

```
CODE:
int t=4;
int e=3;
int l=11;
void setup()
{
  pinMode(t,OUTPUT);
  pinMode(l,OUTPUT);
  pinMode(e,INPUT);
  pinMode(13,OUTPUT);
  pinMode(12,OUTPUT);
```

```
pinMode(11,OUTPUT);
 Serial.begin(9600);
}
void loop()
{
 digitalWrite(t,0);
 digitalWrite(t,1);
 delayMicroseconds(10);
 digitalWrite(t,0);
 float dur = pulseIn(e,HIGH);
 int dis = (dur*0.0343)/2;
 Serial.print("Distnce is ");
 Serial.println(dis);
 analogWrite(I,map(dis,2,320,255,0));
 int a=digitalRead(2);
 Serial.println(a);
 if(a==1){
   tone(13,300);
   delay(1000);
 }
```

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else{
  noTone(13);
}
double z=analogRead(A0);
double s=(((z/1024)*5)-0.5)*100;
Serial.println(s);
if(s>100)
  digitalWrite(12,1);
else
  digitalWrite(12,0);
```