## Source Code

```
#include<LiquidCrystal.h>
#include <Servo.h>
LiquidCrystal lcd(9, 8, 5, 4, 3, 2);
Servo servo_7;
Servo servo_6;
Servo servo 1;
const int buzzer = 10; //buzzer to arduino pin 10
void setup()
  lcd.begin(16,2);
 pinMode(buzzer, OUTPUT); // Set buzzer - pin 10 as an output
 pinMode(11, OUTPUT);
 pinMode(12, OUTPUT);
 pinMode(13, OUTPUT);
 servo_7.attach(7);
 servo_6.attach(6);
 servo_1.attach(1);
}
void loop()
  servo_7.write(0);
 servo_6.write(0);
  servo_1.write(0);
  lcd.setCursor(0,0);
  lcd.print("Medicine");
  lcd.setCursor(2,1);
  lcd.print("Reminder");
 delay(200);
 lcd.clear();
 delay(400); //
  lcd.print("NextCycle = 8AM");
 delay(500); // Wait for 500 millisecond(s)
    lcd.clear();
  // FIRST CYCLE
  digitalWrite(13, HIGH); //Green Light On
```

```
lcd.setCursor(0,0);
lcd.print("8:00 AM");
lcd.setCursor(2,1);
lcd.print("MORNING MED");
servo_7.write(90);
servo_6.write(0);
servo 1.write(0);
tone (buzzer, 500); // Send 1KHz sound signal...
delay(400);
noTone(buzzer);  // Stop sound...
delay(200);
tone(buzzer, 500); // Send 1KHz sound signal...
delay(300);
noTone(buzzer);  // Stop sound...
digitalWrite(13, LOW); //Green Light Off
lcd.clear();
servo 7.write(0);
servo_6.write(0);
servo_1.write(0);
lcd.print("NextCycle = 3PM");
delay(500); // Wait for 500 millisecond(s)
lcd.clear();
// SECOND CYCLE
digitalWrite(12, HIGH); //Blue Light On
lcd.setCursor(0,0);
lcd.print("3:00 PM");
lcd.setCursor(2,1);
lcd.print("AFTERNOON MED");
servo 7.write(0); //TEST
servo 6.write(90);
servo_1.write(0);
tone(buzzer, 500); // Send 1KHz sound signal...
delay(300);
noTone(buzzer);  // Stop sound...
delay(200);
tone(buzzer, 500); // Send 1KHz sound signal...
delay(400);
noTone(buzzer);  // Stop sound...
```

```
digitalWrite(12, LOW); //Blue Light Off
lcd.clear();
servo_7.write(0);
servo_6.write(0);
servo_1.write(0);
lcd.print("NextCycle = 10PM");
delay(1000);
lcd.clear();
// THIRD CYCLE
digitalWrite(11, HIGH); //Red Light On
lcd.setCursor(0,0);
lcd.print("10:00 PM");
lcd.setCursor(2,1);
lcd.print("NIGHT MED");
servo_7.write(0); //TEST
servo_6.write(0);
servo_1.write(90);
tone(buzzer, 500); // Send 1KHz sound signal...
//delay(1000);
                    //
noTone(buzzer);  // Stop sound...
delay(200);
                //
tone(buzzer, 500); // Send 1KHz sound signal..
delay(300);
noTone(buzzer);  // Stop sound...
digitalWrite(11, LOW); //Red Light Off
lcd.clear();
servo_7.write(0);
servo_6.write(0);
servo_1.write(0);
delay(200);
```

}