

## Assignment – 4

<b>Date</b>	19 November 2022
<b>Team ID</b>	PNT2022TMID18648
<b>Project Name</b>	IoT Based Smart Crop Protection System for Agriculture
<b>Maximum Marks</b>	4 Marks

### PROGRAM :

```
// ARDUINO PINS (TRIGGER PIN, ECHO PIN)
const int TRIG_PIN = 7;
const int ECHO_PIN = 8;

// Anything over 400 cm (23200 us pulse) is "out of range"
const unsigned int max_dist = 23200;

void setup() {

    // The Trigger pin will tell the sensor to range find
    pinMode(TRIG_PIN, OUTPUT);
    digitalWrite(TRIG_PIN, LOW);

    //Set Echo pin as input to measure the time duration of pulse returning back from the distance sensor
    pinMode(ECHO_PIN, INPUT);

    // We'll use the serial monitor to view the sensor output
    Serial.begin(9600);
```

```
}
```

```
void loop() {
```

```
    unsigned long t1;  
    unsigned long t2;  
    unsigned long pulse_width;  
    float cm;  
    float inches;
```

```
    // Hold the trigger pin high for at least 10 us
```

```
    digitalWrite(TRIG_PIN, HIGH);
```

```
    delayMicroseconds(10);
```

```
    digitalWrite(TRIG_PIN, LOW);
```

```
    // Wait for pulse on echo pin
```

```
    while ( digitalRead(ECHO_PIN) == 0 );
```

```
    // Measure how long the echo pin was held high (pulse width)
```

```
    // Note: the micros() counter will overflow after ~70 min
```

```
    t1 = micros();
```

```
    while ( digitalRead(ECHO_PIN) == 1);
```

```
    t2 = micros();
```

```
    pulse_width = t2 - t1;
```

```
    // Calculate distance in centimeters and inches. The constants
```

```
    // are found in the datasheet, and calculated from the assumed speed
```

```
    //of sound in air at sea level (~340 m/s).
```

```
    cm = pulse_width / 58.0;
```

```
    inches = pulse_width / 148.0;
```

```
    // Print out results
```

```
if ( pulse_width > max_dist ) {  
    Serial.println("Out of range");  
} else {  
    Serial.println("*****");  
    Serial.print("Distance Measured in cm : ");  
    Serial.println(cm);  
  
    if(cm<100){  
        // while(true){  
        Serial.println("Alert !!");  
        // }  
    }  
  
    Serial.print("*****");  
}  
  
// Wait at least 1000ms before next measurement  
delay(1000);  
}
```

OUTPUT :

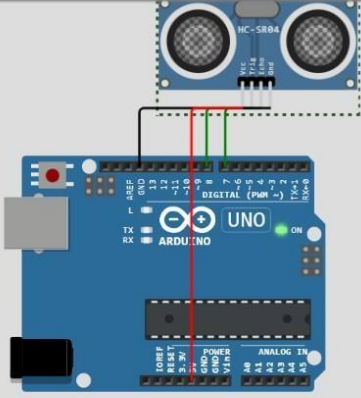
WOKWI SAVE SHARE Docs SIGN IN

sketch.ino • diagram.json • Library Manager

```
1
2
3
4
5 // ARDUINO PINS (TRIGGER PIN, ECHO PIN)
6 const int TRIG_PIN = 7;
7 const int ECHO_PIN = 8;
8
9 // Anything over 400 cm (23200 us pulse) is "out of range"
10 const unsigned int max_dist = 23200;
11
12 void setup() {
13
14     // The Trigger pin will tell the sensor to range find
15     pinMode(TRIG_PIN, OUTPUT);
16     digitalWrite(TRIG_PIN, LOW);
17
18     //Set Echo pin as input to measure the time duration of pulse returning back from the d
19     pinMode(ECHO_PIN, INPUT);
20
21     // We'll use the serial monitor to view the sensor output
22     Serial.begin(9600);
23 }
24
25 void loop() {
26
27     unsigned long t1;
28     unsigned long t2;
29     unsigned long pulse_width;
30     float cm;
31     float inches;
32
33     // Hold the trigger pin high for at least 10 us
34     digitalWrite(TRIG_PIN, HIGH);
```

Simulation 01:27.258 99%

Editing Ultrasonic Distance Sensor  
Distance: 2cm



Distance Measured in cm : 2.07  
Alert !!

Distance Measured in cm : 2.00  
Alert !!

sketch.ino

diagram.json

Library Manager

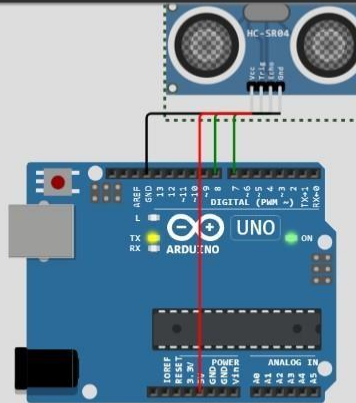
```
1
2
3
4
5 // ARDUINO PINS (TRIGGER PIN, ECHO PIN)
6 const int TRIG_PIN = 7;
7 const int ECHO_PIN = 8;
8
9 // Anything over 400 cm (23200 us pulse) is "out of range"
10 const unsigned int max_dist = 23200;
11
12 void setup() {
13
14     // The Trigger pin will tell the sensor to range find
15     pinMode(TRIG_PIN, OUTPUT);
16     digitalWrite(TRIG_PIN, LOW);
17
18     //Set Echo pin as input to measure the time duration of pulse returning back from the d
19     pinMode(ECHO_PIN, INPUT);
20
21     // We'll use the serial monitor to view the sensor output
22     Serial.begin(9600);
23 }
24
25 void loop() {
26
27     unsigned long t1;
28     unsigned long t2;
29     unsigned long pulse_width;
30     float cm;
31     float inches;
32
33     // Hold the trigger pin high for at least 10 us
34     digitalWrite(TRIG_PIN, HIGH);
```

Simulation

00:47.106 100%

Editing Ultrasonic Distance Sensor

Distance: 268cm



Distance Measured in cm : 271.79

Distance Measured in cm : 271.72

Distance Measured in cm : 271.72

Distance Measured in cm : 271.79