ProjectReport

Date	17Nov2022
TeamID	PNT2022TMID19258
Project	Signs with Smart Connectivity for
	Better Road Safety

1. INTRODUCTION:

1.1 ProjectOverview:

- ➤ TheObjectiveofthisistoreplacethestaticsignboards. Instead,smartconnectedsignboardsare used.
- Thesesmartconnected signboards get the speed limitations from a web appusing we ather API and update automatically. Based on the weather changes the speed may increase or decrease.
- ➤ Basedonthetrafficandfatalsituationsthediversionsignsaredisplayed.Guide(forS chools),Warning,andService

 (Hospitals,Restaurants)signsarealsodisplayedaccordingly.

1.2 Purpose:

The Purpose of this project is to develop a digital sign board system where the normal signs are displayed with their actual names. And also, to create a wareness of the roads a fety to every one and obey the traffic rules. To create a better view and warn in the night time.

2. LiteratureSurvey:

2.1:ExistingProblem:

- ➤ Damagecriteriainstaticsignboards:
 - o Paintdeterioration
 - o FoldedSheets
 - o PoleBent
 - o ConcealmentbyVegetation
- > Driverscanfaceconfusingroadsignsat certaincircumstances.
- ➤ TheNationalCrimeRecordsBureau(NCRB)2022reportstatesthattherewere155, 622fatalities, highestsince2014,out ofwhich69,240deathswereduetotwowheelers.
- ➤ AstudybyIITDelhipointsoutthatthenationalhighwaysconstituteonly2% of the length of roadsinIndia, buttheyaccountfor 30.3% of totalroadaccidents and 36% of deaths.
- ➤ Deathsbyaccidentsonroadsincreasedbyalmost17per centin2021,indicatinganincreaseintherateof deathsper1,000vehicles.

S.No.	Title andAuthor	YearandP	Inferences
		ublication	
1.	Wirelessdigitaltrafficsignsofthefut ure. ChaiK.Toh,Juan- CarlosCano,CarlosFernandez- Laguia,PietroManzoni,CarlosT. Calafate.	2018,Institutionof EngineeringandTe chnology(IET).	Theissuesandchallengesf acingcurrenttrafficsigns, andhowitwillevolveintoa next-generationtrafficsignarch itectureusingadvancedwi relesscommunicationstec hnologies.
2.	TrafficSignBoardDetectionandR	2020,International	Real-
	ecognitionusingAugmented	ResearchJournalof	timeapproachforfastan

	Reality. AkshataAnantPrabhu,Deepika V.D.,Muralikrishna.N,P.Vaishna viAcharya,A.R.Manjula	Engineeringand Technology(IRJ ET).	Frame work for traffic sign recognition Which super imposes virtual object sonto a realsceneunderalltypesof drivingsituations,includi ngunfavorableweatherco nditionsandgivesavoiceal ertwiththehelpofspeakers .
3.	AutomaticSignboardDetectionS ystem bythe Vehicles Anushree.A.S,HimanshuKumar,Id ahIram,KumarDivyam,Rajeshwari .J	2019,IJESC.	Signboarddetectionsyst eminthevehiclewhichw illdetectthesignboardan dwarnthedriveraboutit. Itdisplaysthealertmessa georinformationonprov idedLCDandvoicealertt hroughspeakers.
4.	DevelopmentandTestingofRoad Si gnsAlertSystem Us ing aSmartMobilePhone EricM.Masatu,RamadhaniSinde,an dAnaelSam	2022,HindawiJourna lofAdvancedTransp ortation).	Thepaperisbasedonthere searchaboutAdvancedDr iverAssistancesystemwh ichisoneofthesalientfeatu resofintelligentsystemint ransportation.
5.	AWi- FibasedElectronicRoadSignforEn hancingtheAwarenessofVehicle. ABhawiyuga,RASabriansyah,WYa hya,REPutra.	2016, IOP PublishingLtd.	Employmentof vehicularnetworkconcept inwhichavehiclecancom municatewithothervehicl esorwiththeinfrastructure installedalongtheroad.
6.	AutomaticDetectionofRoadSignst o ControlVehicleSpeed AnujaNanal,PoojaMotwani,	2019,InternationalJo urnalofComputerAp plications.	ElectronicDisplaycontrol lermeantforcontrollingve hiclespeedandmonitorsth ezones,

PragatiPawar,RajatNirhale,RahulPa	andwhichcanalsodisplay
til.	thespeedtotherfreaderwit
	hthehelpofunitattachedin
	thecar.

2.2. References

- 1. Torralba, J. P.García-Martín, J. M. González-Romo, M.García-Castellano, J.Peral-Lópezand V. Pérez-Mira, "An Autonomous, Intelligent Sign Control System Using Wireless Communication and LED Signs for Rural and Suburban Roads, "in IEEE Intelligent Transportation Systems Magazine, vol. 14, no. 2, pp. 115-128, March-April 2022, doi: 10.1109/MITS. 2021. 3049375.
- 2. Toh, C.K., Cano, J.-C., Fernandez-Laguia, C., Manzoni, P. and Calafate, C.T.(2019), Wireless digital traffic signs of the future. IETNetw., 8:74-78. https://doi.org/10.1049/iet-net.2018.5127
- 3. A., Aparna& Shiravale, Sankirti. (2016).RealTimeTrafficSignboardDetectionandRecognitionfrom StreetLevelImageryfor SmartVehicle.InternationalJournalof ComputerApplications. 135. 18-22.10.5120/ijca2016908267.
- 4. A BhawiyugaRA Sabriansyah, W YahyaandREPutra*etal*"AWi-FibasedElectronicRoadSignfor EnhancingtheAwarenessofVehicleDriver", inIOPPublishingLtd2017*J. Phys.: Conf. Ser*.801012085
- 5. KarthikeyanD, Enitha C, BharathiS, DurkadeviK, 2020, TrafficSignDetectionandRecognitionusingImageProcessing, INTERNATIONALJOURNALOF

ENGINEERINGRESEARCH&TECHNOLOGY(IJERT)NCICCT- 2020 (Volume8–Issue08)

- 6. BhawnaSaini1, RachnaDevi2, Shilpi Dhankhar 3, Mohammad-ziaul-Haque4, Jagandeep Kaur 5, Smart LED Display Boards, International Journal of Electronic and Electrical Engineering. ISSN 0974-2174 Volume 7, Number 10(2014), pp. 1057-1067.
- 7. Ramalingam, Mritha& chandrasegar,&gowrishankar,. (2014).Asurveyoflightemittingdiode(LED)DisplayBoard.IndianJournalof ScienceandTechnology. 7. 185-188.10.17485/ijst/2014/v7i2.3.
- 8. EricM. Masatu, RamadhaniSinde, AnaelSam,Development andTestingofRoadSignsAlertSystemUsinga SmartMobile Phone, Journalof AdvancedTransportation, 10.1155/2022/5829607,**2022**, (1-14), (2022).
- 9. ZoltánFazekas, GáborBalázs, CsabaGyulai, PéterPotyondi, PéterGáspár, Road-TypeDetection BasedonTrafficSignandLane
 Data, Journal of AdvancedTransportation, 10.1155/2022/6766455, **2022**, (1-19), (2022).
- 10. JuanhongXie,GuojianShi, WeizhiZhu,IntelligentRecognitionTechnologyfor theSegmentationof

TrafficIndicationImagesConcerningDifferentPavementMaterials,AppliedBionicsan dBiomechanics,10.1155/2022/6278240,**2022**, (1-7), (2022).

