

# **EMERGING METHODS FOR EARLY DETECTION OF FOREST FIRE**

## **A PROJECT REPORT**

*Submitted by*

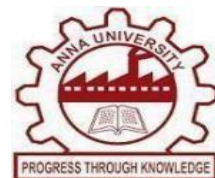
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IN

**ARTIFICIAL INTELLIGENCE DOMAIN**



**VIVEKANANDHA COLLEGE OF ENGINEERING  
FOR WOMEN [Autonomous]**

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Chennai-25, An ISO 9001-2008 Certified Institution  
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## **1.Introduction:**

Forest fires have been and still are serious problem for the European Union and for all other countries in Europe. In the year 2000, the EU has established the European Forest Fire Information system (EFFIS) [1], which will soon become part of the European Emergency Management Service, maintained by the Copernicus Earth Observation Programme [2]. This system provides valuable near real-time and also historical data on the forest fires in Europe, the Middle East and North Africa. Currently EFFIS is being used and supported with data by 25 EU member states and by numerous other countries. According to the annual report of EFFIS for 2016 [3], more than 54 000 forest fires have occurred all around Europe and they have led to nearly 376 thousand hectares of burnt areas. If we compare these values to the average values from the EFFIS reports for the period 2006-2015, the number of forest fires have decreased by 13327 or by nearly 20%. This decrease can be explained with the more severe actions and sanctions towards the arsonists and with the introduction of more advanced technical solutions for early detection of the fires. Even though their number is decreasing, the forest fires continue to be extremely devastating events and they have destroyed just 27 thousand hectares (or 6.6 %) less than the average burnt areas for the period 2006-2015, according to [3]. Confirmation for this are the devastating forest fires from 2018, which took place in the Attica region of Greece and led to more than 90 fatalities and to more than 200 injured people, as well as to the destruction to thousands of buildings [4]. The most important factors in the fight against the forest fires include the earliest possible detection of the fire event, the proper categorisation of the fire and fast response from the fire services. Several different types of forest fires are known, including ground fires, surface fires and crown/tree fires [5]. Each of these types of forest fires is specific and the proper counteractions against it must be considered and implemented to successfully fight it. Over the years the detection of forest fires has been conducted in different ways, ranging from the use of forest outposts to fully automated solutions. In the last decade many improvements in the forest fire detection technologies have been made. The modern IR cameras provide steady and reliable detection of the fires, but the real focus is set on the possibilities to detect the fires by analysing wider

areas for smoke or by sensing the environmental parameters before the actual spread of the fire.

### **1.1 Project Overview:**

Fire can make major hazards in this hectic world. All buildings and vehicles used in public transportation have fire prevention and fire protection systems due to the accelerated number in the fire incidents. Also, many of the firms conduct a mock fire drill in every occurrence of months to protect their employees from the fire. This would help them to understand what to do or what not to do when a fire situation happens. Forests are one of the main factors in balancing the ecology. It is very harmful when a fire occurs in a forest. But most of the time, the detection of forest fire happens when it spread over a wide region. Sometimes, it could not be possible to stop the fire. As a result, the damage of the environment is higher than predictable. The emission of large amount of carbon dioxide (CO<sub>2</sub>) from the forest fire damages the environment. As well as it would lead to complete disappearance of rare species in the world. Also, it can make an impact on the weather, and this make major issues like earthquakes, heavy rains, floods and so on.

A research study shows an automatic fire detection can be divided into three groups: aerial, ground and borne detection. The ground-based systems use several staring black and white video cameras are used in fire detection which detect the smoke and compares it with the natural smoke. The main benefit of using this system is high temporal resolution and spatial resolution. So that, the detection is easier.<sup>2</sup> But these mechanisms still have some drawbacks in detecting the early stage of the fire. So that, it is highly important to introduce a system to detect the fire early as possible.

Moreover, information regarding the seat of the hearth is invaluable for the rapid deployment of fire- fighters. Therefore, early detection, containment at the primary stages and extinguishment of a fireplace before it spreads are crucial for wildfire Management.

### **1.2 Purpose:**

Forest fires as of late have been annihilating both for normal biological system, biodiversity and woodland economy. With expanding populace weight and change

in worldwide atmosphere situation, there is an expansion in level of fires that are a significant reason for declining Indian woodlands. As indicated by woodland study report of India, 50 % of backwoods regions in nation are fire inclined (going from 50 to 90 % in certain conditions of nation). Around 6 % of the woods are inclined to extreme fire harms. The reason for this planned framework is to manufacture a dependable fire location framework so as to know dynamic status of backwoods temperature in specific conditions. It is about the sensors and dynamic checking framework to dodge a significant fire and genuine harm to woods.

