IBM ASSIGNMENT- 4

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Write Code and connections in wokwi for ultrasonic sensor. whatever distance is less than 100 cms send “Alert” to ibm cloud aand display in device recent events.

Solution: //Pins

```
const int TRIG_PIN = 7 ;  const
int ECHO_PIN = 8;

//Anything over 400 cm (23200 us pulse) is "out of range"  const
unsigned int MAX_DIST = 23200;

void setup() {

// The Trigger pin will tell the sensor to range find
Pin Mode(TRIG_PIN, OUTPUT);  digital
Write(TRIG_PIN, LOW);
```

```
//Set Echo pin as input to measure the duration of
//pulses coming back from the distance sensor
pinMode(ECHO_PIN, INPUT ) ;

// We'll use the serial monitor to view the sensor output
 Serial.begin(9600);
}
void loop() { unsigned
long t1; unsigned long
t2;  unsigned long
pulse_width;  float cm;
float inches;
// Hold the trigger pin high for at least 10 us
digitalWrite(TRIG_PIN, HIGH);
delayMicroseconds(10);  digitalWrite(TRIG_PIN,
LOW);

// Wait for pulse on echo pin while
(digitalRead( ECHO_PIN )==0 );

// Measure how long the echo pin was held high (pulse width)
// Note: the micros() counter will overflow after-70 min  t1=
micros ();
```

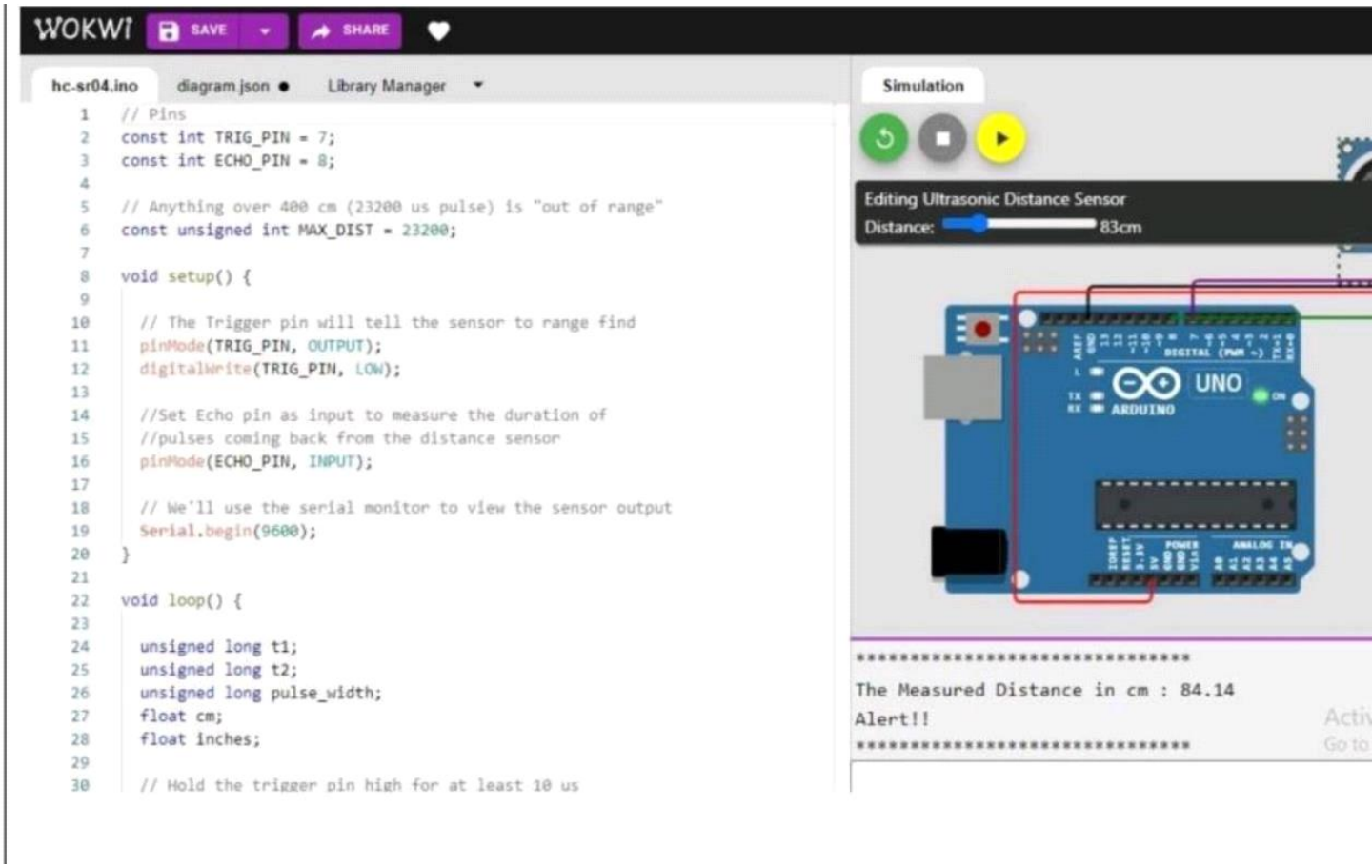
```
  while  (digitalRead(ECHO_PIN)  ==  1);
t2= micros ();    pulse_width = t2-t1;

 // Calculate distance in centimeters and inches. The constants
 //are found in the datasheet, and calculated from the assumed speed
 // of sound in air at sea level (- 340m/s)
cm=pulse_Width   /   58   ;      inches   =
pulse_width/148.0;

//     Print     out     results     if
(pulse_width >MAX _ DIST ){
Serial.println("Out of range");
} else {
Serial.println("*******************************”);
Serial.print("The Measured Distance in cm: ");
Serial.println(cm);

if( cm < 100 ){
     //while(true){
      Serial.println(“Alert!!”);
      //}
}
Serial.print(“*********************************”);
}
//wait at least 1000ms before next measurement
```

