Project Development phase

Date	09 November 2022
Team ID	PNT2022TMID41308
Project Name	Project – SMART WASTE MANAGEMENT FOR
	METROPOLITAN CITIES
Maximum Marks	4 Marks

Delivering of Sprint-3

IBM Cloud service

- Python code for sending location(latitude,longitude)along with the bin status
- Sending the data to the IBM watson

Python code test code:

import time

import sys

import ibmiotf.application

import ibmiotf.device

import random

from geopy.geocoders import Nominatim

```
# initialize Nominatim API
```

geolocator = Nominatim(user_agent="geoapiExercises")

#Provide your IBM Watson Device Credentials

organization = "pb6xw8"

deviceType = "efgh"

deviceId = "1234"

authMethod = "token"

```
authToken = "12345678"
try:
      deviceOptions = {"org": organization, "type": deviceType, "id": deviceId,
"auth-method": authMethod, "auth-token": authToken}
      deviceCli = ibmiotf.device.Client(deviceOptions)
      #.....
except Exception as e:
      print("Caught exception connecting device: %s" % str(e))
      sys.exit()
# Connect and send a datapoint "hello" with value "world" into the cloud as an
event of type "greeting" 10 times
print("checking connection to waston iot...")
deviceCli.connect()
time.sleep(1)
while True:
    name='bin'
    level=random.randint(1,100)
    weight=random.randint(1,100)
    latitude=random.uniform(12.867342,13.043514)
    longitude=random.uniform(77.477635,77.695109)
    Latitude=str(latitude)
    Longitude=str(longitude)
    location = geolocator.reverse(Latitude+","+Longitude)
```

```
address = location.raw['address']
city = address.get('city', '')
print('City:', str(city))
#STATUS OF GARBAGE CAN
if(level<30):
    level_status="low level"
    print("level_status=low level garbage")
elif(level>30)and(level<80):
    level status="medium level garbage"
    print("level_status=low level garbage")
else:
    level_status="high level garbage"
    print("level_status=high level garbage")
if (weight<30):
    weight_status="low level"
    print("weight_status=low level garbage")
elif(weight>30)and(weight<80):
    weight_status="medium level garbage"
    print("weight status=low level garbage")
else:
    weight_status="high level garbage"
    print("weight status=high level garbage")
```

```
data = { 'name' : name, 'level' : level, 'level_status':level_status, 'weight':
    weight, 'weight_status':weight_status, 'lat': Latitude, 'lon':Longitude, 'city':str(city)}
#print data

def myOnPublishCallback():
    print ("Published weight = %s kg" % weight, "level=%s m" %level, "latitude = %s %%" % latitude, "longitude = %s %%" % longitude, "city=%s" %city, "to IBM Watson")

success = deviceCli.publishEvent("project", "json", data, qos=0, on_publish=myOnPublishCallback)
    if not success:
        print("Not connection lost from sensor to ibm iot")
        time.sleep(10)
# Disconnect the device and application from the cloud
deviceCli.disconnect()
```