2.3. ProblemStatementDefinition:

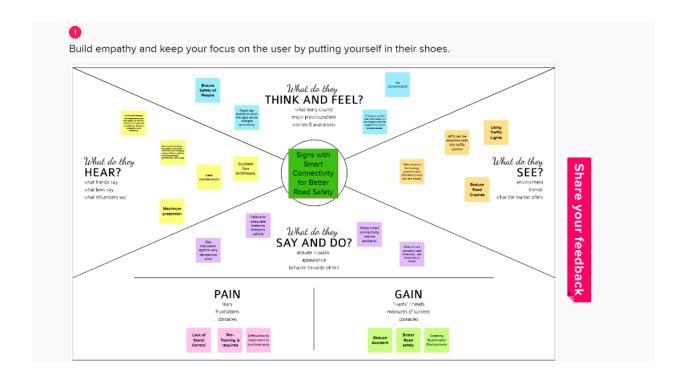
Toreplacethestaticsignboards, withsmart connecteddigitalsignboards. These smart connected signboards get the speed limitations from weather API

andupdateautomatically.

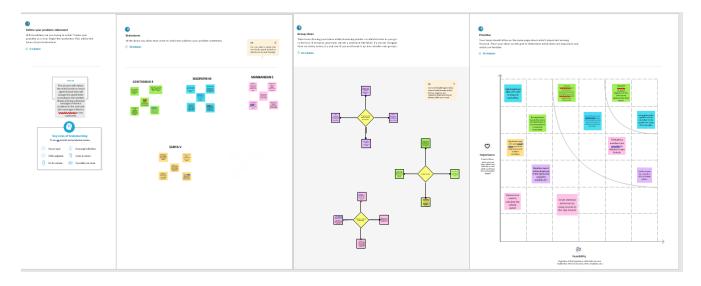
Basedontheweatherchangesthespeedmayincreaseordecrease. It will display the normal lsigns innecessary places with wording stobe aware of the signs. Based on the traffic and fatal situations the diversion signs are displayed. Guide (Schools), Warning and Service (Hospitals, Restaurant) signs are also displayed accordingly. Change of modes will take place automatically.

3. IdeationandProposedSolution:

3.1. EmpathyMapCanvas:



3.2. Ideation&Brainstorming:

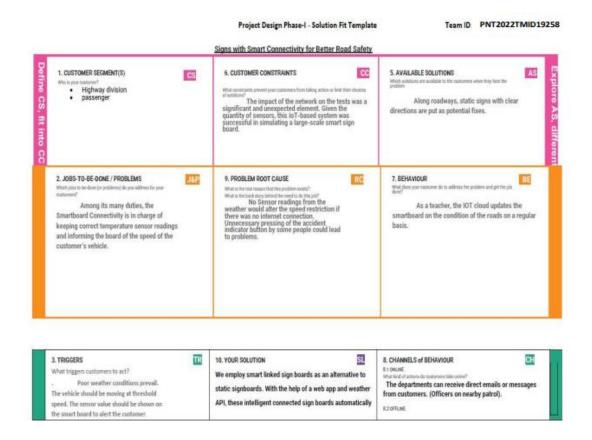


3.3. ProposedSolution:

S.No.	Parameter	Description
1.	ProblemStatement(Problemtobesolved)	InpresentSystemstheroadsignsandthespeed limitsareStatic.Buttheroadsignscanbechang edinsomecases.Wecanconsidersomecases whentherearesomeroaddiversionsduetohea vytrafficorduetoaccidentsthenwecanchang etheroadsignsaccordingly,iftheyaredigitaliz ed.Thisprojectproposesasystemwhichhasdi gitalsignboardsonwhichthesignscanbechan geddynamically.Ifthereisrainfallthentheroa dswillbeslipperyandthespeedlimitwouldbe decreased.Thereisawebappthroughwhichy oucanenterthedataoftheroaddiversions,acci dentproneareasandtheinformationsignboar dscanbeenteredthroughwebapp.Thisdataisr etrievedanddisplayedonthesignboardsaccor dingly.
2.	Idea/Solutiondescription	TheIdeaistoreplacethestaticsignboards.Inst ead,smartconnectedsignboardsareused.The sesmartconnectedsignboardsgetthespeedli mitationsfromawebappusingweatherAPIan dupdate

		automatically.Basedontheweatherchange sthespeedmayincreaseordecrease.Basedo nthetrafficandfatalsituationsthediversions ignsaredisplayed.Guide(forSchools),War ningandService(Hospitals,Restaurant)sig nsarealsodisplayedaccordingly. Additionally,Speedcameraintegratedwithi mageprocessingtechniqueisaddedtodetect anytrafficspeedviolationsandchargefines.
3.	Novelty/Uniqueness	UsageofspeedcameraintegratedwithImag eProcessingtechniquefordetectionofspeed violation.
4.	SocialImpact/CustomerSatisfaction	DiversionIndicationSystemiftrafficorconstructionsahead.SpeedlimitInstructions.Guide (forSchools),WarningandService(Hospitals,Restaurant)signsaredisplayed.
5.	BusinessModel(RevenueModel)	SinceImageProcessingandAPIsareusedfor monitor,thisprojectemploysadecentbusines sstrategyandenhanceservices.
6.	ScalabilityoftheSolution	Low-costImplementationandMaintenance.Dur abilityisoftheproductishigh.

3.4. ProblemSolutionFit:



4. Requirements:

4.1. Functional Requirement:

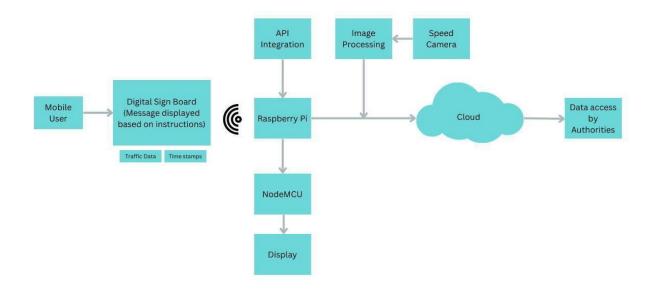
FR No.	FunctionalRequirement(Epic)	SubRequirement(Story/Sub-Task)
FR-1	UserVisibility	SignBoardwillhaveand clearandinteractiveUIsothatitwillbeclearlyvisibletoal
FR-2	UserUnderstanding	The signs that are to be displayed in the sign board will be with this respective names, so that the users can clearly understand everything
FR-3	UserConvenience	Signswillbedisplayedflawlesslysuchthatit willbeofbetterconvenience.

