ASSIGNMENT-4

Team ID	IBM-EPBL/IBM-Project-
	33561-1660222837
Name	Selva Murugan P

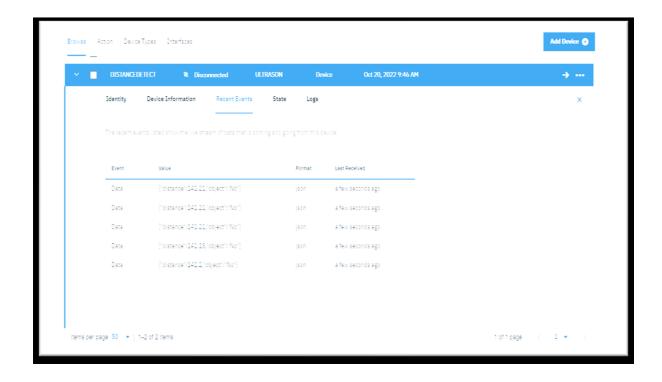
Question1:

Write code and connections in work for ultrasonic sensor. Whenever distance is less than 100cms send "alert" to the IBM cloud and display in device recent events.

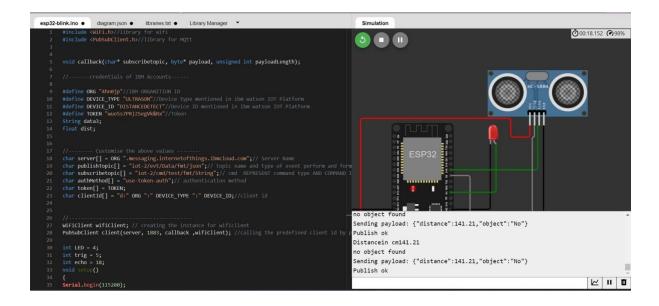
```
esp32-blink.ino
                 diagram.json •
                                  libraries.txt ●
                                                 Library Manager
      pinMode(trig,OUTPUT);
      pinMode(echo, INPUT);
      pinMode(LED, OUTPUT);
      delay(10);
      wificonnect();
      mqttconnect();
      void loop()// Recursive Function
       digitalWrite(trig,LOW);
        digitalWrite(trig,HIGH);
        delayMicroseconds(10);
        digitalWrite(trig,LOW);
        float dur = pulseIn(echo,HIGH);
        float dist = (dur * 0.0343)/2;
        Serial.print ("Distancein cm");
        Serial.println(dist);
        PublishData(dist);
        delay(1000);
        if (!client.loop()) {
          mqttconnect();
      void PublishData(float dist) {
        mqttconnect();//function call for connecting to ibm
```

```
esp32-blink.ino
                  diagram.json •
                                  libraries txt .
                                                 Library Manager
        WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
        while (WiFi.status() != WL CONNECTED) {
          delay(500);
          Serial.print(".");
        Serial.println("");
        Serial.println("WiFi connected");
        Serial.println("IP address: ");
        Serial.println(WiFi.localIP());
      void initManagedDevice() {
        if (client.subscribe(subscribetopic)) {
          Serial.println((subscribetopic));
          Serial.println("subscribe to cmd OK");
          Serial.println("subscribe to cmd FAILED");
      void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
        Serial.print("callback invoked for topic: ");
        Serial.println(subscribetopic);
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        for (int i = 0; i < payloadLength; i++) {</pre>
          data3 += (char)payload[i];
```

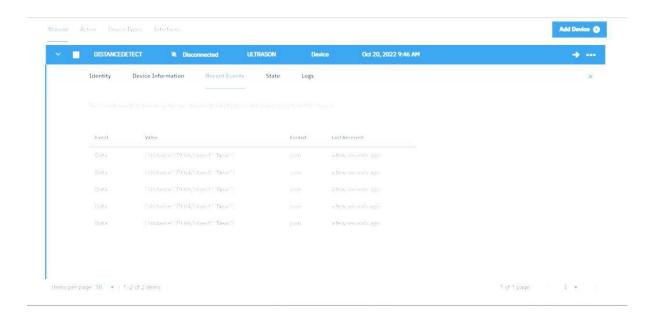
OUTPUT:



Data send to the IBM cloud device when the object is far



Data sent to the IBM Cloud Device when the object is near



When object is near to the ultrasonic sensor

