Assignment -4

Assignment Date	1 October 2022
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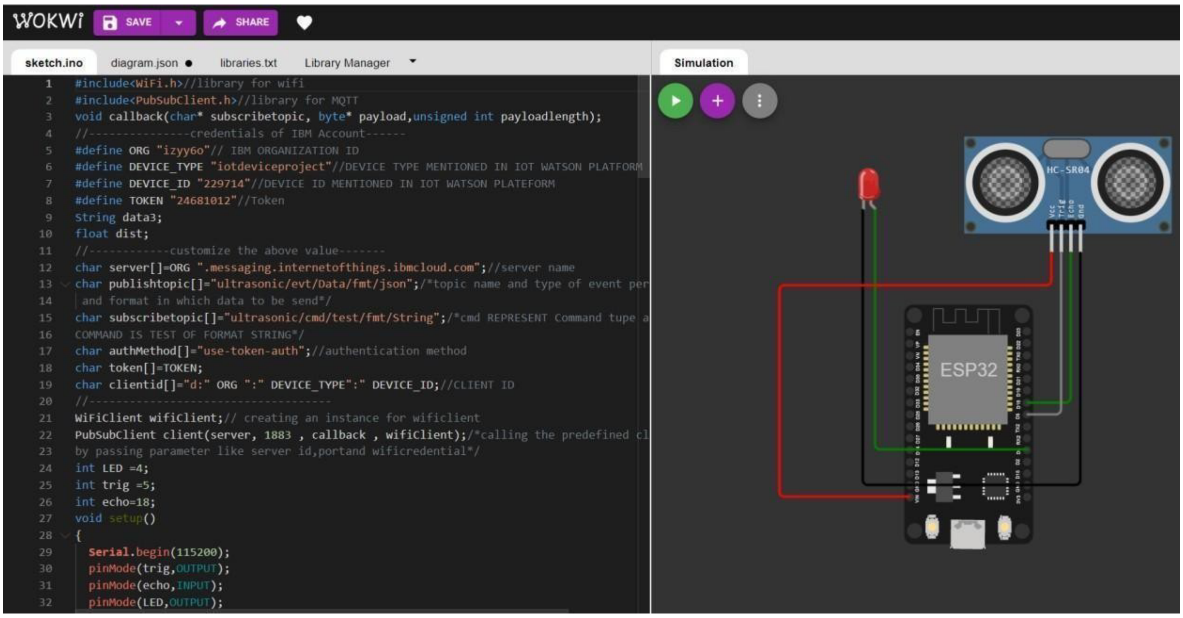
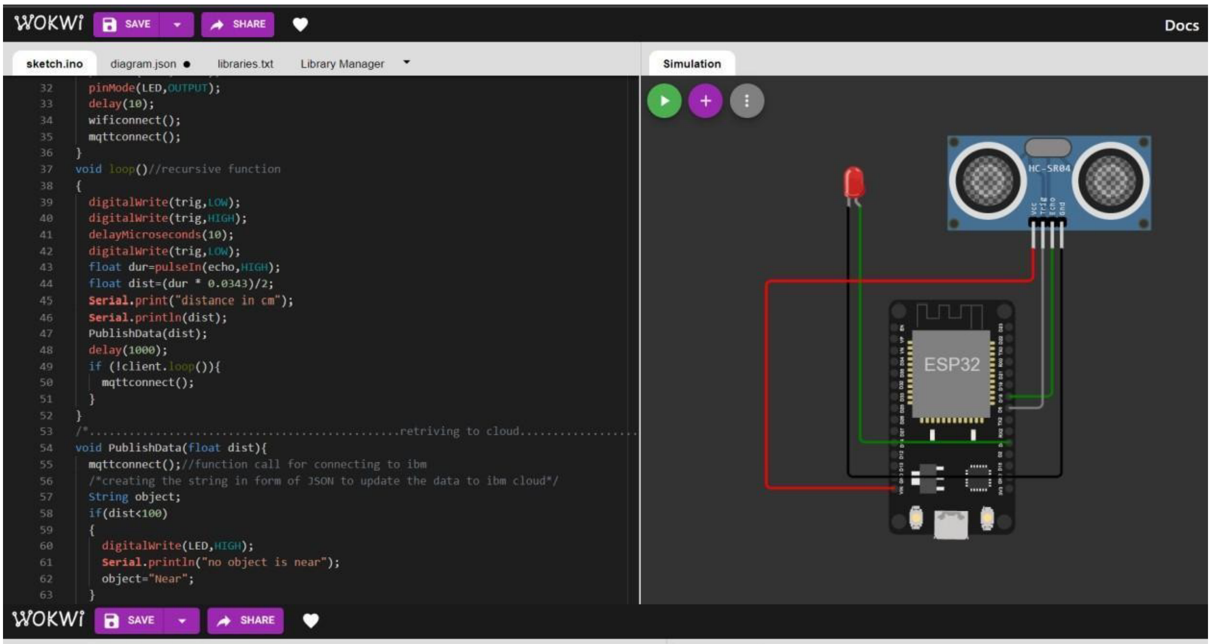
Student Roll Number	622119104088
Maximum Marks	2 Marks

Question-1:

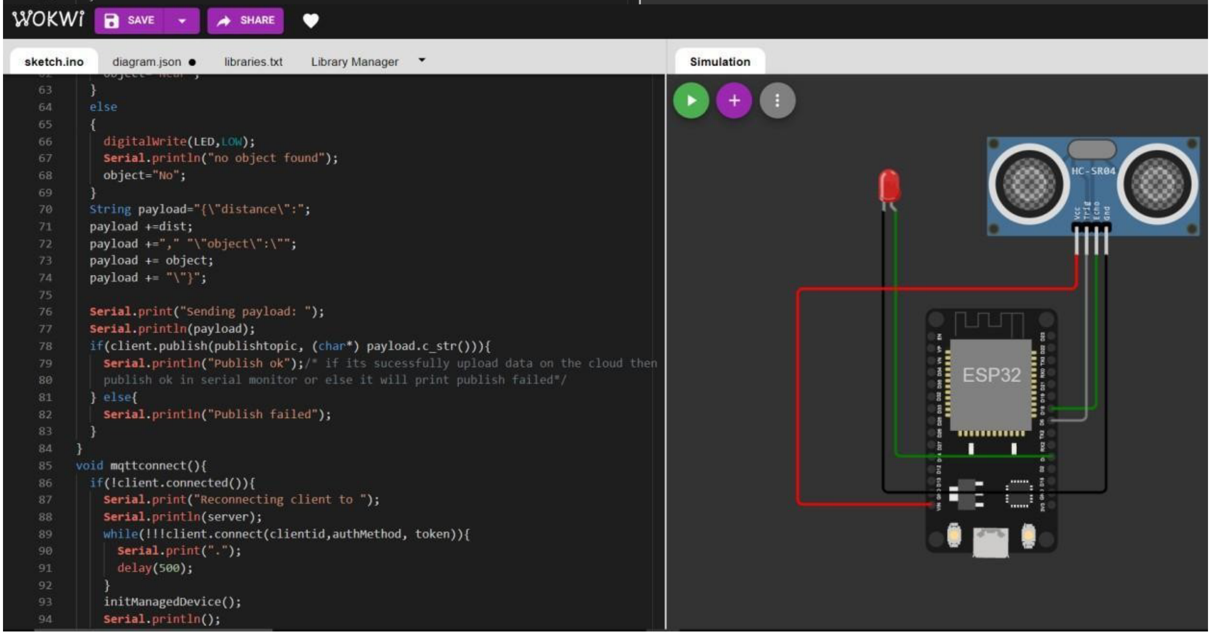
Write code and connections in wokwi for ultrasonic sensors. Whenever distance is less than 100 cms send "alert" to ibm cloud and display in device recent events.



```
#include<WiFi.h>//library for wifi
#include<PubSubClient.h>//library for MQTT
void callback(char* subscribetopic, byte* payload,unsigned int payloadlength);
//---------------credentials of IBM Account------
#define ORG "izyy6o"// IBM ORGANIZATION ID
#define DEVICE_TYPE "iotdeviceproject"//DEVICE TYPE MENTIONED IN IOT WATSON PLATFORM
#define DEVICE_ID "229714"//DEVICE ID MENTIONED IN IOT WATSON PLATEFORM
#define TOKEN "24681012"//Token
String data3;
float dist;
//------------customize the above value-------
char server[]=ORG ".messaging.internetofthings.ibmcloud.com";//server name
char publishtopic[]="ultrasonic/evt/Data/fmt/json";/*topic name and type of event per
 and format in which data to be send*/
char subscribetopic[]="ultrasonic/cmd/test/fmt/String";/*cmd REPRESENT Command tupe a
COMMAND IS TEST OF FORMAT STRING*/
char authMethod[]="use-token-auth";//authentication method
char token[]=TOKEN;
char clientid[]="d:" ORG ":" DEVICE_TYPE":" DEVICE_ID;//CLIENT ID
//-----------------------------------
WiFiClient wifiClient;// creating an instance for wificlient
PubSubClient client(server, 1883 , callback , wifiClient);/*calling the predefined cl
by passing parameter like server id,portand wificredential*/
int LED =4;
int trig =5;
int echo=18;
void setup()
{
  Serial.begin(115200);
  pinMode(trig,OUTPUT);
  pinMode(echo,INPUT);
  pinMode(LED,OUTPUT);
```

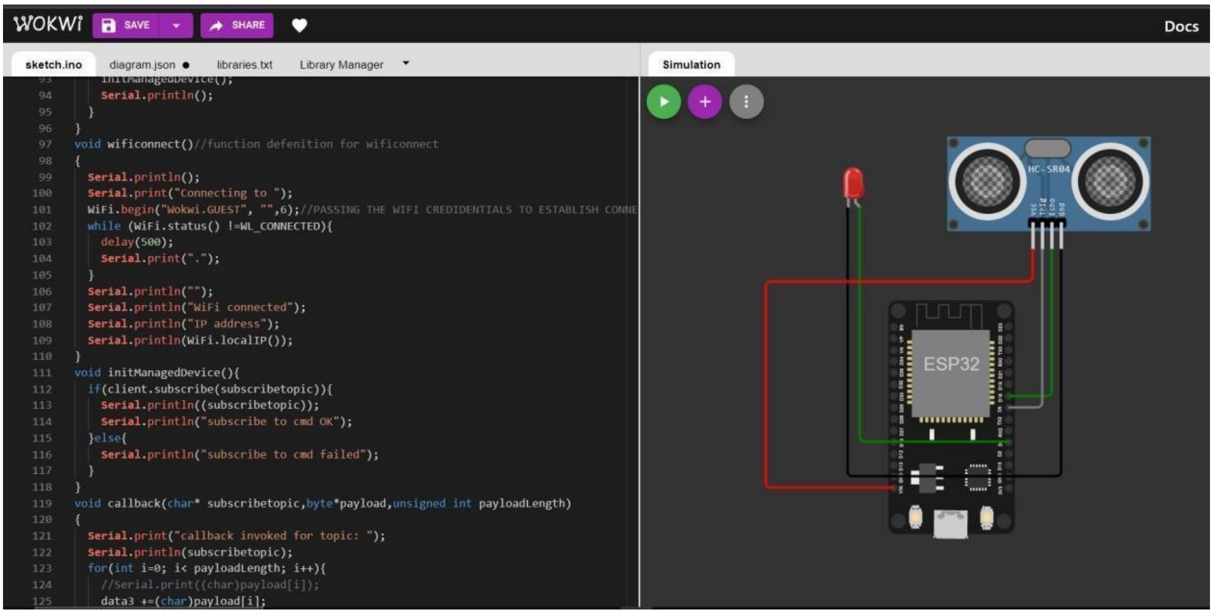


```
  pinMode(LED,OUTPUT);
  delay(10);
  wificonnect();
  mqttconnect();
}
void loop()//recursive function
{
  digitalWrite(trig,LOW);
  digitalWrite(trig,HIGH);
  delayMicroseconds(10);
  digitalWrite(trig,LOW);
  float dur=pulseIn(echo,HIGH);
  float dist=(dur * 0.0343)/2;
  Serial.print("distance in cm");
  Serial.println(dist);
  PublishData(dist);
  delay(1000);
  if (!client.loop()){
    mqttconnect();
  }
}
/*............................................retriving to cloud.................
void PublishData(float dist){
  mqttconnect();//function call for connecting to ibm
  /*creating the string in form of JSON to update the data to ibm cloud*/
  String object;
  if(dist<100)
  {
    digitalWrite(LED,HIGH);
    Serial.println("no object is near");
    object="Near";
  }
```

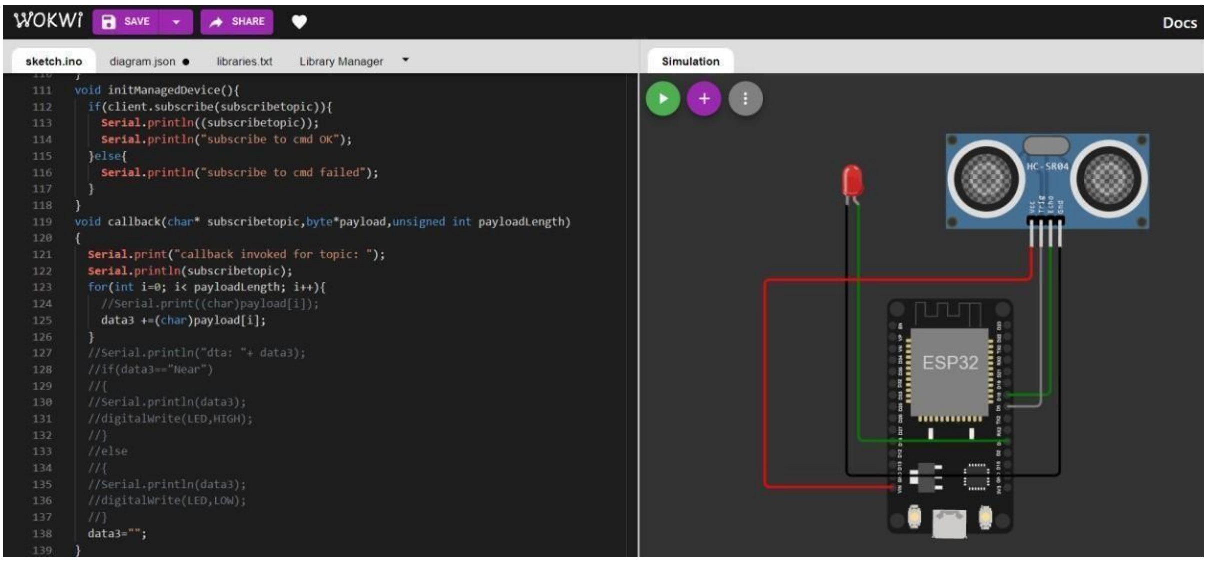


```
  }
  else
  {
    digitalWrite(LED,LOW);
    Serial.println("no object found");
    object="No";
  }
  String payload="{\"distance\":";
  payload +=dist;
  payload +="," "\"object\":\"";
  payload += object;
  payload += "\"}";

  Serial.print("Sending payload: ");
  Serial.println(payload);
  if(client.publish(publishtopic, (char*) payload.c_str())){
    Serial.println("Publish ok");/* if its sucessfully upload data on the cloud then
    publish ok in serial monitor or else it will print publish failed*/
  } else{
    Serial.println("Publish failed");
  }
}
void mqttconnect(){
  if(!client.connected()){
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while(!!!client.connect(clientid,authMethod, token)){
      Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
```

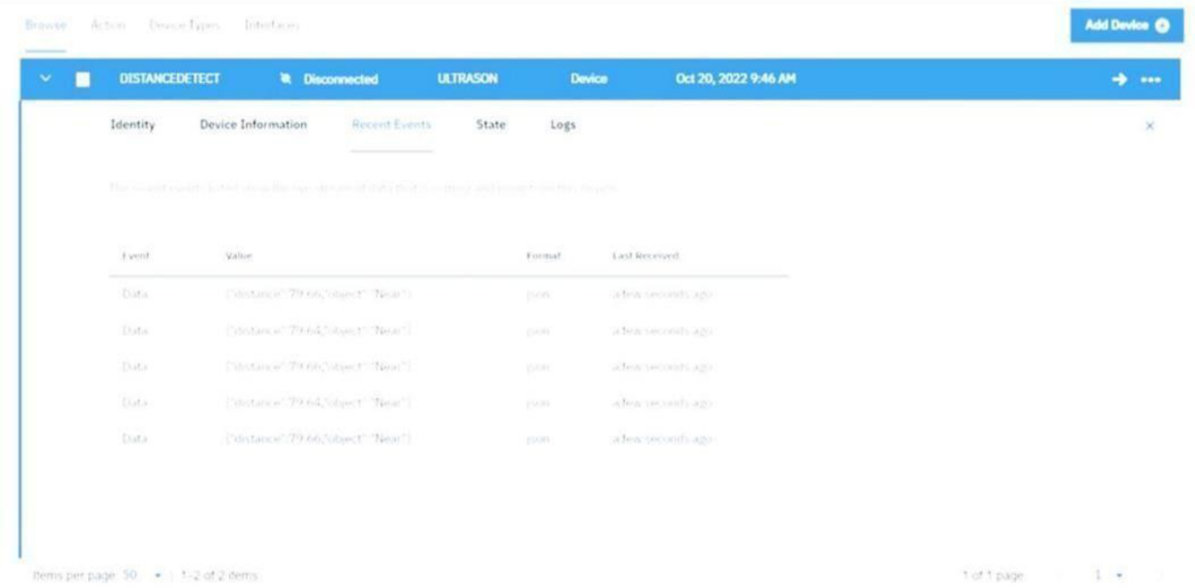


```
    initManagedDevice();
    Serial.println();
  }
}
void wificonnect()//function defenition for wificonnect
{
  Serial.println();
  Serial.print("Connecting to ");
  WiFi.begin("Wokwi.GUEST", "",6);//PASSING THE WIFI CREDIDENTIALS TO ESTABLISH CONNE
  while (WiFi.status() !=WL_CONNECTED){
    delay(500);
    Serial.print(".");
  }
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address");
  Serial.println(WiFi.localIP());
}
void initManagedDevice(){
  if(client.subscribe(subscribetopic)){
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  }else{
    Serial.println("subscribe to cmd failed");
  }
}
void callback(char* subscribetopic,byte*payload,unsigned int payloadLength)
{
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for(int i=0; i< payloadLength; i++){
    //Serial.print((char)payload[i]);
    data3 +=(char)payload[i];
```



```
}
void initManagedDevice(){
  if(client.subscribe(subscribetopic)){
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  }else{
    Serial.println("subscribe to cmd failed");
  }
}
void callback(char* subscribetopic,byte*payload,unsigned int payloadLength)
{
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for(int i=0; i< payloadLength; i++){
    //Serial.print((char)payload[i]);
    data3 +=(char)payload[i];
  }
  //Serial.println("dta: "+ data3);
  //if(data3=="Near")
  //{
  //Serial.println(data3);
  //digitalWrite(LED,HIGH);
  //}
  //else
  //{
  //Serial.println(data3);
  //digitalWrite(LED,LOW);
  //}
  data3="";
}
```

DATA SENT TO IBM CLOUD ON NO OBJECT DETECTED



DISTANCEDETECT	Disconnected	ULTRASON	Device	Oct 20, 2022 9:46 AM

[illegible]

Event	Value	Format	Last Received
Data	{"distance":79.66,"object":"Near"}	json	a few seconds ago
Data	{"distance":79.64,"object":"Near"}	json	a few seconds ago
Data	{"distance":79.66,"object":"Near"}	json	a few seconds ago
Data	{"distance":79.64,"object":"Near"}	json	a few seconds ago
Data	{"distance":79.66,"object":"Near"}	json	a few seconds ago

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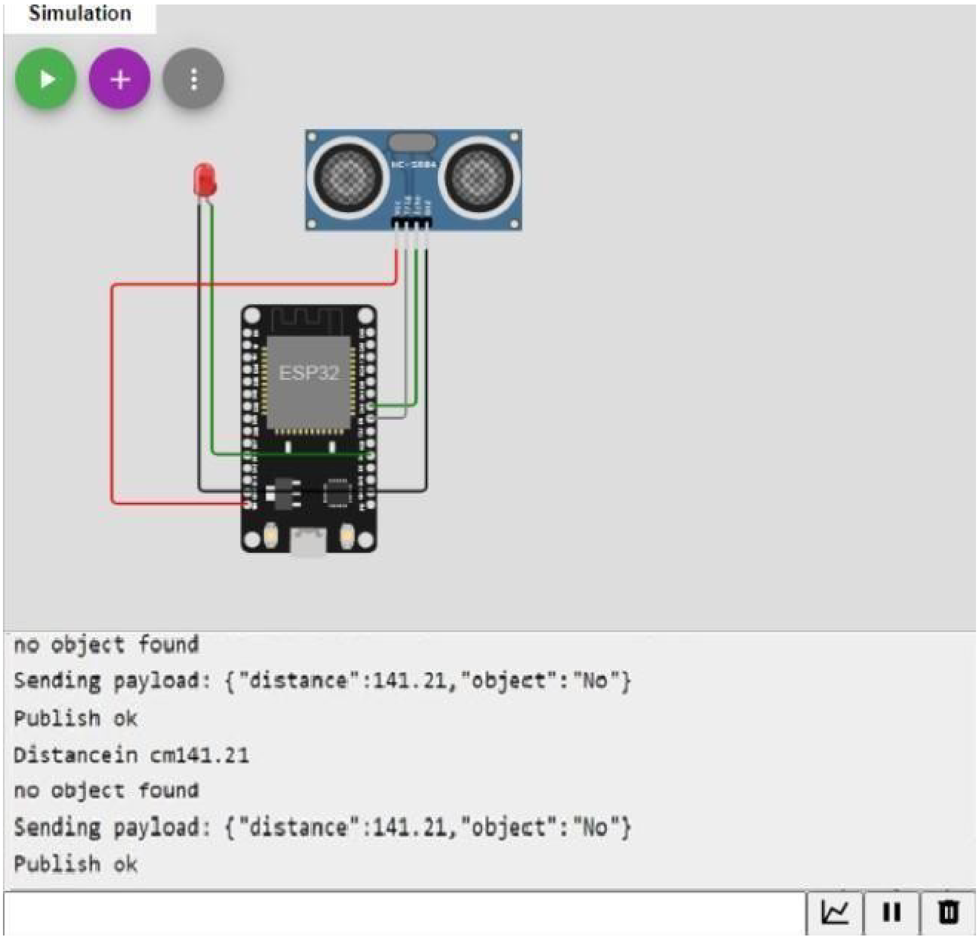
WHEN OBJECT DETECTED BY ULTRASONIC DETECTOR SENSOR



```
no object found
Sending payload: {"distance":141.21,"object":"No"}
Publish ok
Distancein cm141.21
no object found
Sending payload: {"distance":141.21,"object":"No"}
Publish ok
```