4.2. Non-FunctionalRequirement:

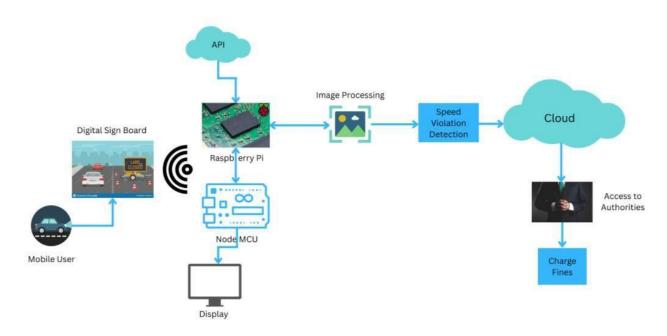
FR No.	Non-FunctionalRequirement	Description	
NFR-1	Usability	Formultiplesigndisplay,timestampswillbeallo catedforeachsign. It willautomaticanddynamicallychangeable.Non eedformanualoperations.	
NFR-2	Security	Onlyrequiredcanwillbeshowed.Nochanceofsecur ityvulnerability.	
NFR-3	Reliability	Morereliablethantheexistingsystem	
NFR-4	Performance	Acceptableperformancewithdynamicupdatingofdat aregardingweather,traffic,etc.	
NFR-5	Availability	Itwillavailableforworkingevery24/7.	
NFR-6	Scalability	Implementation and Maintenance cost will beless, so that the product is highly scalable.	

5. ProjectDesign:

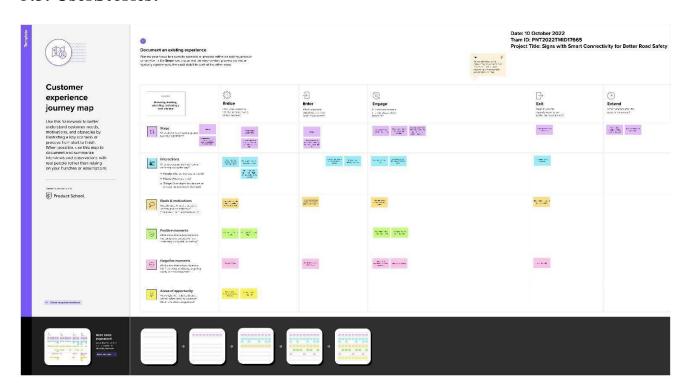
5.1. DataFlowDiagram:



5.2. Solutionand Technical Architecture:



5.3. UserStories:



6. ProjectPlanning&Scheduling:

6.1. SprintPlanning&Estimation:

Sprint	FunctionalR equirement(Epic)	Ţ	JserStory/Task	Story Points	TeamMembers
	UserRegistr ation	siteb	Asauser,Icanregisterontheweb sitebyenteringmyemail,passw ord,andconfirmingmypasswor d.		Surya V
Sprint-1	AdminRegi stration	eusi	Asanadmin,Icanlogintothewebsit eusingmycredentialsandaccessth edata.		Boopathi M
	Login	UserandAdmincanlogintothewe bsitebyenteringemail&password .		1	Gowthaman R
	Dashboard	Developadashboardforthewebsitefor knowledgeaboutroadrules		3	Manikandan S
Sprint	FunctionalR equirement(Epic)		UserStory/Task	Story Points	TeamMembers
	Node-RedUI		DevelopaNode-RedUIFlow.	2	Boopathi M
	Node- RedDashb		DevelopaNode- RedUIDashboard.	2	Manikandan S
Sprint-2	Node- RedWebp age		DevelopaNode- RedWebpagefordisplayingthed ata.	3	Surya V
	Node- RedDataChe	ck	CheckthedatadisplayedontheNo de-RedDashboardUI.	3	Gowthaman R

Sprint	FunctionalR equirement(Epic)	UserStory/Task	Story Points	TeamMembers
Somint 2	APIIntegration	Integratethenecessary API's.	3	Gowthaman R
Sprint-3	DevelopPython Code	DevelopPythoncodetoin tegratethenecessaryAPI s.	2	Boopathi M

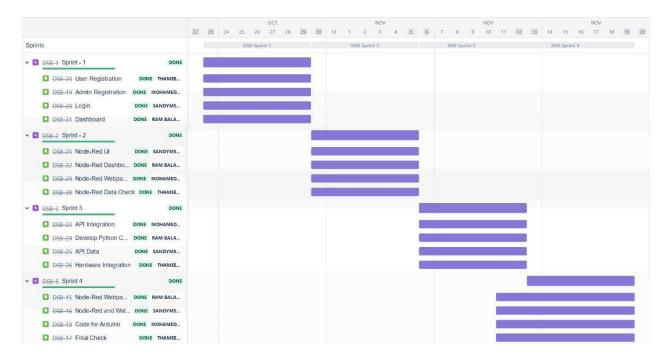
Sprint	FunctionalR equirement(Epic)	UserStory/Task	Story Points	TeamMembers
	APIData	Checkthedatafromw eatherAPI.	2	Manikandan S
	HardwareI ntegration	IntegrateArduinowithTFTD isplayviasimulation.	3	Surya V

Sprint	FunctionalR equirement(Epic)	UserStory/Task	Sprint Points	Team Members
	Node- RedWebpage Data	Developcodetodisplayda taonthewebpageandchec kthenecessary.	2	Boopathi M
Sprint-4	Node- RedandWatso n	ConnectNode- RedwithIBMWatsonplatf ormfordataprocessing(Ra ndomDataGeneration).	3	Surya V
	CodeforArduino	Developcodetodisplaydat ainthedisplayscreen.	3	Gowthaman R
	FinalCheck	Checkingallthesimulationa ndservicesworkingperfectl yanddisplaydataandfinalsu bmissionofproject.	2	Manikandan R

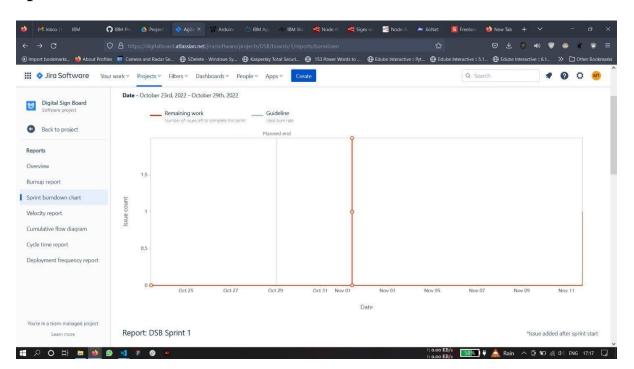
6.2.SprintDeliverySchedule:

Sprint	Total Story Points	Duration	SprintStart Date	SprintEnd Date(Plan ned)	StoryPointsC ompleted(aso nPlannedEnd Date)	Sprint Release Date(Ac tual)
Sprint-1	10	6 Days	24 Oct 2022	29 Oct 2022	10	29 Oct 2022
Sprint-2	10	6 Days	31 Oct 2022	05 Nov 2022	10	05 Nov 2022
Sprint-3	10	6 Days	07 Nov 2022	12 Nov 2022	10	12 Nov 2022
Sprint-4	10	6 Days	14 Nov 2022	19 Nov 2022	10	19 Nov 2022

