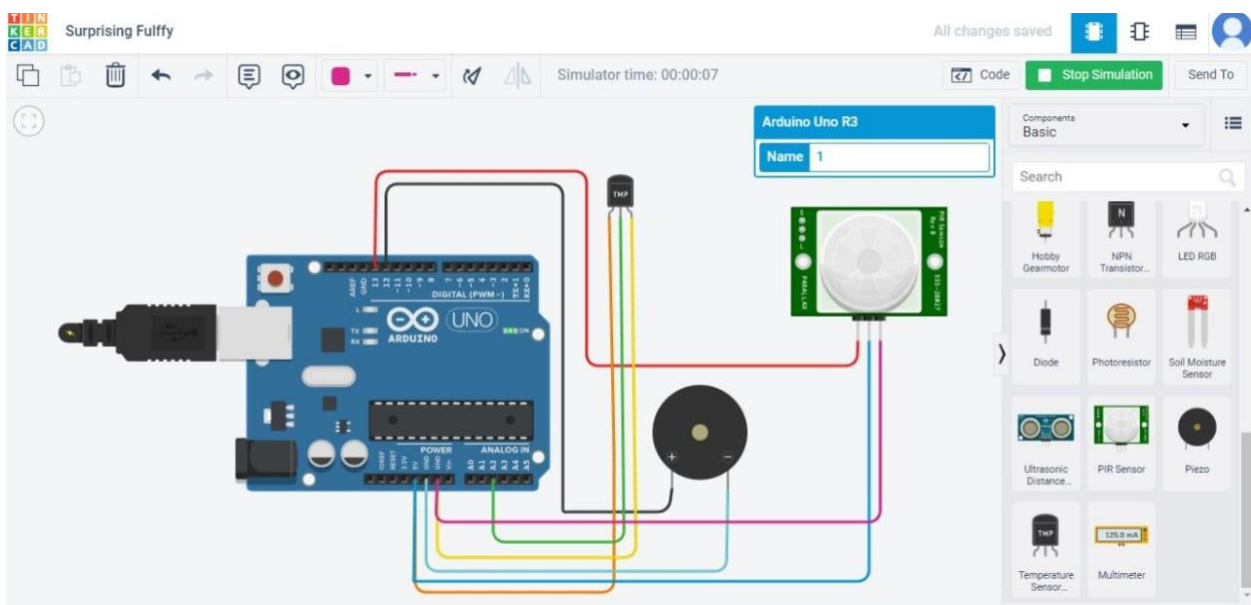
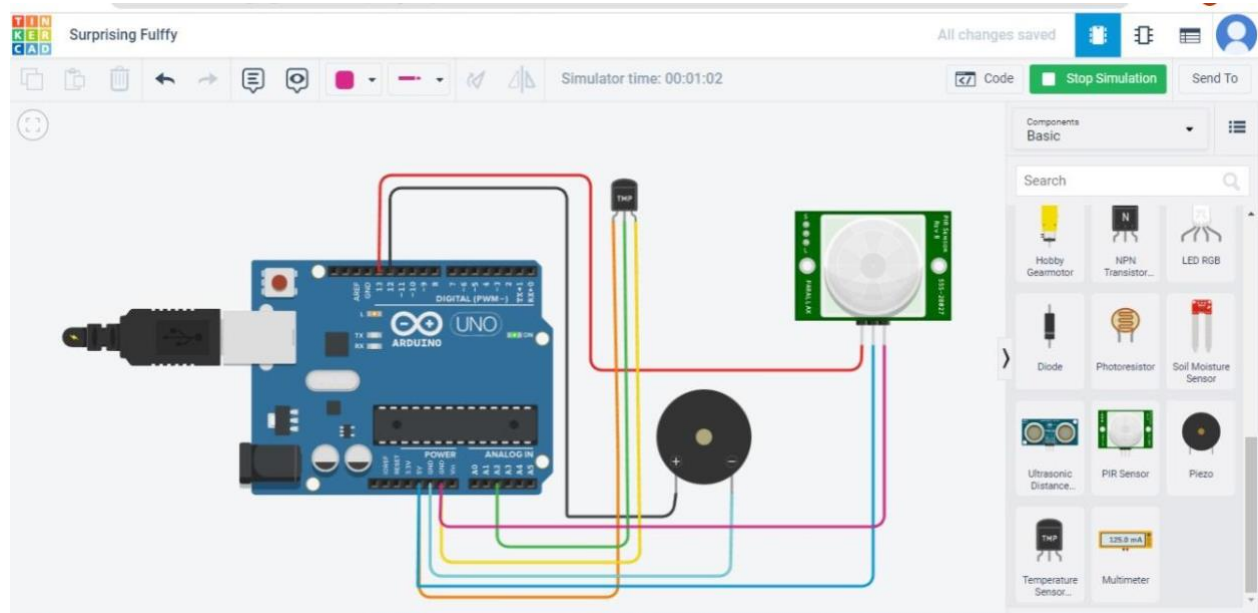


ASSIGNMENT1

SOWMIYA.B , ECE C, 111519106151



Surprising Fulffy

All changes saved

Code Start Simulation Send To

Arduino Uno R3

Name 1

Blocks + Text

Output Control Input Math Notation Variables

on start

set built-in LED to HIGH

set pin 0 to HIGH

set pin 3 to 0

rotate servo on pin 0 to 0 degree

Serial Monitor

```

1 // C++ code
2 //
3 void setup()
4 {
5   pinMode(LED_BUILTIN, OUTPUT);
6 }
7
8 void loop()
9 {
10  digitalWrite(LED_BUILTIN, HIGH);
11  delay(1000); // Wait for 1000 millisecond(s)
12  digitalWrite(LED_BUILTIN, LOW);
13  delay(1000); // Wait for 1000 millisecond(s)
14 }

```

void setup() { Serial.begin(9600); pinMode(13,INPUT); pinMode(12,OUTPUT); } void loop() { double data=analogRead(A2); double n=

Send Clear

Surprising Fulffy

All changes saved

Code Start Simulation Send To

Arduino Uno R3

Name 1

Blocks + Text

Output Control Input Math Notation Variables

on start

set built-in LED to HIGH

set pin 0 to HIGH

set pin 3 to 0

rotate servo on pin 0 to 0 degree

Serial Monitor

```

1 // C++ code
2 //
3 void setup()
4 {
5   pinMode(LED_BUILTIN, OUTPUT);
6 }
7
8 void loop()
9 {
10  digitalWrite(LED_BUILTIN, HIGH);
11  delay(1000); // Wait for 1000 millisecond(s)
12  digitalWrite(LED_BUILTIN, LOW);
13  delay(1000); // Wait for 1000 millisecond(s)
14 }

```

void setup() { Serial.begin(9600); pinMode(13,INPUT); pinMode(12,OUTPUT); } void loop() { double data=analogRead(A2); double n=

Send Clear