

Smart waste management for metropolitan cities

Assignment-4

Write a code and connections in workwi for ultrasonic sensors

Program:

```
#include <WiFi.h>
#include <PubSubClient.h>

WiFiClient wifiClient;

String data3;

#define ORG "4yi0vc"
#define DEVICE_TYPE "nodeMcu"
#define DEVICE_ID "Assignment4"
#define TOKEN "123456789"
#define speed 0.034
#define led 14

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);

void publishData();

const int trigpin=5;
const int echopin=18;
```

```
String command;
```

```
String data="";
```

```
long duration;
```

```
float dist;
```

```
void setup()
```

```
{
```

```
    Serial.begin(115200);
```

```
    pinMode(led, OUTPUT);
```

```
    pinMode(trigpin, OUTPUT);
```

```
    pinMode(echopin, INPUT);
```

```
    wifiConnect();
```

```
    mqttConnect();
```

```
}
```

```
void loop() {
```

```
    bool isNearby = dist < 100;
```

```
    digitalWrite(led, isNearby);
```

```
    publishData();
```

```
    delay(500);
```

```
    if (!client.loop()) {
```

```
        mqttConnect();
```

```
    }
```

```
}
```

```
void wifiConnect() {
```

```
    Serial.print("Connecting to "); Serial.print("Wifi");
```

```

WiFi.begin("Wokwi-GUEST", "", 6);

while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
}

Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}

void mqttConnect() {
    if (!client.connected()) {
        Serial.print("Reconnecting MQTT client to "); Serial.println(server);
        while (!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }
        initManagedDevice();
        Serial.println();
    }
}

void initManagedDevice() {
    if (client.subscribe(topic)) {
        // Serial.println(client.subscribe(topic));
        Serial.println("IBM subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void publishData()
{
    digitalWrite(trigpin, LOW);

```

```

digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
duration=pulseIn(echopin,HIGH);
dist=duration*speed/2;
if(dist<100){
    String payload = "{\"Normal Distance\":";
    payload += dist;
    payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Publish OK");
    }
}

if(dist>101 && dist<111){
    String payload = "{\"Alert distance\":";
    payload += dist;
    payload += "}";

    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if(client.publish(publishTopic, (char*) payload.c_str())) {
        Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
        digitalWrite(led,HIGH);
    }else {
        Serial.println("Publish FAILED");
    }
}

```

```
}

}

}

void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
  Serial.print("callback invoked for topic:");
  Serial.println(subscribeTopic);
  for(int i=0; i<payloadLength; i++){
    dist += (char)payload[i];
  }
  Serial.println("data:" + data3);
  if(data3=="lighton"){
    Serial.println(data3);
    digitalWrite(led,HIGH);
  }
  data3="";
}
```