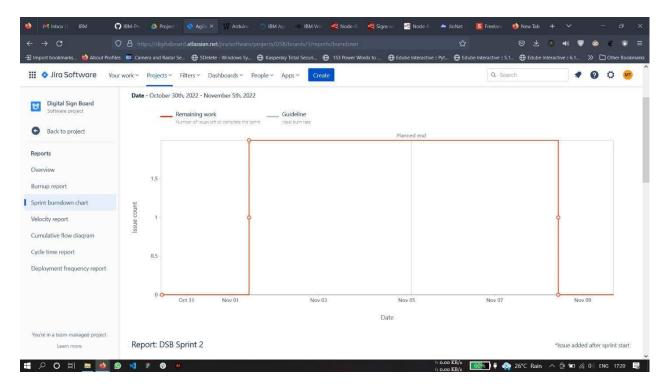
6.3. Reportfrom Jira:



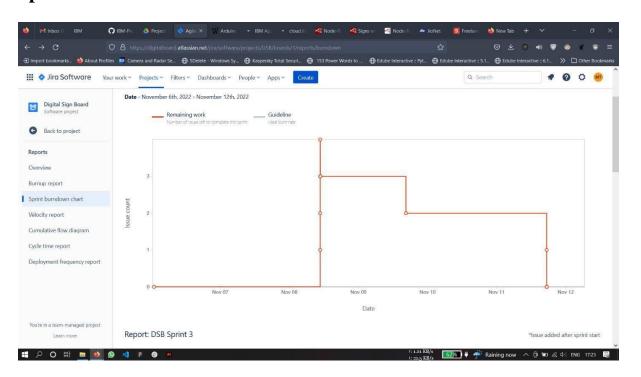
Sprint-1Burndown chart:



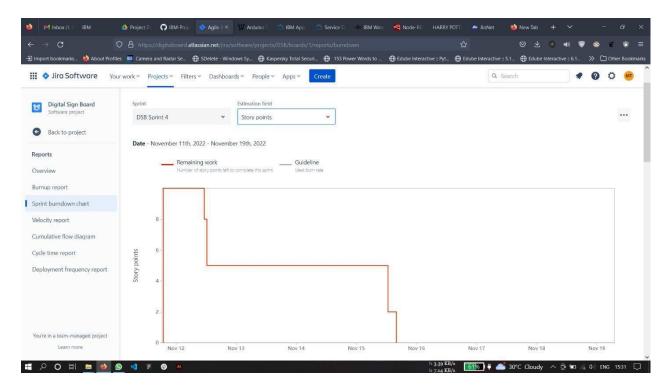
Sprint-2Burndown Chart:



Sprint-3Burndown Chart:



Sprint-4BurndownChart:



7. Coding&Solutioning:

7.1. Feature1:

Climatepredictionisdonefromtemperaturedatafromtheopeanweatherapi.

Butasfornowrandomvaluesareused.

Speed is increased or decreased based on the climate prediction.

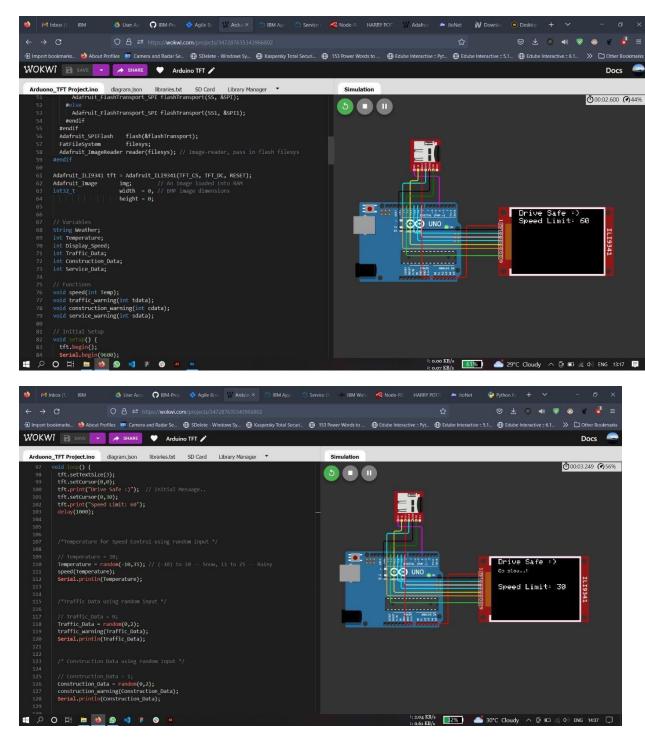
```
/*Temperaturefor SpeedControlusingrandom input*/

//Temperature =20;
Temperature=random(-10,35);//(-10)to 10 -- Snow,11 to25 --
Rainyspeed(Temperature);
Serial.println(Temperature);

/*Speed Controlprocess..
*/voidspeed(int Temp)
{
   tft.fillScreen(Black);
   if(Temp >=-10 &&Temp <=14) //It's Snow
   {</pre>
```

```
Weather="Snowy";tft.setCursor
    (0,0);tft.print("DriveSafe
    :)");tft.setTextSize(2);tft.s
    etCursor(0,40);tft.print("Gos
    low..!");tft.setCursor(0,100)
    ;tft.setTextSize(3);tft.print
    ("SpeedLimit:
    30");delay(3000);tft.fillScre
    en(Black);
  elseif(Temp >=15&&Temp <=25)//It's Rainy</pre>
    Weather="Rainy";tft.setCursor(0,0
    );tft.print("DriveSafe:)");tft.se
    tTextSize(2);tft.setCursor(0,40);
    tft.print("SlipperyRoad
    Ahead");tft.setCursor(0,70);tft.p
    rint("GoSlow..!");tft.setCursor(0
    ,100);tft.setTextSize(3);tft.prin
    t("SpeedLimit:
    40");delay(3000);tft.fillScreen(B
    lack);
  }
    tft.setCursor(0,0);tft.print(
    "DriveSafe!!");tft.setCursor(
    0,30);tft.print("SpeedLimit:
    60");delay(3000);tft.fillScre
    en(Black);
  tft.fillScreen(Black);
voidtraffic_warning(int tdata)
```

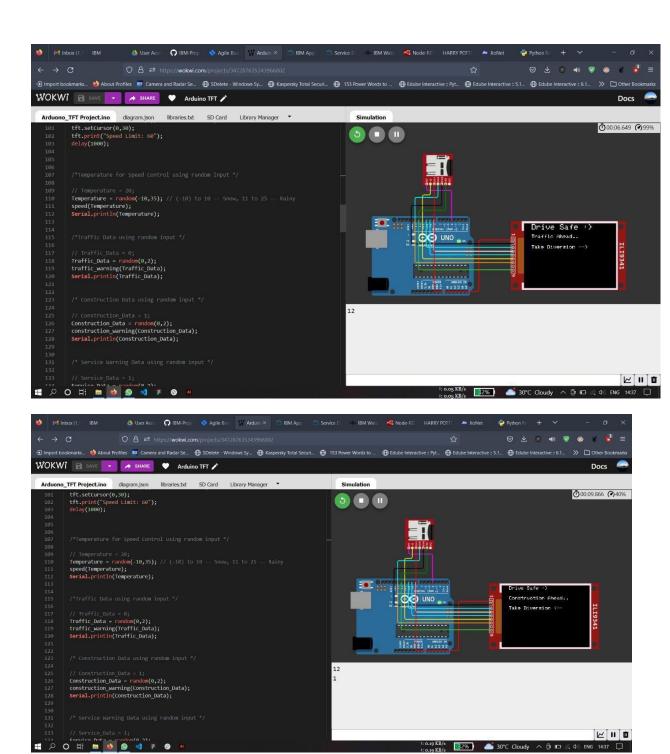
```
tft.fillScreen(Black);
if(tdata ==0)
  tft.setCursor(0,0);tft.prin
  t("DriveSafe :)");
  //tft.setTextSize(2);tft.setC
  ursor(0,40);tft.print("Traffi
  cAhead..");tft.setCursor(0,80
  );
  //tft.setTextSize(3);tft.print
  ("DriveCarefully!");delay(3000
  );tft.fillScreen(Black);
if(tdata ==1)
  tft.setCursor(0,0);tft.print(
  "DriveSafe
  :)");tft.setTextSize(2);tft.s
  etCursor(0,40);tft.print("Tra
  fficAhead..");tft.setCursor(0
  ,80);
  //tft.setTextSize(3);tft.print("
  TakeDiversion--
  >");delay(3000);tft.fillScreen(B
  lack);
```



