ASSIGNMENT 4

Date	**October 2022**
Team ID	**PNT2022TMID38325**
Project Name	**Smart Solution for Railways**

QUESTION :

Write code and connection in wowki for ultrasonic sensor. Whenever distance is less than 100 cms send “alert” to IBM cloud and display in device recent events

CODE :

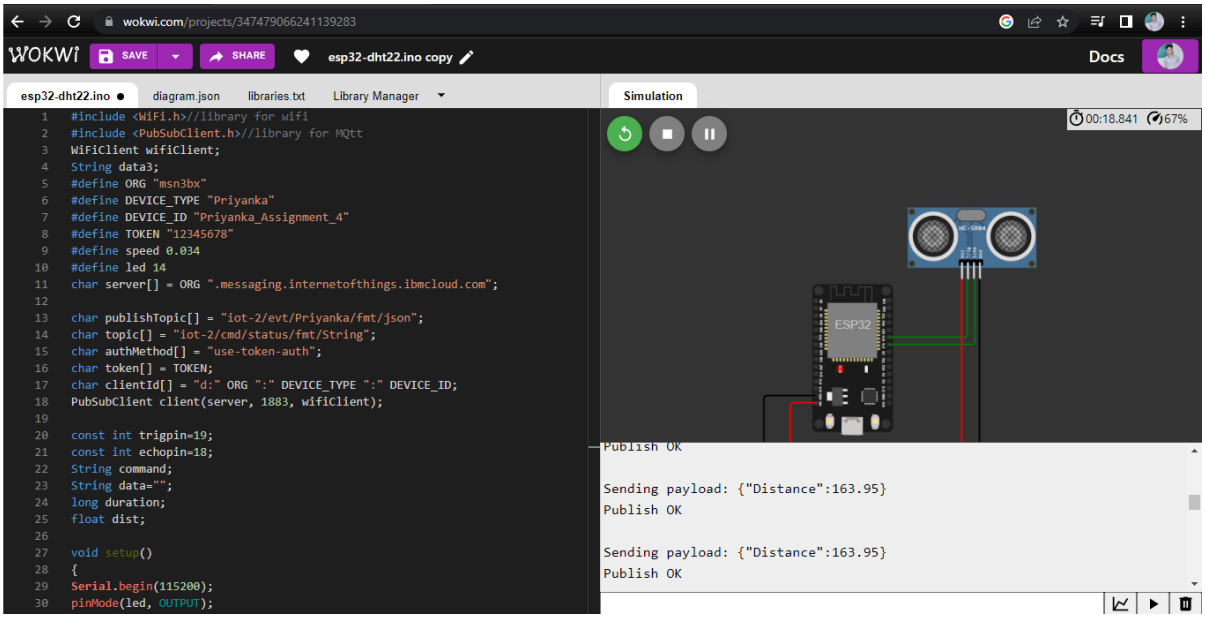
```
#include <WiFi.h>//library for wifi
#include <PubSubClient.h>//library for MQtt
WiFiClient wifiClient;
String data3;
#define ORG "msn3bx"
#define DEVICE_TYPE "Priyanka"
#define DEVICE_ID "Priyanka_Assignment_4"
#define TOKEN "12345678"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";

char publishTopic[] = "iot-2/evt/Priyanka/fmt/json";
char topic[] = "iot-2/cmd/status/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);

const int trigpin=19;
const int echopin=18;
String command;
String data="";
long duration;
float dist;

void setup()
```

```
{
Serial.begin(115200);
pinMode(led, OUTPUT);
pinMode(trigpin, OUTPUT);
pinMode(echopin, INPUT);
wifiConnect();
mqttConnect();
}
void loop()
{

bool isNearby = dist < 100;
digitalWrite(led, isNearby);
publishData();
delay(500);
if (!client.loop())
{
mqttConnect();
}
}
void wifiConnect()
{
Serial.print("Connecting to "); Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED)
{
delay(500);
Serial.print(".");
}
Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect()
{
if (!client.connected())
{
Serial.print("Reconnecting MQTT client to "); Serial.println(server);
while (!client.connect(clientId, authMethod, token))
{

Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}
void initManagedDevice() {
if (client.subscribe(topic))
```

```
{
// Serial.println(client.subscribe(topic));
Serial.println("IBM subscribe to cmd OK");
}
else
{
Serial.println("subscribe to cmd FAILED");
}
}
void publishData()
{
digitalWrite(trigpin,LOW);
digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100)
{
String payload = "{\"Alert Distance\":";
payload += dist;

payload += "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if (client.publish(publishTopic, (char*) payload.c_str()))
{
Serial.println("Publish OK");
}
}
if(dist>100){
String payload = "{\"Distance\":";
payload += dist;
payload += "}";
Serial.print("\n");
Serial.print("Sending payload: ");
Serial.println(payload);
if(client.publish(publishTopic, (char*) payload.c_str()))
{
Serial.println("Publish OK");
}
else
{
Serial.println("Publish FAILED");
}
}
}
```

