# ASSIGNMENT - 1

### **BUILD A SMART HOME IN THINKERCAD**

Assignment date	26 September 2022	
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Maximum marks	2 marks	

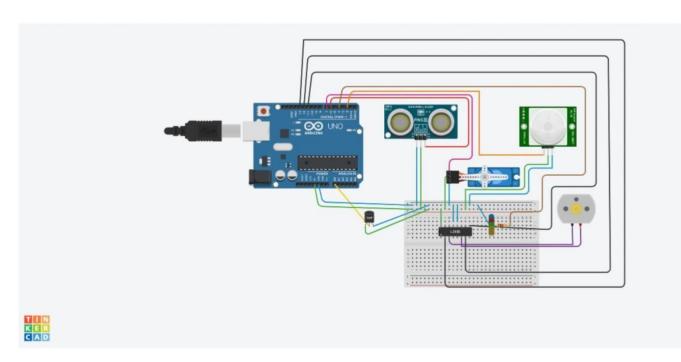
# QUESTION -1:

Build a smart home in thinkercad

Use atleast 2 sensor, led, buzzer in a circuit. Stimulate in a single code.

## **Solution:**

## CIRCUIT



## CODE:

#include<Servo.h>

int us = 6; int

servo = 7;

Servo servo1;

```
void setup() {
Serial.begin(9600);
servo1.attach(servo);
pinMode(2,INPUT);
pinMode(4,OUTPUT);
pinMode(11,OUTPUT);
pinMode(12,OUTPUT);
pinMode(13,OUTPUT);
pinMode(A0,INPUT);
digitalWrite(2,LOW);
digitalWrite(11,HIGH);
}
void loop() {
 long duration, inches, cm;
 pinMode(us, OUTPUT);
 digitalWrite(us, LOW);
delayMicroseconds(2);
digitalWrite(us, HIGH);
delayMicroseconds(5);
digitalWrite(us, LOW);
 pinMode(us, INPUT);
duration = pulseIn(us, HIGH);
inches =
microsecondsToInches(duratio
```

```
n); cm =
microseconds To Centimeters (d\\
uration);
 servo1.write(0);
if(cm < 30)
  servo1.write(120);
  Serial.println("A Person Arrived, Door is Opening.....");
delay(2000);
 }
 else
 {
  servo1.write(0);
 Serial.println("Door is Closed.....");
 }
 int pir = digitalRead(2);
if(pir == HIGH)
  digitalWrite(4,HIGH);
delay(3000);
 else if(pir == LOW)
  digitalWrite(4,LOW);
 }
```

```
float value=analogRead(A0); float
temp=(((value/1024)*5.0199)-0.5)*100;
 Serial.print("temp is ");
Serial.println(temp);
delay(3000);
 if(temp > 20)
  digitalWrite(12,HIGH);
digitalWrite(13,LOW);
 }
 else
 {
  digitalWrite(12,LOW);
digitalWrite(13,LOW);
}
}
long microsecondsToInches(long microseconds) {
return microseconds / 74 / 2;
}
long microsecondsToCentimeters(long microseconds) {
return microseconds / 29 / 2;
}
```