp32-blink.ino
                 diagram.json •
                                   libraries.txt •
                                                Library Manager
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
esp32-blink.ino •
                   diagram.json •
                                    libraries.txt ●
                                                    Library Manager
          WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
          while (WiFi.status() != WL CONNECTED) {
            delay(500);
            Serial.print(".");
         Serial.println("");
Serial.println("WiFi connected");
          Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
        void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
            Serial.println((subscribetopic));
            Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
 148
          Serial.println(subscribetopic);
          for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
```

```
esp32-blink.ino  diagram.json  libraries.txt  Library Manager  

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)

void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)

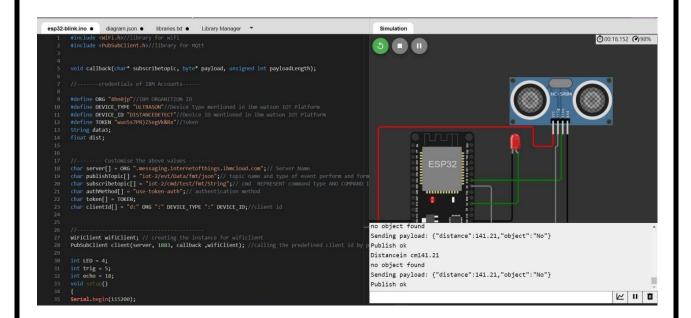
serial.print("callback invoked for topic: ");

serial.println(subscribetopic);

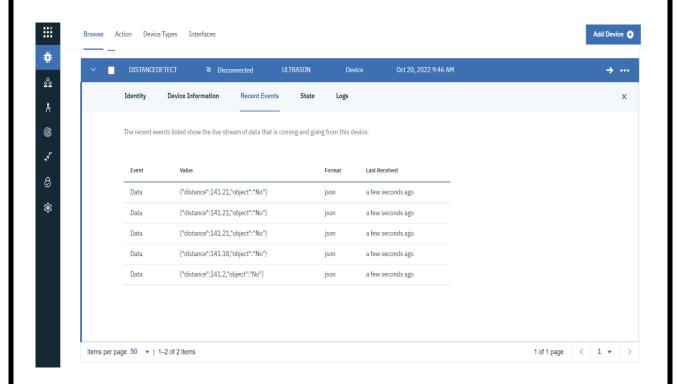
for (int i = 0; i < payloadLength; i++) {
    //serial.println((char)payload[i]);
    data3 += (char)payload[i];
    // serial.println("data: "+ data3);
    // // serial.println(data3);
    // serial.println(data3);
    // digitalwrite(LED,HIGH);

// else
// else
// // serial.println(data3);
// digitalwrite(LED,LOW);
// digitalwrite(LED,LOW);
// digitalwrite(LED,LOW);
// digitalwrite(LED,LOW);
// // else
// // serial.println(data3);
// digitalwrite(LED,LOW);
// digitalwrite(LED,LOW);
// digitalwrite(LED,LOW);
// else
// ```

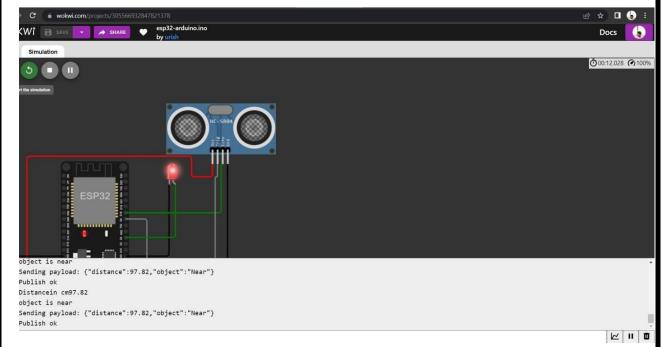
### **OUTPUT:**



#### Data send to the IBM cloud device when the object is far



## when object is near to the ultrasonic sensor



## Data sent to the IBM Cloud Device when the object is near

