## SMARTWASRE MANAGEMENT SYSTEM FOR METRO CITIES TEAM ID:PNT2022TMID48488 IBM-Project-35221-1660282887

```
output code:
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "vn6oc2"
#define DEVICE TYPE "vikash"
#define DEVICE ID "nodeMcu"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Gayathri/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE TYPE ":" DEVICE ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
 Serial.begin(115200);
 pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
  wifiConnect();
 mqttConnect();
}
void loop() {
  bool isNearby = dist < 100;</pre>
  digitalWrite(led, isNearby);
  publishData();
  delay(500);
  if (!client.loop()) {
   mqttConnect();
  }
}
```

```
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL CONNECTED) {
    delay(500);
    Serial.print(".");
                                            ΙP
                                                                      ");
  Serial.print("WiFi
                           connected,
                                                     address:
Serial.println(WiFi.localIP());
void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting
                                     MOTT
                                                client
                                                             to
                                                                      ");
Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    initManagedDevice();
    Serial.println();
  }
}
void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
}
void publishData()
 digitalWrite(trigpin,LOW);
  digitalWrite(trigpin, HIGH);
  delayMicroseconds (10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin, HIGH);
  dist=duration*speed/2;
  if(dist<100){
    String payload = "{\"Alert Distance\":";
    payload += dist;
   payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
      if(client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Warning crosses 110cm -- it automaticaly of the
loop");
      digitalWrite(led, HIGH);
    }
    if(dist>101 && dist<111){
    String payload = "{\"Normal Distance\":";
```

```
payload += dist;
    payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
   }
  }
  void callback(char* subscribeTopic, byte* payload, unsigned int
payloadLength) {
  Serial.print("callback invoked for topic:");
  Serial.println(subscribeTopic);
  for(int i=0; i<payloadLength; i++) {</pre>
   dist += (char)payload[i];
  Serial.println("data:"+ data3);
  if (data3=="lighton") {
   Serial.println(data3);
   digitalWrite(led, HIGH);
  data3="";
}
```