OUTPUT :

1) When Distance greater than 100 cm



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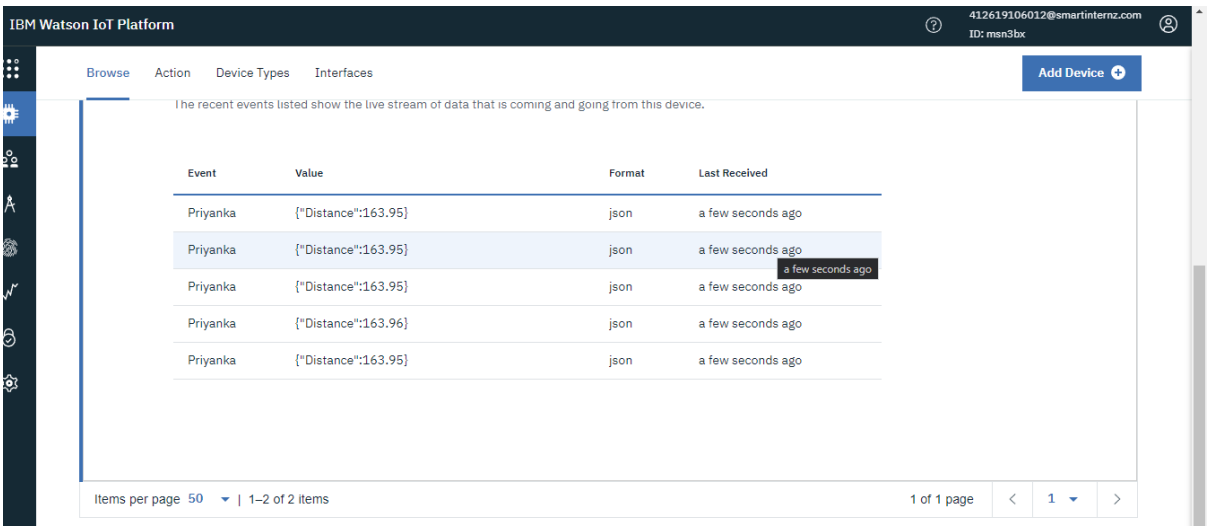
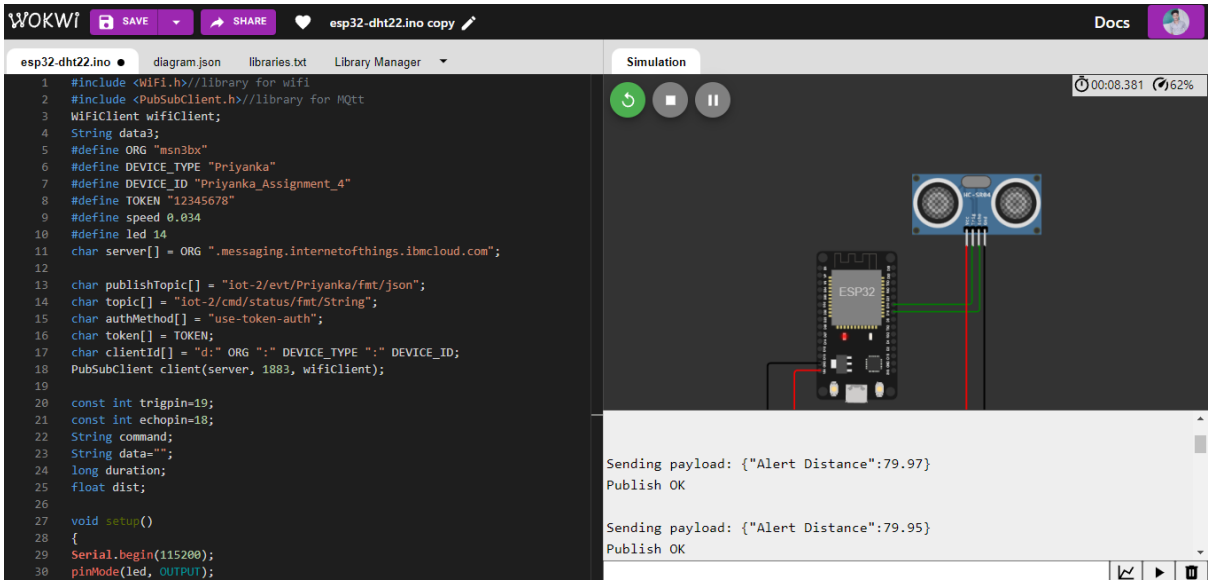


2) When distance less than 100



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