TrafficdataandConstructionwarningdataare givenwithrandominputs. Basedontrafficandconstructiondata, warningaredisplayed.

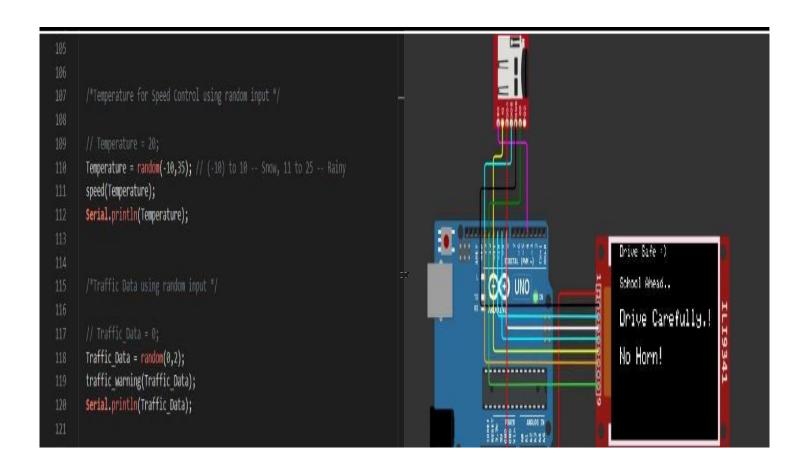
```
=0;Traffic Data=random(0,2);tra
  ffic_warning(Traffic_Data);Seri
  al.println(Traffic_Data);
  =1;Construction_Data=random(0,2);construc
  tion_warning(Construction_Data);Serial.pr
 intln(Construction_Data);
/*Traffic WarningSystem */
voidtraffic_warning(int tdata)
  tft.fillScreen(Black);i
  f(tdata ==0)
    tft.setCursor(0,0);tft.prin
    t("DriveSafe :)");
    //tft.setTextSize(2);tft.setC
    ursor(0,40);tft.print("Traffi
    cAhead..");tft.setCursor(0,80
    );
    //tft.setTextSize(3);tft.print("D
    riveCarefully!");delay(3000);tft.
    fillScreen(Black);
 if(tdata ==1)
    tft.setCursor(0,0);tft.print(
    "DriveSafe
    :)");tft.setTextSize(2);tft.s
    etCursor(0,40);tft.print("Tra
    fficAhead..");tft.setCursor(0
    ,80);
    //tft.setTextSize(3);tft.print("T
    akeDiversion--
    >");delay(3000);tft.fillScreen(Bl
    ack);
```

```
/*Construction WarningSystem
*/voidconstruction_warning(int
cdata)
  tft.fillScreen(Black);
  if(cdata ==0)
    tft.setCursor(0,0);tft.print("Driv
    :)");tft.setTextSize(2);tft.setCur
    sor(0,40);tft.print("ConstructionA
    head..");tft.setCursor(0,80);tft.s
    etTextSize(3);tft.print("DriveCare
    fully..!");delay(2000);tft.fillScr
    een(Black);
  if(cdata ==1)
    tft.setCursor(0,0);tft.print("Driv
    eSafe
    :)");tft.setTextSize(2.5);tft.setC
    ursor(0,40);tft.print("Constructio")
    nAhead..");tft.setCursor(0,80);tft
    .setTextSize(2.5);tft.print("TakeD
    iversion <--
    ");delay(2000);tft.fillScreen(Blac
    k);
```



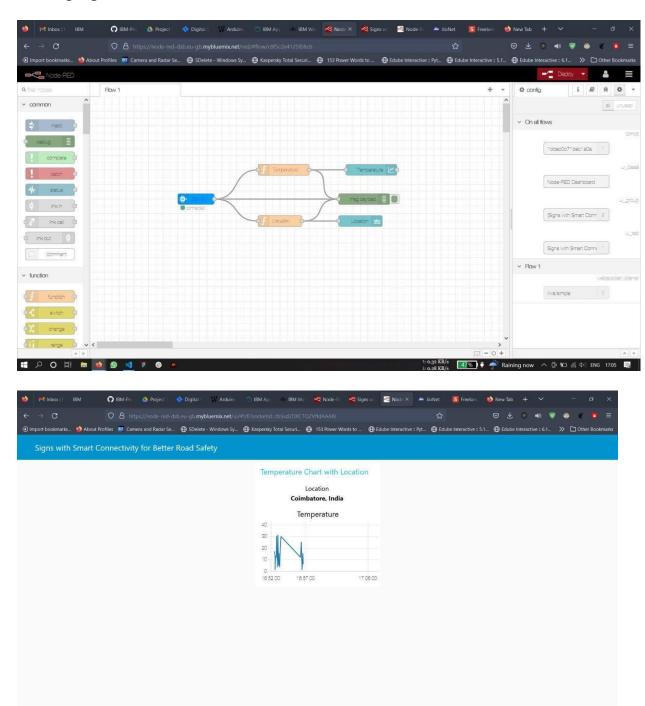
Servicewarningslikeschools, hospitalsandholyplacesaredisplayed.