## **2.LITERATURE SURVEY:**

### **Abstract:**

Forest fires are occurring throughout the year with an increasing intensity in the summer and autumn periods. These events are mainly caused by the actions of humans, but different nature and environmental phenomena, like lightning strikes or spontaneous combustion of dried leaf or sawdust, can also be credited for their occurrence. Regardless of the reasons for the ignition of the forest fires, they usually cause devastating damage to both nature and humans. Forest fires are also considered as a main contributor to the air pollution, due to the fact that during every fire huge amount of gases and particle mater are released in the atmosphere. To fight forest fires, different solutions were employed throughout the years. They were primary aimed at the early detection of the fires. The simplest of these solutions is the establishment of a network of observation posts – both cheap and easy to accomplish, but also time-consuming for the involved people. The constant evolution of the information and communication technologies has led to the introduction of a new generation of solutions for early detection and even prevention of forest fires. ICT-based networks of cameras and sensors and even satellite-based solutions were developed and used in the last decades. These solutions have greatly decreased the direct involvement of humans in the forest fire detection process, but have also proven to be expensive and hard to maintain. In this paper we will discuss and present two different emerging solutions for early detection of forest fires. The first of these solutions involves the use of unmanned aerial vehicles (UAVs) with specialized cameras. Several different scenarios for the possible use of the drones for forest fire detection will be presented and

analysed, including a solution with the use of a combination between a fixed-wing and a rotary-wing UAVs. In the next chapter of the paper, we will present and discuss the possibilities for development of systems for early forest fire detection using Lora WAN sensor networks and we will analyse and present some of the hardware and software components for the realisation of such sensor networks. The paper will also provide another point-of-view, which will present the involvement of students in the development and in the use of both systems and we will analyse the advantages and the benefits, which the students will gain from their work on and with these solutions.

## **Introduction:**

With the dawn of the Internet, folks have come increasingly interrelated at a novel separate. However, a seamless interconnection between devices is gradually being make, due to the escalation of inadequate-ramble reticulation and the omnipresence of devices constant to these nets. Some of the lacking-order net terminate ZigBee, wireless Fidelity (Wi-Fi), radio frequency identification (RFID) net, Bluetooth, and wireless sensor network (WSNs). It is foreseen that devices will generally be connected collaboratively to construct, converge, and distribute data. These processes mentioned before will involve a series of communication between devices that may or may not need human intervention. These devices are various types of objects or things with embedded intelligence and communication capabilities. Some of those are sensors, cars, smartphones, health care gadgets, home appliances, or RFID tags. Therefore, not only humans are being interconnected, but devices also are being interconnected. The cause of the IoT (Internet of Things) has been come by the pattern chemise enumerate. The IoT is an underived course of the grant Internet, which has been chance from supply man interconnection into a body of interrelated devices.

## **2.1 EXISTING PROBLEMS:**

The existing system for detecting fire are smoke alarms and heat alarms. The main disadvantage of the smoke sensor alarm and heat sensor alarms are that just one module is not enough to monitor all the potential fire prone places. The only way to prevent fire is too cautious at the time. Even if they are installed in every nook and corner, it just is not sufficient for an efficient output consistently. As the

number of smoke sensor requirement increase the cost will also increase to its multiple. The proposed system can produce consistent and highly accurate alerts within seconds of accident of the fire. It reduces cost because only one software is enough to power the entire network of surveillance. Research is active on this field by data scientists and machine learning researchers. The real challenge is to minimize the error in detection of fire and sending alerts at the right time. The idea of this research is to fabricate a system through IoT sensors, which is arbitrarily spread in the forest and to make a self-sorted out powerful system between the sensors to cover all the enormous territories in the forest that will used to maintain a strategic distance from the fire harm whenever. The capacity of the sensor is to identify fire in the inclusion region between the time intermission of each 5-10 minutes. At the point when the fire is recognized the entirety of the sensor in the region will be dynamic and order to stop the normal assignment. The concept is to build early fire detector using Arduino which is connected with different IoT sensors. Putting all efforts to develop a smarter system by connecting it to a webpage and monitoring the developed system statistics controlled by the Arduino programming. The use of latest technology can help to prevent the catastrophic accidents in forests. The aim is to early detect the fireplace in forest by considering the several factor like smoke, temperature, humidity, flame and based on the data we get from this programming, the forest department will be able to take an appropriate decision and the rescue team will be able to arrive on time at exact location. Consider, if it is a large region and it produces more carbon monoxide than the ordinary vehicle traffic. Surveillance of the danger areas and an early detection of fireplace can appreciably shorten the response time and additionally decrease the practicable injury as nicely as the fee of firefighting. Known rule applies here: 1 minute – 1 cup of water, 2 minutes - 100 liters of water, 10 minutes - 1000 liters of water. The goal is to notice the fireplace as quicker as possible, its actual localization and early notification to the fire devices. When fire starts then the flammable texture may likewise issues fuel to the hearth focal spot. The spot at that point will expand and more extensive. The first phase of start is alluded as "surface fire" stage. This may feed on abutting bushes and the fire will turn into higher and transforming into "crown fire". Generally, at this stage the hearth transforms into wild and injury which end up being extreme that could stay for quite long time while depending on atmosphere conditions and the territory. Forest fire detection using optimized solar-powered ZigBee wireless sensor networks- In this paper, they have developed system for Forest Fire Detection which overcomes the demerits of the Existing technologies of Forest Fire Detection. It can be ensured that the system developed can be implemented on a large scale with its promising results. The system is provided with low-power elements, higher versions of Zigbee, Maximum power point tracking Algorithm is used in order to



make the system run for longer periods efficiently. Forest fires are a very serious problem in many countries, and global warming may contribute to make this problem worse. Experts agree that, in order to prevent these tragedies from happening, it is necessary to invest in new technologies and equipment that enable a multifaceted approach. This paper describes a WSN for early detection of forest fires. This network can be easily deployed at areas of special interest or risk. There are two types of nodes from the physical structure point of view: SNs, to collect data from the environment, and CNs, to gather data from the SNs and transmit the information to a Control Centre. The nodes also can be in different functioning modes. This enables a proper and seamless configuration of the network, provides redundancy, and ensures there will be full temporal and geographical coverage in the deployment zone. The information gathered is related not only to early detection purposes but also to environment monitoring to maximize the WSN usage. This environmental data can also be employed to firefighting preventive tasks such as vegetation modelling, microclimate studies, and propagation model parametrization.

In this paper, a forest fire detection algorithm is proposed. The algorithm uses YCbCr color space since it effectively separates luminance from chrominance and is able to separate high temperature fire center pixels because the fire at the high temperature center region is white. The final results show that the proposed system has good detection rates and fewer false alarms, which are the main crucial problems of the most existing algorithms. The presences of fire in video streams are indicated by semantic events. Most of the existing systems can only be used for the videos obtained from stationary cameras and videos obtained from the controlled lightening conditions. These existing automatic fire detection systems cannot be used for video streams obtained from mobile phones or any handheld devices. It was decried as a global tragedy. Lit by farmers, the fires raged through villages, destroyed ecosystems and pumped climate-warming pollution into the atmosphere.

### **Construction:**

The sensors cover two in terminal with an electrolyte. The electrodes are classically fictional by arrangements a highly costly character on to the penetrable hydrophobic pia mater. The at work(predicate) electrode gain both the electrolyte and the chillout information which has to be supervised regularly through a open dura mater. The electrolyte most commonly habit is a rock acrimonious the

electrodes and shelter are for the most part in a moldable saddlecloth which restrain a gasoline vestibule concavity for the petrol and electrical brush.

## **INTERNET OF THINGS:**

The internet of things (IoT) can be determine as the mass of material devices, buildings, vehicles and many paragraph that are fixed with sensors, software, cobweb connectivity, actuators, and electronics that suffer these sight for amass and interchanging complaint. In usual Internet of Things (IoT) is a framework that afford animals, aim or community, the capability to emit over data to a netting that may not enjoin the Christian-to-electronic computer (H2C) or the humane-tohuman (H2H) interaction and the unparalleled identifiers.

## **DATA MANAGEMENT:**

Data charge is an exact air in Internet of Things (IoT). The compass of the furnish data and the activities complex in thumbing of those notice come judicious, when examine a circle of end interrelated and statically dealing all style of instruction. An utilizable space came for wireless communications hew makers when M2M number has been emit, which is also the endow technology for Internet of Things (IoT). This technology hobble free row of applications.

Some of the most relevant concepts which enable us to understand the challenges and opportunities of data management are:

- Data Collection and Analysis
- Big Data
- Semantic Sensor Networking
- Virtual Sensors
- Complex Event Processing.

## **CONCLUSION**

In this project changeable sensory parameters algorithmic rule, a system has been improved which will reduce the error perception and updates the deficiency to the

expert often through the IOT landing. D2D association conventionality an definite integral part which intercept IOT surrounding to designate, accomplish, and support a endureable ecosystem. The system thus intend is powerful to expose the mixture variations, daring gases and fire event through the sensors in an diligence and powerful to update the complaint to the style expert through the IOT fulfill secondhand MQTT policy. The improved system can be unfold for tenement appliances and in industries also. However, the system above is meant for a sincere opinion news only. As a tomorrow aggravation, several-decision company through the IOT landing is study a object and the exploration is being done to effectuate this enormous toil. It is trust that with the technological advancements profitable in instant age scenario, the above rehearse several-opinion correspondence will also be unfold in aqiqiy delay environments.