Delay(1000);

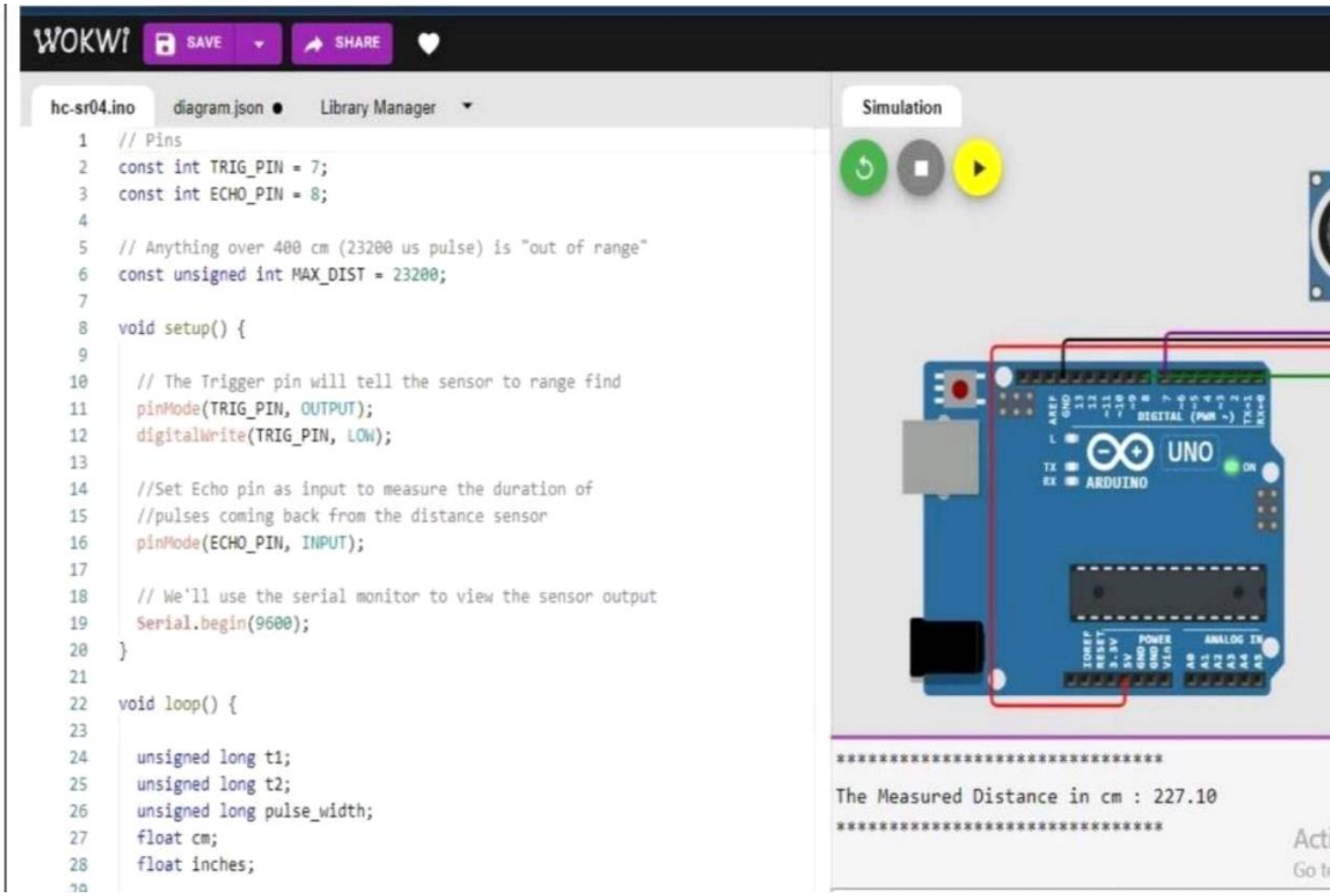
}

Output:

1.If the distance is less than 100 cms ,it alerts.



2.If the distance is more than 100 cms,it won’t alert



3.Simulation and code execution