

## Assignment -4

### Python Programming

Student Name	Anitha C
Student Roll Number	720319106002

#### Question-1:

#### Solution:

Link : <https://wokwi.com/projects/348011432680358484>

```
#include<WiFi.h>
#include<PubSubClient.h>
WiFiClient wifiClient;

#define trigpin    18
#define echopin    5

String data3;

#define ORG "gw3cs4"//IBM ORGANITION ID
#define DEVICE_TYPE "smart"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "123547"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "12345678"

#define speed 0.034
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();

String command;
String data="";
long duration;
```

```

float dist;

void setup()
{
    Serial.begin(115200);
    wifiConnect();
    pinMode(trigpin, OUTPUT);
    pinMode(echopin, INPUT);

    mqttConnect();
}

void wifiConnect() {
    Serial.print("Connecting to "); Serial.print("Wifi");
    WiFi.begin("Wokwi-GUEST", "", 6);
    while (WiFi.status() != WL_CONNECTED) {
        delay(500);
        Serial.print(".");
    }
    Serial.print("WiFi connected, IP address: ");
    Serial.println(WiFi.localIP());
}

void loop()
{
    int pulseWidth = 0;
    digitalWrite(trigpin, HIGH);
    delayMicroseconds(100);
    digitalWrite(trigpin, LOW);
    pulseWidth = pulseIn(echopin, HIGH);
    Serial.print("AlertDistance: ");
    Serial.println(pulseWidth/58);

    publishData();
    if(!client.loop()) {
        mqttConnect();
    }
}

void mqttConnect() {
    if(!client.connected()) {
        Serial.print("Reconnecting MQTT client to "); Serial.println(server);
        while(!client.connect(clientId, authMethod, token)) {
            Serial.print(".");
            delay(500);
        }
    }
}

```

```

    }
    initManagedDevice();
    Serial.println();
}
}

void initManagedDevice() {
    if (client.subscribe(topic)) {
        // Serial.println(client.subscribe(topic));
        Serial.println("IBM subscribe to cmd OK");
    } else {
        Serial.println("subscribe to cmd FAILED");
    }
}

void publishData()
{
    digitalWrite(trigpin, LOW);
    digitalWrite(trigpin, HIGH);
    delayMicroseconds(10);
    digitalWrite(trigpin, LOW);
    duration = pulseIn(echopin, HIGH);
    dist = duration * speed / 2;
    if (dist < 100) {
        String payload = "{\"Normal Distance\": ";
        payload += dist;
        payload += "}";

        Serial.print("\n");
        Serial.print("Sending payload: ");
        Serial.println(payload);
        if (client.publish(publishTopic, (char*) payload.c_str())) {
            Serial.println("Publish OK");
        }
    }

    if (dist > 101 && dist < 111) {
        String payload = "{\"Alert distance\": ";
        payload += dist;
        payload += "}";

        Serial.print("\n");
        Serial.print("Sending payload: ");
        Serial.println(payload);
        if (client.publish(publishTopic, (char*) payload.c_str())) {
            Serial.println("Warning crosses 110cm -- it automatically of the loop");
        }
    }
}

```

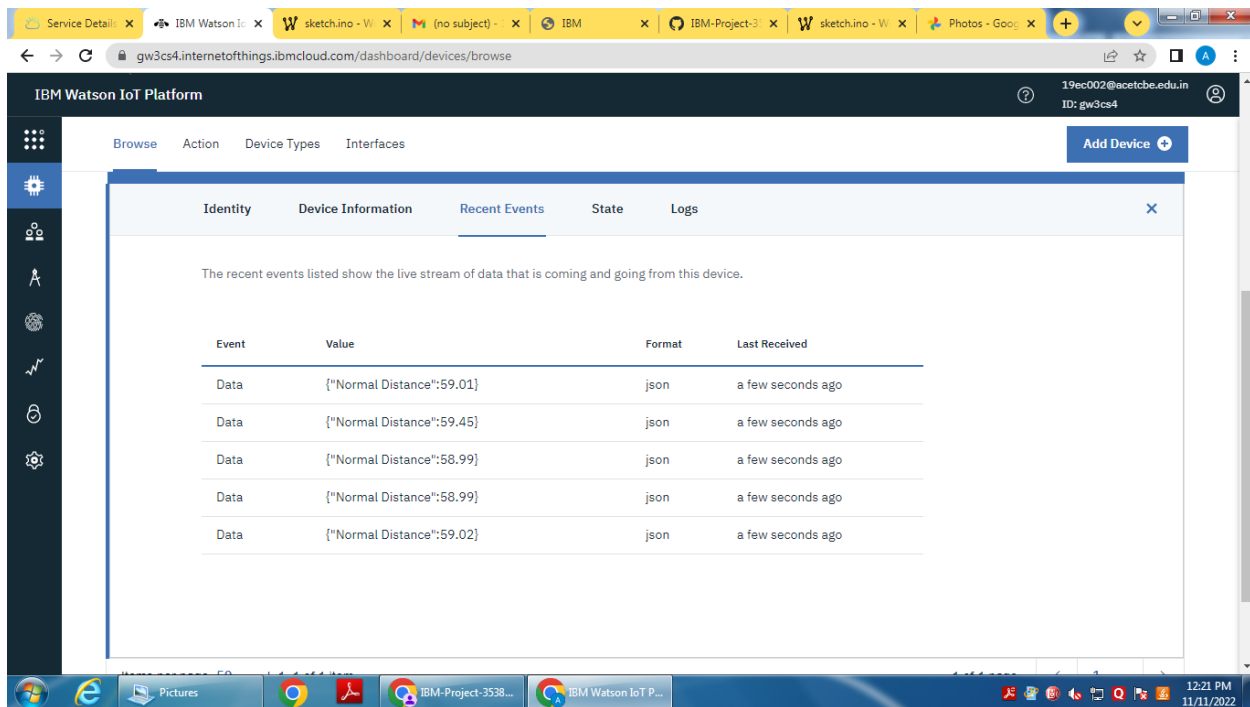
```

    }else {
        Serial.println("Publish FAILED");
    }
}

}

void callback(char* subscribeTopic, byte* payload, unsignedint payloadLength){
    Serial.print("callback invoked for topic:");
    Serial.println(subscribeTopic);
    for(int i=0; i<payloadLength; i++){
        dist += (char)payload[i];
    }
    Serial.println("data:"+ data3);
    if(data3=="lighton"){
        Serial.println(data3);
    }
    data3="";
}

```



Output : <https://gw3cs4.internetofthings.ibmcloud.com/dashboard/devices/browse>