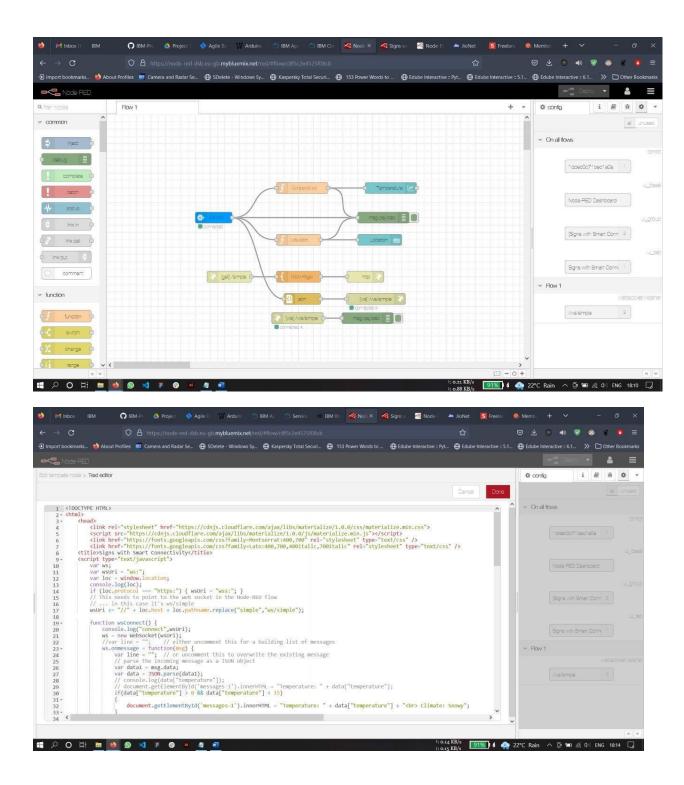
```
/*ServiceWarningData usingrandom input*/
  =1;Service_Data=random(0,2);se
  rvice_warning(Service_Data);Se
  rial.println(Service_Data);
System*/voidservice_warning(int
sdata)
  tft.fillScreen(Black);
  if(sdata ==0)
    tft.setCursor(0,0);tft.print
    ("DriveSafe
    :)");tft.setTextSize(2);tft.
    setCursor(0,40);tft.print("S
    choolAhead..");tft.setCursor
    (0,80);tft.setTextSize(3);
    tft.print("DriveCarefully.!\nNoHorn!");del
    ay(2000);
    tft.fillScreen(Black);
  if(sdata ==1)
    tft.setCursor(0,0);tft.print("
    DriveSafe
    :)");tft.setTextSize(2.5);tft.
    setCursor(0,40);tft.print("Hos
    pitalAhead..");tft.setCursor(0
    ,80);tft.setTextSize(2.5);
    tft.print("DriveCarefully.!\nNoHorn!");del
    ay(2000);
    tft.fillScreen(Black);
```

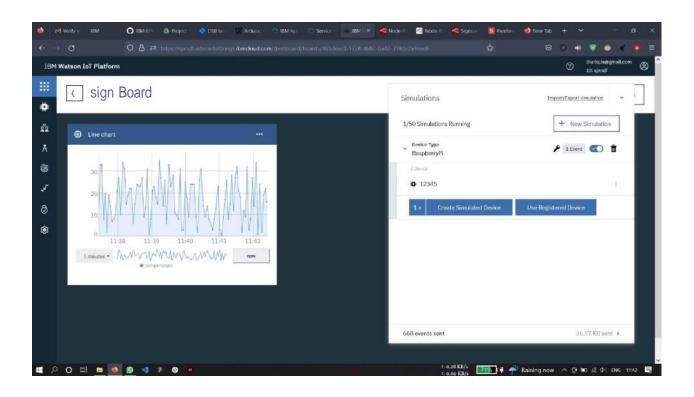


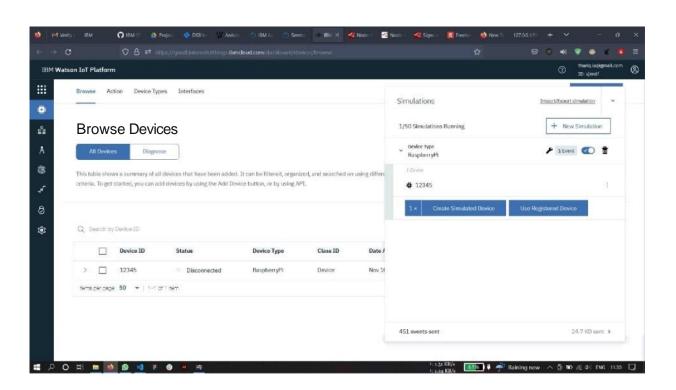
7.2. Feature2:

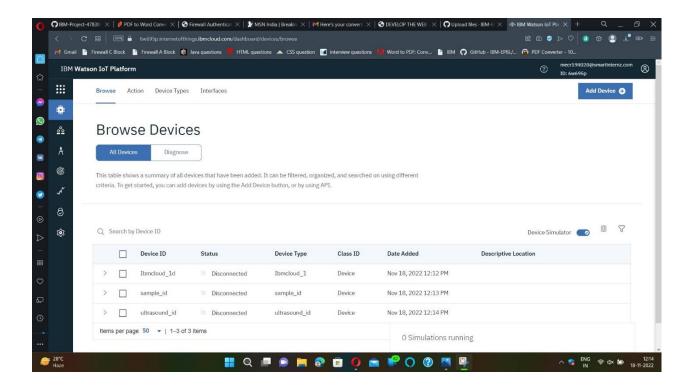
The temperature and the location data are exactly displayed in the webpage using Node—Red and the forthatis randomized using IBMW at son. A device is created for that purpose and is simulated to send data to node—red.











The following features are some ideas we decided to implement but we didn't had much time...

Additionally, a speed cam willbeintegrated with the digital sign board which use Image processing & AI, to get the details of the driver who breaks the traffic rules (especially speed) will be updated in the cloud database.

Also,

for Noparking and Oneway ruleviolations can also be detected and appropriate action can be etaken. Violations of stopsigns in intersection will also be detected using AI.

8. Testing:

8.1. TestCases:

	_					-	- 15	-		
- 1	Date	17-Nov-22								
2	Team ID	PNT2022TMID19258								
3	Project Name	Project - Signs with Smart Conne	1							
4	Maximum Marks	4 marks								
5	Pre-Requisite	Steps To Execute	Test Data	Expected Result	Actual Result	Stat	Comments	TC for Automation(Y/N)	BUG	Executed By
6	IBM Cloud Login ID & Password	1.Go to IBM Cloud signup page 2.Enter e-mail id and other credentials 3.Enter a password		User should sign up IBM cloud and details should be verified	Working as expected	Pass	Results verified	No		R.Gowthaman,M.Boopathi,S.Manikandan,V.Surya
7	IBM Cloud Login ID & Password	3. Verify login by the popup display	https://oloud.ibm.com/logi p	User login to IBM Cloud and should be navigated to IBM Cloud dashboard page	Working as expected	Pass	Results verified	No		R.Gowthaman,M.Boopathi,S.Manikandan,V.Surya
8		1Login to IBM Cloud 2.Click Catalog 3.Search IoT and click create 4.Go to resource list and search Internet of Things platform 5.Press Launch and click Sign in IBM Watson Platform		User should be navigated to IBM IoT Watson Platform	Working as expected	Pass	Results verified	No		R.Gowthaman,M.Boopathi,S.Manikandan,V.Surga
9	IBM Watson IoT Platform	1.Login to IBM Watson Platform 2. Click Add Device 3.Enter the details and click		Temperature sensor values and Location are generated randomly in simulation	Working as expected	Pass	Results verified	No		R.Gowthaman,M.Boopathi,S.Manikandan,V.Surga
	Node Red Installation	1.Install node red and open node		User should be able to see the Node Red page	Working as expected	Pass	Results verified	No		R.Gowthaman,M.Boopathi,S.Manikandan,V.Surya

