

## Assignment 4

```
#include <WiFi.h>
#include <WiFiClient.h>
#include <PubSubClient.h>

const char* ssid = "Wokwi-GUEST";
const char* password = "";

#define ORG "****"
#define DEVICE_TYPE "****"
#define DEVICE_ID "****"
#define TOKEN "****"

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char pubTopic[] = "iot-2/event_1/status1/fmt/json";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;

WiFiClient wifiClient;
PubSubClient client(server, 1883, NULL, wifiClient);

#define ECHO_PIN 13
#define TRIG_PIN 12
#define LED_BUILTIN 5
#define DHT_PIN 15

void setup()
{
    Serial.begin(115200);
    pinMode(LED_BUILTIN, OUTPUT);
    pinMode(TRIG_PIN, OUTPUT);
    pinMode(ECHO_PIN, INPUT);

    Serial.print("Connecting to ");
    Serial.print(ssid);
    WiFi.begin(ssid, password);
    while (WiFi.status() != WL_CONNECTED)
    {
        delay(500);
        Serial.print(".");
    }
    Serial.println("");
}
```

```

Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());

if (!client.connected())
{
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!client.connect(clientId, authMethod, token))
    {
        Serial.print(".");
        delay(500);
    }
    Serial.println("Bluemix connected");
}
}

float readDistanceCM() {
    digitalWrite(TRIG_PIN, LOW);
    delayMicroseconds(2);
    digitalWrite(TRIG_PIN, HIGH);
    delayMicroseconds(10);
    digitalWrite(TRIG_PIN, LOW);
    int duration = pulseIn(ECHO_PIN, HIGH);
    return duration * 0.034 / 2;
}

void loop() {
    float distance = readDistanceCM();

    bool isNearby = distance < 100;
    digitalWrite(LED_BUILTIN, isNearby);

    Serial.print("Measured distance: ");
    Serial.println(readDistanceCM());

    if(distance<100)
    {
        String payload = "{\"d\":{\"Name\":\"" DEVICE_ID "\"";
        payload += "\",\"Distance\":";
        payload += distance;
        payload += "\"}"}";

        Serial.print("Sending value: ");
        Serial.println(payload);
    }
}

```

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    if (client.publish(pubTopic, (char*) payload.c_str()))
    {
        Serial.println("Publish Success");
    }
    else
    {
        Serial.println("Publish Failed");
    }
}

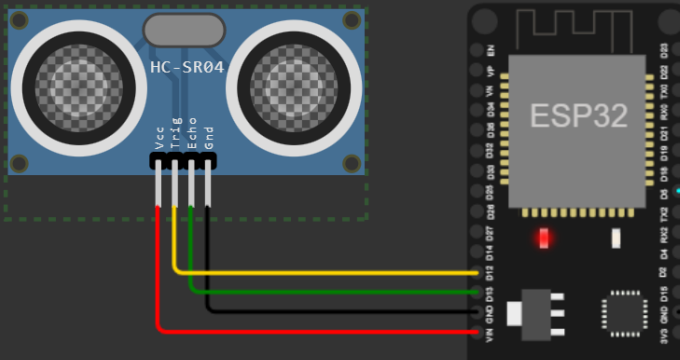
delay(100);
}

```

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Editing Ultrasonic Distance Sensor

Distance: 67cm



Publish Success

Measured distance: 66.98

Sending value: {"d":{"Name":"ultrasonic\_sensor","Distance":66.98}}

Publish Success

Measured distance: 66.98

Sending value: {"d":{"Name":"ultrasonic\_sensor","Distance":66.98}}

Publish Success

Event	Value	Format	Last Received
status1	{"d":{"Name":"ultrasonic_sensor","Distance":56....	json	a few seconds ago
status1	{"d":{"Name":"ultrasonic_sensor","Distance":56....	json	a few seconds ago
status1	{"d":{"Name":"ultrasonic_sensor","Distance":56....	json	a few seconds ago
status1	{"d":{"Name":"ultrasonic_sensor","Distance":56....	json	a few seconds ago
status1	{"d":{"Name":"ultrasonic_sensor","Distance":56....	json	a few seconds ago