

FINAL CODE

TEAM ID	PNT2022TMID17040
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PROJECT NAME:	SIGNS WITH SMART CONNECTIVITY FOR BETTER ROAD SAFETY

```
#include <LiquidCrystal.h> #define BLYNK_PRINT Serial #include <ESP8266WiFi.h>
```

```
#include <BlynkSimpleEsp8266.h>
```

```
char auth[] "Y4DBRJfvaDUee9LMZHCWT7pd=VL01RGU";
```

```
// Your WiFi credentials. // Set password to " for open networks.
```

```
char said[] = "hellow";
```

```
char pass[] "12345678":
```

```
const int rs = D5, en = D6, d4 = D1, d5 = D2, d6 = D3, d7 = D4; LiquidCrystal lcd(rs, en, d4, d5, d6, d7);
```



```
int a=0;
```

```
BLYNK_WRITE(V2)
```

```
aparan.asInt();
```

```
void setup() { // set up the LCD's number of columns and rows: Serial.begin(9600);  
Blynk.begin(auth, ssid, pass); led.begin(16, 2);
```

```
void loop() {
```

```
Blynk.run();
```

```
lcd.setCursor(0, 1); if(a+1)
```

```
{
```

```
led.print ("accident occurred"); Serial.print("hi");
```

```
}
```

```
Else
```

```
{
```

```
Icd.print("welcome");
```

```
}
```

```
#define BLYNK_PRINT Serial
```

```
#include <ESP8266WiFi.h>
```



```
#include <BlynkSimpleEsp8266.h>
```

```
char auth[q6FAQIggdiHIxAPEa116]; char said[] "hellow":
```

```
char pass 12345678":
```

```
String stri
```

```
void setup() { Serial.begin(9600);
```

```
Blynk.begin(auth, said, pass);
```

```
void loop() {
```

```
Blynk.run();
```

```
if(Serial.available()>0)
```

```
str=Serial.readStringUntil('/');
```

```
}
```

```
// Serial.print(str); // Blynk.notify("location:");
```

```
Blynk.notify(str);
```

```
}
```



```
#include <TinyGPS++. #include <SoftwareSerial.b>
```

```
TinyGPSPlus : SeftvareSerial (3,4):
```

```
attachInterrupt (digitalPinToInterrupt (2), piezo, CHANCE);
```

```
}
```

```
void loop() { Derial.read();
```

```
// Serial.println(" ");
```

```
delay(200);
```

```
C
```

```
digitalWrite(e,HIGH); digitalWrite(11,HIGH); digitalWrite(12,HIGH); delay(200);  
digitalWrite(12,LOW);
```

```
else if(n-2)
```

```
digitalWrite(6,LOW);
```

```
digitalWrite(11,LOW); digitalWrite(10,LOW); digitalWrite(9,LOW);  
digitalWrite(12,HIGH);delay(200); digitalWrite(12,LOW);
```

```
else if (1)
```

```
analogWrite(11,100); analogWrite(6,100); digitalWrite(12,HIGH); delay(200):
```



```
digitalWrite(12,tov);
```

```
// while (az.available() > 0) // if (p.encode(as.read())) //displayinfo():
```

```
void displayInfo()
```

```
// Serial.print(F("Location: "));
```

```
Serial.print(gpe.location lat(), 63: Serial.print (FC", "
```

```
Serial.print(ps/location, Ing(), );
```

```
// Berial print (F("INVALID" }}}\
```

```
Serial.print(+10, 308125")
```

```
Serial.print(", Berial prias (7.3)
```

```
Serial.print(F(" Date/Time: ")); if (ps.date.isValid())
```

```
Serial.print(ps.date.outh());
```

```
Serial.print(F("/"));
```



```
Serial.print(ps.date.day()); Serial.print((
```

```
Serial.print(gps.date.year());
```

```
Serial.print(F(INVALID));
```

```
Serial.print(F()); if (gpe tine isValid())
```

```
if (gpe tine.bour() < 10) Serial.print(F(""));
```

```
Serial.print(gps.tine.bour());
```

```
}Serial.priss (F(":")); if (ga tine.minute() < 10) Serial.priet (F(**));
```

```
Serial.print(gps.tine.attute());
```

```
Serial.print(F(3):
```

```
if (gps.tise second() < 10) Serial.print(F("0"));
```

```
Serial.print(gps.tine.second()); Serial.print(F("."));
```

```
if (gpe.time.centisecond() < 10) Berial.print(F("0"));
```



```
Serial.print(gps.time.cantisecond());

// Serial.print (F(INVALID"));

Serial.println();

void piezo()

while (.available() > 0)

displayInfo();

void setup() (

pisode (D2, INPUT); plaude (03, 18PUT);

digitalrite,Lo

Ferial Begin(3600);

void loop(){

a-digitalRead(D1); if (a1)

Serial.print("1"); } bedigitalRead(D2);
```



```
if (b==1)
```

```
Serial.print("2");
```

```
d=digitalRead(D4); if (d=-1)
```

```
Serial.print("3");
```

```
}
```

