

## IBM ASSIGNMENT- 4

**TEAM ID: PNT2022TMID26584**

**NAME:VINOTHKUMAR K**

**ROLL NO: 212919104056**

**Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cms send "Alert" to ibm cloud aand display in device recent events.**

**Solution:**

```
//Pins
```

```
const int TRIG_PIN = 7 ; const
```

```
int ECHO_PIN = 8;
```

```
//Anything over 400 cm (23200 us pulse) is "out of range"
```

```
const unsigned int MAX_DIST = 23200;
```

```
void setup() {
```

```
// The Trigger pin will tell the sensor to range find
```

```
Pin Mode(TRIG_PIN, OUTPUT); digital
```

```
Write(TRIG_PIN, LOW);
```

```

//Set Echo pin as input to measure the duration of
//pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT );

// We'll use the serial monitor to view the sensor output
Serial.begin(9600);
}
void loop() {
  unsigned long t1;
  unsigned long t2;
  unsigned long
  pulse_width; float
  cm; float inches;
  // Hold the trigger pin high for at least 10 us
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);

  // Wait for pulse on echo pin while
  (digitalRead( ECHO_PIN )==0 );

  // Measure how long the echo pin was held high (pulse width)
  // Note: the micros() counter will overflow after-70 min  t1=
  micros ();
  while (digitalRead(ECHO_PIN) == 1);
  t2= micros ();  pulse_width = t2-t1;

```

```

// Calculate distance in centimeters and inches. The constants
//are found in the datasheet, and calculated from the assumed speed
// of sound in air at sea level (- 340m/s)
cm=pulse_Width / 58 ;    inches  =
pulse_width/148.0;

//  Print  out  results  if
(pulse_width >MAX _ DIST ){
Serial.println("Out of range");
} else {
Serial.println("*****");
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);

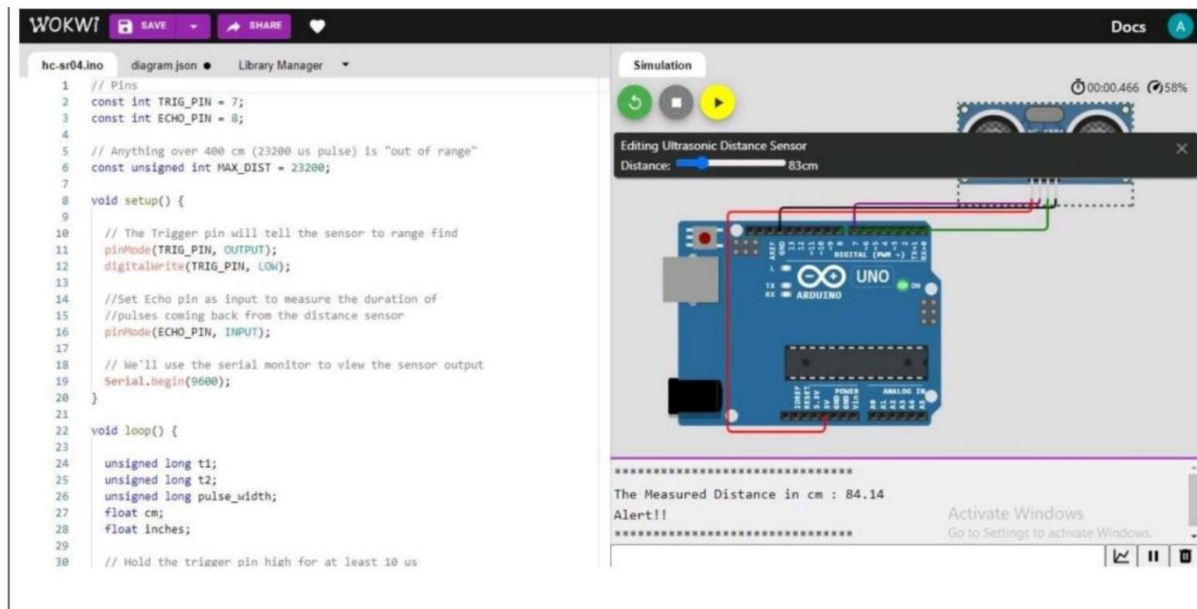
if( cm < 100 ){
    //while(true){
        Serial.println("Alert!!");
        //}
    }
Serial.print("*****");
}

//wait at least 1000ms before next measurement
Delay(1000);
}

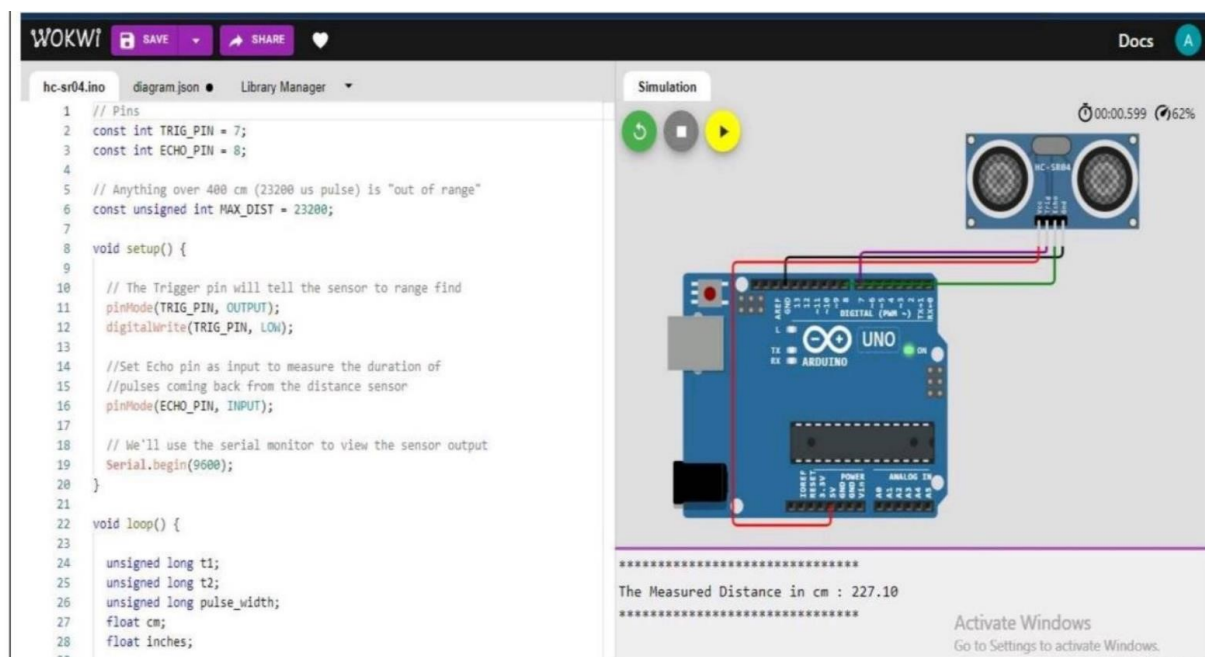
```

## Output:

1.If the distance is less than 100 cms ,it alerts.



2.If the distance is more than 100 cms,it won't alert



### 3.Simulation and code execution

