

SMART HOME:

```
1  #include <Servo.h>
2
3  int output1Value = 0;
4  int sen1Value = 0;
5  int sen2Value = 0;
6  int const gas_sensor = A1;
7  int const LDR = A0;
8  int limit = 400;
9
10 long readUltrasonicDistance(int triggerPin, int echoPin)
11 {
12   pinMode(triggerPin, OUTPUT);
13   digitalWrite(triggerPin, LOW);
14   delayMicroseconds(2);
15
16   digitalWrite(triggerPin, HIGH);
17   delayMicroseconds(10);
18   digitalWrite(triggerPin, LOW);
19   pinMode(echoPin, INPUT);
20
21   return pulseIn(echoPin, HIGH);
22 }
23
24 Servo servo_7;
25
26 void setup()
27 {
28   Serial.begin(9600);
29   pinMode(A0, INPUT);
30   pinMode(A1, INPUT);
31   pinMode(13, OUTPUT);
32   servo_7.attach(7, 500, 2500);
33
34   pinMode(8, OUTPUT);
35   pinMode(9, INPUT);
36   pinMode(10, OUTPUT);
37   pinMode(4, OUTPUT);
38   pinMode(3, OUTPUT);
39
40 }
```

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```
41
42 void loop()
43 {
44     int val1 = analogRead(LDR);
45     if (val1 > 500)
46     {
47         digitalWrite(13, LOW);
48         Serial.print("Bulb ON = ");
49         Serial.print(val1);
50     }
51     else
52     {
53         digitalWrite(13, HIGH);
54         Serial.print("Bulb OFF = ");
55         Serial.print(val1);
56     }
57
58     sen2Value = digitalRead(9);
59     if (sen2Value == 0)
60     {
61         digitalWrite(10, LOW);
62         digitalWrite(4, HIGH);
63         digitalWrite(3, LOW);
64         Serial.print(" || NO Motion Detected ");
65     }
66
67     if (sen2Value == 1)
68     {
69         digitalWrite(10, HIGH);
70         delay(5000);
71         digitalWrite(4, LOW);
72         digitalWrite(3, HIGH);
73         Serial.print(" || Motion Detected! ");
74     }
75
76     int val = analogRead(gas_sensor);
77     Serial.print("|| Gas Sensor Value = ");
78     Serial.print(val);
79     //val = map(val, 300, 750, 0, 100);
80     if (val > limit)
```

SMART HOME:

```
81 {
82  tone(8, 650);
83 }
84  delay(300);
85  noTone(8);
86
87  sen1Value = 0.01723 * readUltrasonicDistance(6, 6);
88
89  if (sen1Value < 100)
90  {
91    servo_7.write(90);
92    Serial.print(" || Door Open! ; Distance = ");
93    Serial.print(sen1Value);
94    Serial.print("\n");
95
96  }
97  else
98  {
99    servo_7.write(0);
100    Serial.print(" || Door Closed! ; Distance = ");
101    Serial.print(sen1Value);
102    Serial.print("\n");
103  }
104  delay(10);
105 }
```

TINKERCAD-LINK :

[SMART HOME-TINKERCAD LINK](#)

SMART HOME:

SMART HOME-IMAGE:

