

## Assignment 4: Ultra sonic sensor

### Wokwi Link :

<https://wokwi.com/projects/346229697892319828>

### Program:

```
#include <WiFi.h>
#include <WiFiClient.h>
#include <PubSubClient.h>

const char* ssid = "Wokwi-GUEST";
const char* password = "";

#define ORG "4fvvguz"
#define DEVICE_TYPE "ESP32"
#define DEVICE_ID "ultrasonic_sensor"
#define TOKEN "12345678"

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char pubTopic[] = "iot-2/evt/status1/fmt/json";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;

WiFiClient wifiClient;
PubSubClient client(server, 1883, NULL, wifiClient);

#define ECHO_PIN 13
#define TRIG_PIN 12
#define LED_BUILTIN 5
#define DHT_PIN 15

void setup()
{
  Serial.begin(115200);
  pinMode(LED_BUILTIN, OUTPUT);
```

```

pinMode(TRIG_PIN, OUTPUT);
pinMode(ECHO_PIN, INPUT);

Serial.print("Connecting to ");
Serial.print(ssid);
WiFi.begin(ssid, password);
while (WiFi.status() != WL_CONNECTED)
{
    delay(500);
    Serial.print(".");
}
Serial.println("");

Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());

if (!client.connected())
{
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!client.connect(clientId, authMethod, token))
    {
        Serial.print(".");
        delay(500);
    }
    Serial.println("Bluemix connected");
}
}

float readDistanceCM() {
    digitalWrite(TRIG_PIN, LOW);
    delayMicroseconds(2);
    digitalWrite(TRIG_PIN, HIGH);
    delayMicroseconds(10);
    digitalWrite(TRIG_PIN, LOW);
    int duration = pulseIn(ECHO_PIN, HIGH);
    return duration * 0.034 / 2;
}

void loop() {
    float distance = readDistanceCM();

    bool isNearby = distance < 100;
    digitalWrite(LED_BUILTIN, isNearby);
}

