## Assignment - 4

## Question-1:

Write code and connections in wokwi for ultrasonic sensor. Whenever distance is less than 100 cms send "Alert" to IBM cloud and display in device recent events.

```
Solution:
```

```
// Pins
const int TRIGpPIN = 7;
const int ECHOpPIN = 8;
// Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int MAXpDIST = 23200;
void setup() (
 // The Trigger pin will tell the sensor to range find
 pinMode(TRIGpPIN, OUTPUT);
 digital Write (TRIGpPIN, LOW);
 //Set Echo pin as input to measure the duration of
 //pulses coming back from the distance sensor
 pinMode(ECHO PIN, INPUT);
 // We'll use the serial monitor to view the sensor output
 Serial.begin(9600);
void loop() (
 unsigned long t1;
 unsigned long t2;
 unsigned long pulsepwidth;
 float cm;
 float inches;
 // Hold the trigger pin high for at least 10 us
```

```
digita1Write(TRIGpPIN, HIGH);
delayMicroseconds(10);
digital Write(TRIGpPIN, LOW);
// Wait for pulse on echo pin
while (digita1Read(ECHO PIN) == 0);
// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after -70 min
t1 = micros();
while (digital Read (ECHO PIN) == 1);
t2 = micros();
pulsepwidth = t2 - t1;
// Calculate distance in centimeters and inches. The constants
// are found in the datasheet, and calculated from the assumed speed
//of sound in air at sea level (340 mls).
cm = pulsepwidth / 58.0;
inches = pulsepwidth / 148.0;
// Print out results
if (pulsepwidth > MAX DIST) (
 Serial.println("Out of range");
} else (
 Serial.print1n("******************************);
 Serial.print("The Measured Distance in cm:");
 Serial.println(cm);
 if(cm<100)(
  // while(true)(
  Serial.println("Alert!!");
 // Wait at least 1000ms before next measurement
delay(1000);
```

## Output

1) If the distance is less than 100 cms, it alerts.



2) If the distance is more than 100 cms, it won't alert.





unsigned long t1; unsigned long t2; unsigned long pulse\_width

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## 3) Simulation and code execution













