## Project Development - Delivery Of Sprint-4

```
import board
import digitalio
LED PIN = board.D13
PIR_PIN = board.D2
pir = digitalio.Digital InOut(PIR_PIN)
pir.direction = digitalio.Direction.INPUT
led = digitalio.Digital InOut(LED_PIN)
led.direction = digitalio.Direction.OUTPUT
old_value = pir.value
while True:
  pir_value = pir.value
  if pir_value:
     led.value = True
     if not old value:
       print('Motion detected!')
  else:
     led.value = False
     if old_value:
       print('Motion ended!')
  old_value = pir_value
```