## V.S.B. ENGINEERING COLLEGE, KARUR

## **Department of Electronics and Communication Engineering**

**TITLE**: Signs with smart connectivity for better

**Road Safety** 

**DOMAIN NAME**: Internet of Things

NAME : Pragadeeshwaran K

**MENTOR NAME**: Sivalingam T

## **Coding:**

```
#include<Servo.h>
int us = 6;
int servo = 7;

Servo servo1;

void setup() {
    Serial.begin(9600);
    servo1.attach(servo);
    pinMode(2,INPUT);
    pinMode(4,OUTPUT);
    pinMode(11,OUTPUT);
    pinMode(12,OUTPUT);
    pinMode(13,OUTPUT);
    pinMode(A0,INPUT);
```

```
digitalWrite(2,LOW);
 digitalWrite(11,HIGH);
}
void loop() {
 long duration, inches, cm;
 pinMode(us, OUTPUT);
 digitalWrite(us, LOW);
 delayMicroseconds(2);
 digitalWrite(us, HIGH);
 delayMicroseconds(5);
 digitalWrite(us, LOW);
 pinMode(us, INPUT);
 duration = pulseIn(us, HIGH);
 inches = microsecondsToInches(duration);
 cm = microsecondsToCentimeters(duration);
 servo1.write(0);
 if(cm < 30)
  servo1.write(120);
```

```
Serial.println("A Person Arrived, Door is Opening.....");
 delay(2000);
}
else
{
 servo1.write(0);
 Serial.println("Door is Closed.....");
}
int pir = digitalRead(2);
if(pir == HIGH)
 digitalWrite(4,HIGH);
 delay(3000);
}
else if(pir == LOW)
 digitalWrite(4,LOW);
}
float value=analogRead(A0);
float temp=(((value/1024)*5.0199)-0.5)*100;
Serial.print("temp is ");
Serial.println(temp);
delay(3000);
if(temp > 20)
```

```
digitalWrite(12,HIGH);
  digitalWrite(13,LOW);
}
else
{
  digitalWrite(12,LOW);
  digitalWrite(13,LOW);
}
long microsecondsToInches(long microseconds) {
  return microseconds / 74 / 2;
}
long microsecondsToCentimeters(long microseconds) {
  return microseconds / 29 / 2;
}
```

