

Date	3 november 2022
Team ID	PNT2022TMID53515
Project Name	Project- <u>Signs with Smart Connectivity for Better Road Safety</u>
Maximum Marks	4 Marks

Final code:

```
#include <LiquidCrystal.h> #define BLYNK_PRINT Serial #include <ESP8266WiFi.h>
```

```
#include <BlynkSimpleEsp8266.h>
```

```
char auth[] "Y4DBRJfvaDUee9LMZHCWT7pd=VL01RGU";
```

```
// Your WiFi credentials. // Set password to " for open networks.
```

```
char said[]= "hellow";
```

```
char pass[]"12345678":
```

```
const int rs = D5, en D6, d4 D1, ds D2, d6 D3, d7 = D4; LiquidCrystal led(rs, en, d4, d5, d6, d7);
```



```
int a=0;
```

```
BLYNK_WRITE(V2)
```

```
aparan.asInt();
```

```
void setup() { // set up the LCD's number of columns and rows: Serial.begin(9600);  
Blynk.begin(auth, ssid, pass); led.begin(16, 2);
```

```
void loop() {
```

```
Blynk.run();
```

```
lcd.setCursor(0, 1); if(a+1)
```

```
{
```

```
led.print ("accident occurred"); Serial.print("hi");
```

```
}
```

```
Else
```

```
{
```

```
lcd.print("welcome");
```

```
}
```

```
#define BLYNK_PRINT Serial
```

```
#include <ESP8266WiFi.h>
```



```
#include <BlynkSimpleEsp8266.h>
```

```
char auth[q6FAQlggdiHlxAPEa116]; char said[]"hellow":
```

```
char pass 12345678":
```

```
String stri
```

```
void setup() { Serial.begin(9600);
```

```
Blynk.begin(auth, said, pass);
```

```
void loop() {
```

```
Blynk.run();
```

```
if(Serial.available()>0)
```

```
str=Serial.readStringUntil('/');
```

```
}
```

```
// Serial.print(str); // Blynk.notify("location:");
```

```
Blynk.notify(str);
```

```
}
```



```
#include <TinyGPS++.h> #include <SoftwareSerial.h>
```

```
TinyGPSPlus : SoftwareSerial (3,4):
```

```
attachInterrupt (digitalPinToInterrupt (2), piezo, CHANGE);
```

```
}
```

```
void loop() { Serial.read();
```

```
// Serial.println(" ");
```

```
delay(200);
```

```
C
```

```
digitalWrite(e,HIGH); digitalWrite(11,HIGH); digitalWrite(12,HIGH); delay(200);  
digitalWrite(12,LOW);
```

```
else if(n-2)
```

```
digitalWrite(6,LOW);
```

```
digitalWrite(11,LOW); digitalWrite(10,LOW); digitalWrite(9,LOW); digitalWrite(12,HIGH);  
delay(200); digitalWrite(12,LOW);
```

```
else if (1)
```

```
analogWrite(11,100); analogWrite(6,100); digitalWrite(12,HIGH); delay(200);
```



```
digitalWrite(12,tov);
```

```
// while (az.available() > 0) // if (p.encode(as.read())) //displayinfo():
```

```
void displayInfo()
```

```
// Serial.print(F("Location: "));
```

```
Serial.print(gpe.location lat(), 63: Serial.print (FC","
```

```
Serial.print(ps/location, lng(), );
```

```
// Berial print (F("INVALID"}}\
```

```
Serial.print(+10, 308125")
```

```
Serial.print(", Berial prias (7.3)
```

```
Serial.print(F(" Date/Time: ")); if (ps.date.isValid())
```

```
Serial.print(ps.date.outh());
```

```
Serial.print(F("/"));
```



```
Serial.print(ps.date.day()); Serial.print((
```

```
Serial.print(gps.date.year());
```

```
Serial.print(F(INVALID));
```

```
Serial.print(F()); if (gpe tine isValid())
```

```
if (gpe tine.bour() < 10) Serial.print(F(""));
```

```
Serial.print(gps.tine.bour());
```

```
}Serial.priss (F(":")); if (ga tine.minute() < 10) Serial.priet (F(**));
```

```
Serial.print(gps.tine.attute());
```

```
Serial.print(F(3):
```

```
if (gps.tise second() < 10) Serial.print(F("0"));
```

```
Serial.print(gps.tine.second()); Serial.print(F(". "));
```

```
if (gpe.time.centisecond() < 10) Berial.print(F("0"));
```



```
Serial.print(gps.time.centisecond());
```

```
// Serial.print (F(INVALID));
```

```
Serial.println();
```

```
void piezo()
```

```
while (.available() > 0)
```

```
displayInfo();
```

```
void setup() (
```

```
pinMode (D2, INPUT); pinMode (D3, OUTPUT);
```

```
digitalWrite,Lo
```

```
Serial.begin(3600);
```

```
void loop(){
```

```
a=digitalRead(D1); if (a1)
```

```
Serial.print("1"); } else digitalWrite(D2);
```



```
if (b==1)
```

```
Serial.print("2");
```

```
d=digitalRead(D4); if (d==1)
```

```
Serial.print("3");
```

```
}
```