```

```
Serial.print("Measured distance: ");
Serial.println(readDistanceCM());

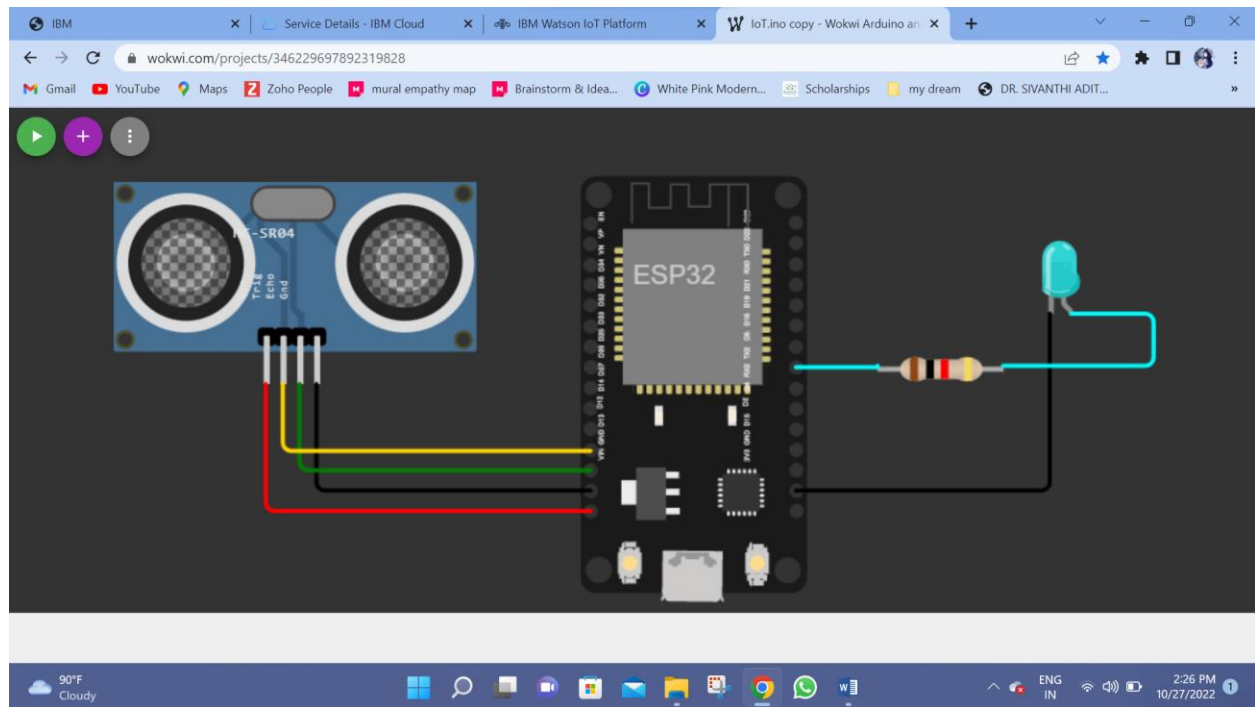
if(distance<100)
{
    String payload = "{\"d\":{\"Name\":\" DEVICE_ID \"\"";
    payload += "\",\"Distance\":";
    payload += distance;
    payload += "\"}"}";

    Serial.print("Sending value: ");
    Serial.println(payload);

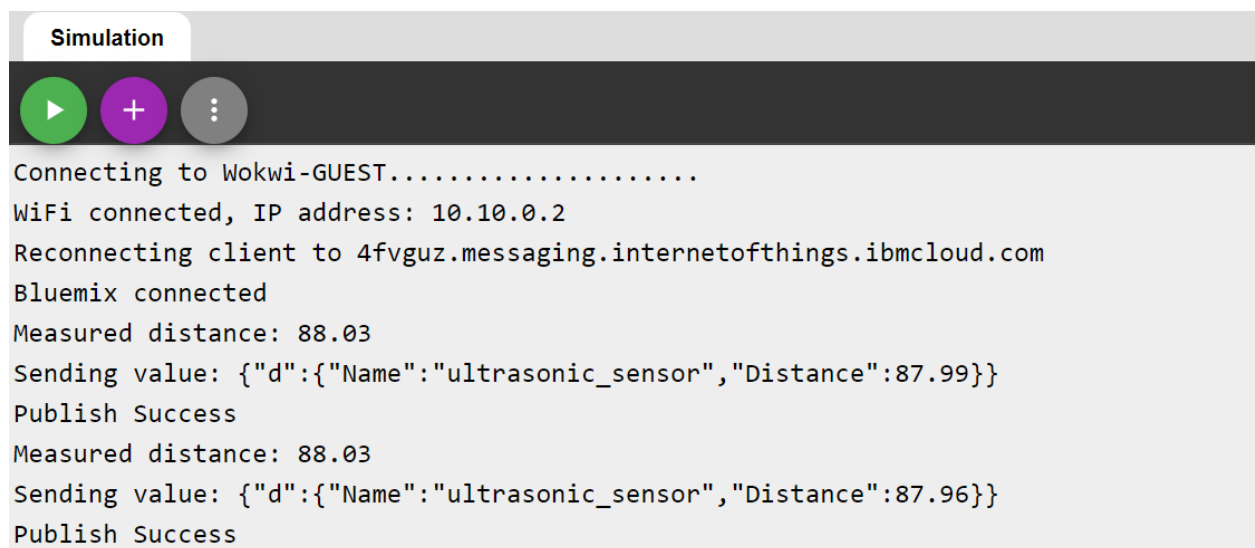
    if (client.publish(pubTopic, (char*) payload.c_str()))
    {
        Serial.println("Publish Success");
    }
    else
    {
        Serial.println("Publish Failed");
    }
}

delay(100);
}
```

## Connections:



## Output:



The screenshot displays the IBM Watson IoT Platform interface. At the top, the browser address bar shows the URL `4fvqz.internetofthings.ibmcloud.com/dashboard/devices/browse`. The page header includes the IBM Watson IoT Platform logo and user information: `11191022@drsacoe.com` and `ID: 4fvqz`. The left sidebar contains navigation icons for various functions. The main content area is titled 'Browse' and shows a list of devices. The selected device is 'ultrasonic\_sensor', which is 'Connected' and uses an 'ESP32' module. The 'Recent Events' tab is active, displaying a table of events. The table has four columns: 'Event', 'Value', 'Format', and 'Last Received'. The events show a status1 with a distance value of 87 in JSON format, received a few seconds ago. A '0 Simulations running' notification is visible at the bottom.

| Event   | Value  | Format | Last Received     |
|---------|--|--------|-------------------|
| status1 | {"d":{"Name":"ultrasonic_sensor","Distance":87.... | json   | a few seconds ago |
| status1 | {"d":{"Name":"ultrasonic_sensor","Distance":87.... | json   | a few seconds ago |
| status1 | {"d":{"Name":"ultrasonic_sensor","Distance":87.... | json   | a few seconds ago |
| status1 | {"d":{"Name":"ultrasonic_sensor","Distance":87.... | json   | a few seconds ago |
| status1 | {"d":{"Name":"ultrasonic_sensor","Distance":87.... | json   | a few seconds ago |

0 Simulations running