-		,				**			
	17-Nov-22								
	PNT2022TMID19258								
Project Name	Project - Signs with Smart Conne								
Maximum Marks	4 marks								
Pre-Requisite	Steps To Execute	Test Data	Expected Result	Actual Result	Stat	Comments	TC for Automation(Y/N)	BUG	Executed By
Node Red Installation	1.Select IBM IoT input in Node. In IBM IoT valsors Platform, go to apps and click on generate API keys. 2.Copy & paste generated API keys and token in the IBM IoT input. After entering all details, click the done button. 3.Add debug to the IBM IoT and rename as Msg.psgload and olick on done. Click chart from the desblocard and fill the details add functions to the chart. Check the generated values from the despload growing the safe function node, connect them, add another chart and functions, name them as "Temperature" & "Location". "Temperature" & "Location". "Temperature" & "Location". "Temperature" & "Location". "Finally add light CNVOFF buttors to the IBM IoT and	button for light ON/OFF is	Values of sensors and button for light. ON/OFF should be displayed	Working as expected	Pass	Results verified	No		R.Goethaman,M.Boopathi,S.Manikandan,V.Surya
Python 3.7.0(64 bit) installatio	debug. Verify the output from NICHE REPORTING Local local link 1.Download and install Python 3.7.0 2.Develop python code	https://www.python.org/do wnloads/release/python: 370/	User should be able to develop a python code	Working as expected	Pass	Results verified	No		R.Gowthaman,M.Boopathi,S.Manikandan,V.Surya
⊃ython 3.7.0(64 bit) installatio	1.Downlinstall Python 3.7.0 2.After python code	Bet the output from the cod	User should be able to get the results from the developed code	Working as expected	Pass	Results verified	No		R.Gowthaman,M.Boopathi,S.Manikandan,V.Surya

8.2. UserAcceptanceTesting:

1. PurposeofDocument

The purpose of this document is to briefly explain the test coverage and open issues of the [Product Name] project at the time of the release to User Acceptance Testing (UAT).

2. DefectAnalysis

This reports how sthenumber of resolved or closed bugs at each severity level, and how they were resolved

Resolution	Severity1	Severity2	Severity3	Severity4	Subtotal
By Design	10	4	2	3	20
Duplicate	0	2	2	0	4
External	2	3	0	1	6
Fixed	11	2	4	17	34
NotReproduced	0	0	1	0	1
Skipped	0	0	0	1	1
Won't Fix	0	1	0	3	4
Totals	23	12	9	25	70

3. TestCaseAnalysis

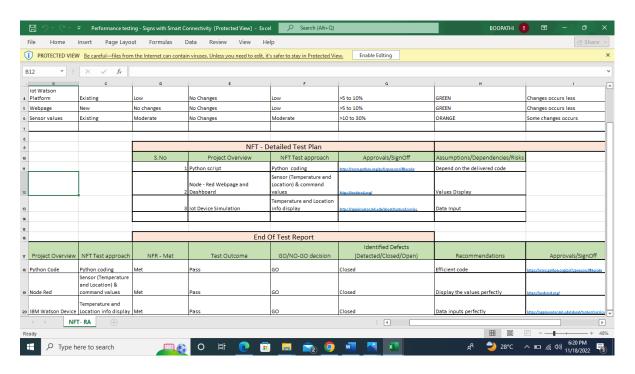
This reports how sthenumber of test cases that have passed, failed, and untested

Section	TotalCases	NotTested	Fail	Pass
PrintEngine	20	0	0	20
ClientApplication	38	0	0	38
Security	3	0	0	3

OutsourceShipping	3	0	0	3
ExceptionReporting	5	0	0	5
FinalReportOutput	10	0	0	10
VersionControl	3	0	0	3

9. Results:

9.1. PerformanceMetrics:



10. Advantages&Disadvantages:

Themainadvantage of this project is that it is a dynamic system which can change different modes of operations automatically.

 $It gathers we at her data \\from open we at her API and displays peed according based on the climate.$

Displayservicewarningslikeschools, hospitalsandholyplaces andwarntoslowdownandbesilent.

TrafficdataandConstructionwarningdataare givenwithrandominputs. Basedontrafficandconstructiondata, warningsaredisplayed.

Additionally, a speed cam willbeintegrated with the digital sign board which use Image processing & AI, to get the details of the driver who breaks the traffic rules (especially speed) will be updated in the cloud database.

Also,

for Noparking and Oneway ruleviolations can also be detected and appropriate action can be etaken. Violations of stopsigns in intersection will also be detected using AI.

11. Conclusion:

The project concluded by replacing the static sign boards with smart connected digit also go also go as a sign boards. Digital road signs are an important part of modern infrastructure and are becoming increasingly common.

Digitalroadsignsarebecomingmorecommonastechnologyimprovesandmorestatesad optthem. Theuseofdigitalroadsignsisexpectedtocontinuetogrowinthefuture asitwouldbeobserveduser-friendly,economic,

environmentfriendly,profitablepromotingroadsafety.Digitalroadsignsaredesignedtoi mproveroadsafetyandefficiencybyprovidingreal-time

informationtodrivers. These signs can display a variety of information,

including speed limits, traffic conditions, and weather warnings.

Digital road signs can

helpdriversbyprovidinginformationthatisnotalwaysavailablefromtraditionalstaticsig ns.

12. FutureScope:

- Inthefuture aspeedcam willbeintegratedwiththedigitalsign board.
- UsingImageprocessing&AI, thedetailsof thedriverwhobreaksthetrafficruleswillbe updatedintheclouddatabase.
- NoparkingandOnewayruleviolationscanalsobe detectedandappropriateactioncanbetaken.
- Violationsofstopsignsinintersectionwill also bedetectedusing AI.

13. Appendix:

```
Code:
/*tft.setTextColor(ILI9341_RED);Futur
eScope:
 Image
  Processing:Spee
  dCam
  NoParking
  One-Way
  Stopsigninintersection
*/
//NodeMcUPinsConnection
//#defineTFT_MOSID7
```

//#defineTFT_SCLKD5

```
//#defineTFT_CSD2
//#defineTFT_DCD4
//#defineTFT_RSTD3
//LibraryFuctions
#include"SPI.h"
#include"Adafruit_GFX.h"
#include"Adafruit_ILI9341.h"
#include<SdFat.h>
#include<Adafruit_SPIFlash.h>
#include<Adafruit_ImageReader.h>
//Colours
#defineBlack0x000000
#defineWhite0xffffff
//ArduinoPinsConnection
#defineUSE_SD_CARD
#defineSD_CS 4//SDcardselectpin
#defineTFT_DC9
```

```
//ImageInitalization..
#ifdefined(USE_SD_CARD)
                       //SDcardfilesystem
 SdFat
               SD;
Adafruit_ImageReaderreader(SD);//Image-readerobject, passinSDfilesys
#else
 //SPIor QSPIflashfilesystem(i.e. CIRCUITPYdrive)
#ifdefined( SAMD51 )||
  defined(NRF52840_XXAA)Adafruit_FlashTransport_QSPIflash
  Transport(PIN_QSPI_SCK,
PIN_QSPI_CS,
   PIN_QSPI_IO0,PIN_QSPI_IO1, PIN_QSPI_IO2,PIN_QSPI_IO3);
 #else
  #if (SPI_INTERFACES_COUNT== 1)
   Adafruit_FlashTransport_SPIflashTransport(SS,&SPI);
  #else
   Adafruit_FlashTransport_SPIflashTransport(SS1, &SPI1);
  #endif
```

