

Assignment - 4
Ultrasonic sensor simulation
In Wokwi

ASSIGNMENT DATE	29 OCTOBER 2022
TEAM ID	PNT2022TMID03698
PROJECT NAME	SMART SOLUTIONS FOR RAILWAYS
MAXIMUM MARKS	2 MARKS

Code:

```
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
//-----credentials of IBM Accounts-----
#define ORG "ytluse"
#define DEVICE_TYPE "2702"
#define DEVICE_ID "12345"
#define TOKEN "O+n)Eh+lNX0y3?rG!8" /
String data3;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, callback ,wifiClient);
const int trigPin = 5;
const int echoPin = 18;
#define SOUND_SPEED 0.034
long duration;
float distance;
void setup() {
  Serial.begin(115200);
  pinMode(trigPin, OUTPUT);
  pinMode(echoPin, INPUT);

  wificonnect();
  mqttconnect();
}
void loop()
{
  digitalWrite(trigPin, LOW);
  delayMicroseconds(2);
  digitalWrite(trigPin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigPin, LOW);
  duration = pulseIn(echoPin, HIGH);
  distance = duration * SOUND_SPEED/2;
```

```

Serial.print("Distance (cm): ");
Serial.println(distance);
if(distance<100)
{
Serial.println("ALERT!!");
delay(1000);
PublishData(distance);
delay(1000);
if (!client.loop()) {
mqttconnect();
}
}
delay(1000);
}
void PublishData(float dist) {
mqttconnect();
String payload = "{\"Distance\":";
payload += dist;
payload += ", \"ALERT!!\": \"\" \"Distance less than 100cms\"\"";
payload += "}";
Serial.print("Sending payload: ");
Serial.println(payload);

if (client.publish(publishTopic, (char*) payload.c_str())) {
Serial.println("Publish ok");
} else {
Serial.println("Publish failed");
}
}

void mqttconnect() {
if (!client.connected()) {
Serial.print("Reconnecting client to ");
Serial.println(server);
while (!client.connect(clientId, authMethod, token)) {
Serial.print(".");
delay(500);
}
initManagedDevice();
Serial.println();
}
}

void wificonnect()
{
Serial.println();
Serial.print("Connecting to ");
WiFi.begin("Wokwi-GUEST", "", 6);
while (WiFi.status() != WL_CONNECTED) {
delay(500);
Serial.print(".");
}
Serial.println("");
Serial.println("WiFi connected");
Serial.println("IP address: ");
Serial.println(WiFi.localIP());

```

```

}
void initManagedDevice() {
if (client.subscribe(subscribetopic)) {
Serial.println((subscribetopic));
Serial.println("subscribe to cmd OK");
} else {
Serial.println("subscribe to cmd FAILED");
}
}
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
Serial.print("callback invoked for topic: ");
Serial.println(subscribetopic);
for (int i = 0; i < payloadLength; i++) {
//Serial.print((char)payload[i]);
data3 += (char)payload[i];
}
Serial.println("data: "+ data3);
data3="";
}

```

Diagram.json:

```

{
  "version": 1,
  "author": "RENDLA SURESH KRISHNA REDDY",
  "editor": "wokwi",
  "parts": [
    { "type": "wokwi-esp32-devkit-v1", "id": "esp", "top": 6, "left": -66, "attrs": {} },
    { "type": "wokwi-hc-sr04", "id": "ultrasonic1", "top": 32.56, "left": 81.02, "attrs": {} }
  ],
  "connections": [
    ["esp:TX0", "$serialMonitor:RX", "", [] ],
    ["esp:RX0", "$serialMonitor:TX", "", [] ],
    ["esp:VIN", "ultrasonic1:VCC", "red", [ "h-31.67", "v-176.8", "h152", "v163.33" ] ],
    ["esp:D18", "ultrasonic1:ECHO", "green", [ "h11.37", "v64.67", "h121.33" ] ],
    ["esp:D5", "ultrasonic1:TRIG", "green", [ "h16.7", "v45.07", "h4" ] ],
    ["esp:GND.1", "ultrasonic1:GND", "black", [ "h8.7", "v14.7", "h138.67" ] ]
  ]
}

```

OUTPUT:

```
Connecting to ....
WiFi connected
IP address:
10.10.0.2
Reconnecting client to ytluse.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String
subscribe to cmd OK

Distance (cm): 399.92
Distance (cm): 399.96
Distance (cm): 399.94
Distance (cm): 399.98
Distance (cm): 399.94
Distance (cm): 399.92
Distance (cm): 399.94
```

Circuit Diagram:

