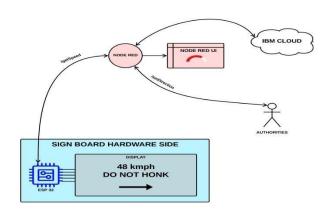
Date	16 November 2022
Team Id	PNT2022TMID09925
Project Name	Project - Signs with smart connectivity for Better road safety

Signs with smart connectivity for Better road safety

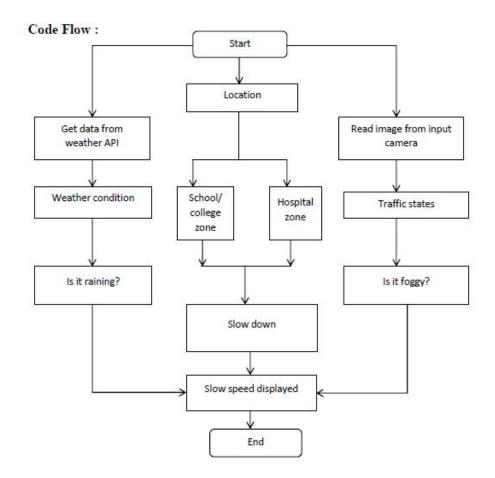
Sprint Goals:

1. Hardware & Cloud integration

Process Flow:

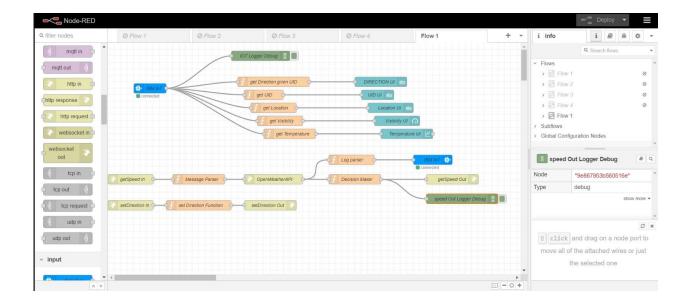


Code Flow:



Node RED:

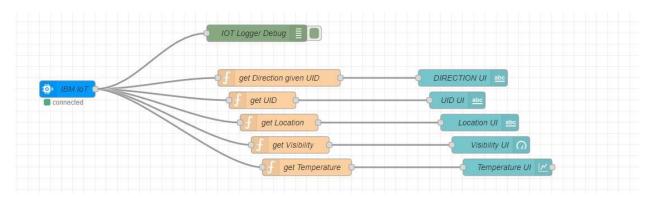
Node RED flow:



There are 3 flows in the above Node RED flow. They are

- 1. Node RED UI flow
- 2./getSpeed API flow 3. /setDirection API flow 1.

Node RED UI flow:



- 1. "IBM IOT" node connects the backend to Node RED UI
- 2. The function nodes such as "get Direction given UID", "get UID", "get Location", "get Visibility" & "get Temperature" extract the respective data out and provides them to the UI nodes "Direction UI", "UID UI", "Location UI", "Visibility UI" & "Temperature UI".

```
// get Direction given UID
msg.payload = global.get(String(msg.payload.uid));
return msg;
```

```
// get UID
msg.payload = msg.payload.uid; return
msg;

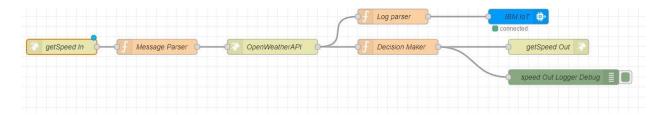
// get Location
msg.payload = msg.payload.location; return
msg;

// get Visibility
msg.payload = msg.payload.visibility; return
msg;

// get Temperature
msg.payload = msg.payload.temperature; return
msg;
```

3. "IOT Logger Debug" node logs the data at debugger.

2./getSpeed API flow:



- 1. "getSpeed In" node is an http end point. It accepts parameters like microcontroller UID, location, school & hospital zones info.
- 2. "Message Parser" node parses the data and passes on only required information to the next node

```
global.set("data",msg.payload);
msg.payload.q = msg.payload.location;
msg.payload.appid = "9cd610e5fd400c74212074c7ace0d62c";
return msg;
```

- 3. "OpenWeatherAPI" node is a http request node which calls the OpenWeather API and send the data to the next node.
- 4. "Log Parser" node extracts specific parameters from the weather data and and sends it to the next node.

```
weatherObj = JSON.parse(JSON.stringify(msg.payload));
localityObj = global.get("data");
```

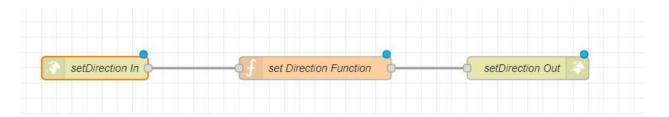
- 5. "**IBM IoT**" node here (IBM IoT OUT)connects the "**IBM IoT**" node (IBM IoT IN) metioned in the **Node RED UI flow** which enables UI updation and logging.
- 6. "Decision Maker" node processes the weather data and other information from the micro controller to form the string that is to be displayed at the Sign Board

```
weatherObj = JSON.parse(JSON.stringify(msg.payload));
localityObj = global.get("data");
var suggestedSpeedPercentage = 100;
var preciseObject = {
    temperature : weatherObj.main.temp - 273.15,
    weather : weatherObj.weather.map(x=>x.id).filter(code => code<700),</pre>
visibility : weatherObj.visibility/100
if(preciseObject.visibility<=40)</pre>
suggestedSpeedPercentage -=30
     switch(String(preciseObject.weather)[-1]) //
https://openweathermap.org/weatherconditions refer weather codes meaning here
    case "0" : suggestedSpeedPercentage -=10;break;
case "1" : suggestedSpeedPercentage -=20;break;
"2" : suggestedSpeedPercentage -=30;break;
msg.payload = preciseObject;
var doNotHonk = 0;
if(localityObj.hospitalZone=="1"||localityObj.schoolZone=="1")
doNotHonk = 1;
var returnObject = {
    suggestedSpeed : localityObj.usualSpeedLimit*(suggestedSpeedPercentage/100),
doNotHonk : doNotHonk
msg.payload = String(returnObject.suggestedSpeed) + " kmph \n\n" +
```

```
(returnObject.doNotHonk==1?"Do Not Honk":"") + "$" +
global.get(String(localityObj.uid));
  return
msg;
```

- 7. "getSpeed Out" node returns a http response for the request at node "getSpeed In".
- 8. "speed Out Logger Debug" logs the data for debugging.

3. /setDirection API flow:



- 1. "setDirection In" node is an http end point. It accepts parameters like microcontroller UID & direction.
- 2. "set Direction Function" node sets the direction for the given UID.

```
global.set(String(msg.payload.uid),msg.payload.dir);
return msg;
```

3. "setDirection Out" node returns a http response for the request at node "setDirection In".

Click on this link to change direction to Straight:

https://node-red-rvfut-2022-11-14.au-syd.mybluemix.net/setDirection?uid=2504&dir=s Click

on this link to change direction to Left:

https://node-red-rvfut-2022-11-14.au-syd.mybluemix.net/setDirection?uid=2504&dir=l Click on this link to change direction to Right: https://node-red-rvfut-2022-11-14.au-

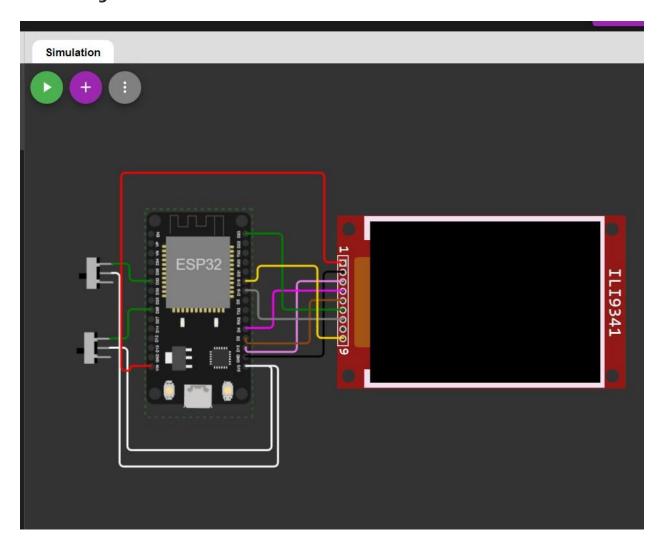
syd.mybluemix.net/setDirection?uid=2504&dir=r

Wokwi Circuit:

Wokwi Code Wokwi Link

https://wokwi.com/projects/348420917875966547

Circuit Diagram:



ESP 32 CODE:

#include <WiFi.h>

#include <HTTPClient.h>

#include <Adafruit_GFX.h>

#include <Adafruit_ILI9341.h>

```
#include <string.h>
const char* ssid = "Wokwi-GUEST"; const
char* password = "";
#define TFT_DC 2
#define TFT_CS 15
Adafruit_ILI9341 tft = Adafruit_ILI9341(TFT_CS, TFT_DC);
String myLocation = "Chennai,IN";
String usualSpeedLimit = "70"; // kmph
int schoolZone = 32; int
hospitalZone = 26;
int uid = 2504;
String getString(char x)
{
  String s(1, x);
return s;
}
```

```
String stringSplitter1(String fullString,char delimiter='$')
{
  String returnString = ""; for(int i =
0; i<fullString.length();i++) {
                                    char c
= fullString[i];
                    if(delimiter==c)
break;
            returnString+=String(c);
  }
  return(returnString);
}
String stringSplitter2(String fullString,char delimiter='$')
{
  String returnString = "";
bool flag = false;
  for(int i = 0; i<fullString.length();i++) {</pre>
char c = fullString[i];
                           if(flag)
returnString+=String(c);
if(delimiter==c)
                         flag = true;
  }
  return(returnString);
```

```
}
void rightArrow()
{
 int refX = 50; int refY =
tft.getCursorY() + 40;
 tft.fillRect(refX,refY,100,20,ILI9341_RED); tft.fillTriangle(refX+100,refY-
30,refX+100,refY+50,refX+40+100,refY+10,ILI9341_RED);
}
void leftArrow()
{
 int refX = 50;
 int refY = tft.getCursorY() + 40;
 tft.fillRect(refX+40,refY,100,20,ILI9341_RED); tft.fillTriangle(refX+40,refY-
30,refX+40,refY+50,refX,refY+10,ILI9341_RED);
}
void upArrow()
{
```

```
int refX = 125; int refY =
tft.getCursorY() + 30;
 tft.fillTriangle(refX-40,refY+40,refX+40,refY+40,refX,refY,ILI9341_RED); tft.fillRect(refX-
15,refY+40,30,20,ILI9341_RED);
}
String APICall() {
 HTTPClient http;
 String url = "https://node-red-nwmrt-2022-11-04.eu-gb.mybluemix.net/getSpeed?";
url += "location="+myLocation+"&"; url +=
"schoolZone="+(String)digitalRead(schoolZone)+(String)"&"; url +=
"hospitalZone="+(String)digitalRead(hospitalZone)+(String)"&";
 url += "usualSpeedLimit="+(String)usualSpeedLimit+(String)"&";
url += "uid="+(String)uid; http.begin(url.c_str()); int
httpResponseCode = http.GET();
 if (httpResponseCode>0) {
String payload = http.getString();
http.end(); return(payload);
```

```
}
else {
  Serial.print("Error code: ");
  Serial.println(httpResponseCode);
 }
 http.end();
}
void myPrint(String contents) {
tft.fillScreen(ILI9341_BLACK);
tft.setCursor(0, 20); tft.setTextSize(4);
tft.setTextColor(ILI9341_RED);
//tft.println(contents);
 tft.println(stringSplitter1(contents));
String c2 = stringSplitter2(contents);
if(c2=="s") // represents Straight
 {
  upArrow();
 }
 if(c2=="l") // represents left
```

```
{
  leftArrow();
 }
 if(c2=="r") // represents right
 {
  rightArrow();
 }
}
void setup() {
 WiFi.begin(ssid, password, 6);
 tft.begin();
 tft.setRotation(1);
 tft.setTextColor(ILI9341_WHITE);
tft.setTextSize(2); tft.print("Connecting
to WiFi");
 while (WiFi.status() != WL_CONNECTED) {
delay(100); tft.print(".");
 }
```

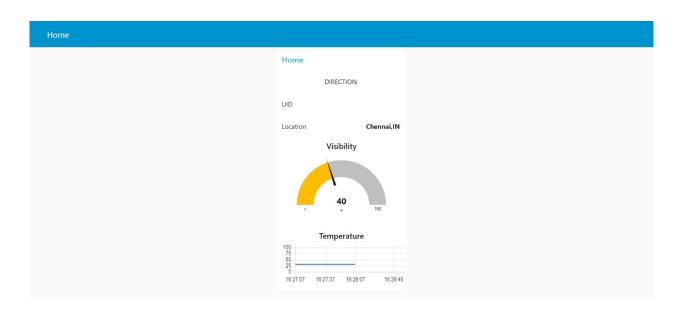
```
tft.print("\nOK! IP=");
tft.println(WiFi.localIP());
}

void loop() {
    myPrint(APICall());
    delay(100);
}
```

Output:

Node RED Dashboard:

LINK TO NODE RED DASHBOARD



Wokwi Output:

LINK TO WOKWI PROJECT

OUTPUT1