#defineTFT_CS10

#defineRESET 8

```
#endif
 Adafruit_SPIFlash
                   flash(&flashTransport);F
 atFileSystem
                   filesys;
Adafruit_ImageReaderreader(filesys);//Image-reader,passin flash filesys
#endif
Adafruit_ILI9341tft= Adafruit_ILI9341(TFT_CS, TFT_DC,RESET);
Adafruit_Image
                   img;
              //AnimageloadedintoRAMint32_t
               width=0,//BMPimagedimensions
            height=0;
//VariablesString
Weather;intTem
perature;
intDisplay_Speed;int
Traffic_Data;
intConstruction_Data;int
Service_Data;
```

//Functions

```
voidnormal_signs();void
speed(intTemp);
voidtraffic_warning(inttdata);
voidconstruction_warning(intcdata);vo
idservice_warning(intsdata);
//InitialSetupvoid
setup() {
ImageReturnCodestat;t
ft.begin();Serial.begin(
9600);tft.setRotation(1)
 tft.setTextColor(ILI9341_WHITE);
}
//Normalsignswithwordings
//Weather --Speedchange
//Traffic
//Construction
//School, HospitalWarnings
```

```
voidloop()
 {tft.setTextSize(3);tft.setCurs
 or(0,0);
 tft.print("DriveSafe:)");
 //InitialMesaage..tft.setCursor(0,30);
 tft.print("SpeedLimit:60");delay(1000
 );
 /*NormalSignsDisplay*/normal_sign
 s();
 /*TemperatureforSpeedControlusingrandominput*/
 //Temperature = 20;
 Temperature = random(-10,35);//(-10)to10--Snow, 11to25--
 Rainyspeed(Temperature);
 Serial.println(Temperature);
```

```
/*TrafficDatausing randominput*/
//Traffic_Data =0;Traffic_Data
=
random(0,2);traffic_warning(Tr
affic_Data);Serial.println(Traffi
c_Data);
/*ConstructionDatausingrandominput*/
//Construction_Data
=1;Construction_Data=
random (0,\!2); construction\_warning (Constru
ction_Data);Serial.println(Construction_Dat
a);
/*ServiceWarningDatausingrandominput*/
//Service_Data
=1;Service_Data =
```

random(0,2);

```
service_warning(Service_Data);Serial.printl
 n(Service_Data);
}
/*NormalSignsImageDisplaywithwordingsfor
awareness*/voidnormal_signs()
{
 stat= reader.drawBMP("/wokwi.bmp",tft, 0,
 0);reader.printStatus(stat);
}
/*SpeedControl process..
*/voidspeed(intTemp)
 tft.fillScreen(Black);
 if( Temp>=-10&&Temp<=14)//It's Snow
  Weather
  ="Snowy";tft.setCursor(0,0);tf
  t.print("DriveSafe:)");tft.setTe
  xtSize(2);
```

```
tft.setCursor(0,40);tft.print("G
 oslow..!");tft.setCursor(0,100);
 tft.setTextSize(3);tft.print("Sp
 eedLimit:30");delay(3000);tft.
 fillScreen(Black);
}
elseif(Temp>=15&&Temp<=25)//It'sRainy
 Weather =
 "Rainy";tft.setCursor(0,0);tft.prin
 t("DriveSafe:)");tft.setTextSize(2
 );tft.setCursor(0,40);tft.print("Sli
 pperyRoadAhead");tft.setCursor(
 0,70);
 tft.print("GoSlow..!");tft.setCu
 rsor(0,100);tft.setTextSize(3);t
 ft.print("SpeedLimit:40");
```

```
delay(3000);tft.fillScr
  een(Black);
 else
  tft.setCursor(0,0);tft.print("Dr
  iveSafe!!");tft.setCursor(0,30)
  ;tft.print("SpeedLimit:60");del
  ay(3000);tft.fillScreen(Black);
 tft.fillScreen(Black);
/*TrafficWarningSystem*/
voidtraffic_warning(inttdata)
{
 tft.fillScreen(Black);
```

```
if (tdata ==0)
{
 tft.setCursor(0,0);tft.print("Dri
 veSafe:)");
 //tft.setTextSize(2);tft.setCurs
 or(0,40);tft.print("TrafficAhea
 d..");tft.setCursor(0,80);
 //tft.setTextSize(3);tft.print("D
 riveCarefully!");delay(3000);tf
 t.fillScreen(Black);
}
if (tdata == 1)
{
 tft.setCursor(0,0);tft.print("Dri
 veSafe:)");tft.setTextSize(2);tf
 t.setCursor(0,40);tft.print("Tra
 fficAhead..");tft.setCursor(0,8
 0);
```

```
//tft.setTextSize(3);tft.print("Tak
  eDiversion--
  >");delay(3000);tft.fillScreen(Bl
  ack);
/*ConstructionWarningSystem*/
voidconstruction_warning(intcdata)
 tft.fillScreen(Black);i
 f (cdata ==0)
  tft.setCursor(0,0);tft.print("Drive
  Safe:)");tft.setTextSize(2);tft.set
  Cursor(0,40);tft.print("Constructi
  onAhead..");tft.setCursor(0,80);
```

```
tft.setTextSize(3);tft.print("Dr
 iveCarefully..!");delay(2000);t
 ft.fillScreen(Black);
}
if (cdata == 1)
 tft.setCursor(0,0);tft.print("Drive
 Safe:)");tft.setTextSize(2.5);tft.se
 tCursor(0,40);tft.print("Construct
 ionAhead..");tft.setCursor(0,80);t
 ft.setTextSize(2.5);tft.print("Tak
 eDiversion<--
 ");delay(2000);tft.fillScreen(Blac
 k);
```

```
/*School, HospitalWarningSystem*/
voidservice_warning(intsdata)
 tft.fillScreen(Black);i
 f (sdata == 0)
 {
  tft.setCursor(0,0);tft.print("Dr
  iveSafe:)");tft.setTextSize(2);t
  ft.setCursor(0,40);tft.print("Sc
  hoolAhead..");tft.setCursor(0,
  80);tft.setTextSize(3);
  tft.print("DriveCarefully.!\nNoHorn!"); dela
  y(2000);
  tft.fillScreen(Black);
 if (sdata == 1)
```

tft.setCursor(0,0);

```
tft.print("DriveSafe:)");tft.setTextSi
ze(2.5);tft.setCursor(0,40);tft.print("
HospitalAhead..");tft.setCursor(0,80
);tft.setTextSize(2.5);
tft.print("DriveCarefully.!\nNoHorn!");dela
y(2000);
tft.fillScreen(Black);
}
```

Node—RedDashboard(Flow)Link-<u>https://node-red-dsb.eu-gb.mybluemix.net/red/#flow/c8f5c2e4125f08cb</u>

Node–RedDashboard(UI)Link-<u>https://node-red-dsb.eu-gb.mybluemix.net/ui/#!/0?socketid=fsJfHymZb0JMNE0bAAA</u>

Node—RedDashboard(Webpage)Link-<u>https://node-red-dsb.eu-gb.mybluemix.net/simple</u>

GitHubProjectLink-https://github.com/IBM-EPBL/IBM-Project-43785-1660719573

VideoDriveLink-

https://drive.google.com/drive/folders/1KnLe_wOO9nI6Aw2jG RKzIU6zvHhYKSt3?usp=sharing