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- [5] D. Lake, A. Rayes, and M. Morrow, "The Internet of Things," *Internet Protocol J.*, vol. 15, no. 3, pp. 10–19, Sep. 2012. [Online]. Available: [http://www.cisco.com/web/about/ac123/ac147/archived\\_issues/ipj\\_15-3/153\\_Internet.html](http://www.cisco.com/web/about/ac123/ac147/archived_issues/ipj_15-3/153_Internet.html)

## **2.3 Problem Statement Definition:**

- \_\_\_\_In earlier times fires were detected with the help of watching towers or using

satellite images.

- Satellites collect images and send it to the monitoring authority which will decide by seeing images that it is a fire or not.
- But this approach was very slow as the fire may have spread in the large areas and caused so much damage before the rescue team came.
- In the watching tower method, there was a man always standing on the tower who would monitor the area and inform if there was fire.
- This method was also slow because before the man got to know about the fire it may have spread in the inner parts of forest, also it always requires a man who must be present there.
- Since, we know that some areas, especially forest areas are large so it is practically impossible to put a man in every part of forest from where they can monitor the forest area.
- So, both these approaches of watching towers and satellite images failed to detect fire as early as possible to reduce the damage done by fire. Problems in fire detection:
- There were mainly two problems in fire detection as discussed:
- (a). Judging criteria for the fire: Edge is set, on the off chance that the worth is more noteworthy than edge, it is a fire, else not.
- So, this problem was removed by using machine learning techniques by many researchers.
- (b). Connection of nodes: Traditional systems used cables to connect alarm with the detectors.
- Cable was mainly of copper. But copper wire may be costly or it can suffer from fault in the mid-way.
- So, this problem was removed using wireless sensor networks.
- So, with the advancement in technology researchers find an efficient method to detect forest fire with the help of Wireless Sensor Network.
- Fire can be identified by conveying sensor hubs in timberland regions by which they illuminate about fire.
- Conveying sensor hubs in the timberland regions means placing sensors in every part of the forest and mostly in the prone areas where risk of catching fire is more. With the use of wireless sensor networks, now it is easy to detect the fire in large areas as soon as possible.

## Customer Problem Statement Template :



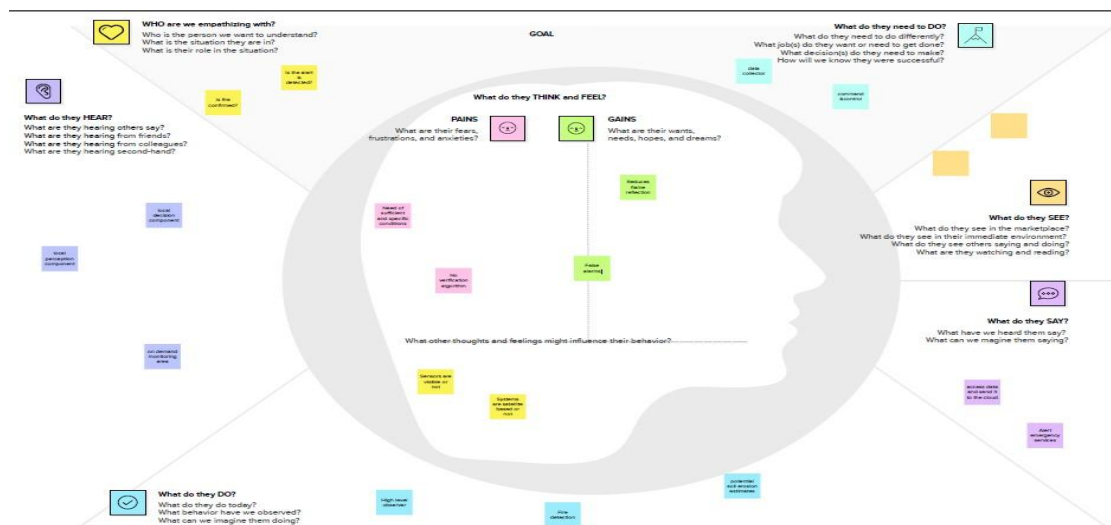
Problem Statement (PS)	I am (Customer)	I'm trying to	But	Because	Which makes me feel
PS-1	an officer from the forest department	conserve, protect and develop forests and wildlife	forest fire is making it impossible. Forest fire results in the loss of valuable resources, loss of biodiversity and extinction of plants and animals	of lack of resources for the early detection of forest fire	underperforming
PS-2	a fire fighter	put out fire, helping the injured and keeping people safe in emergency situation	forest fire is making it impossible.	of the quick spread of fire and it is difficult to control fire after spread	underperforming

### 3.IDEATION & PROPOSED SOLUTION

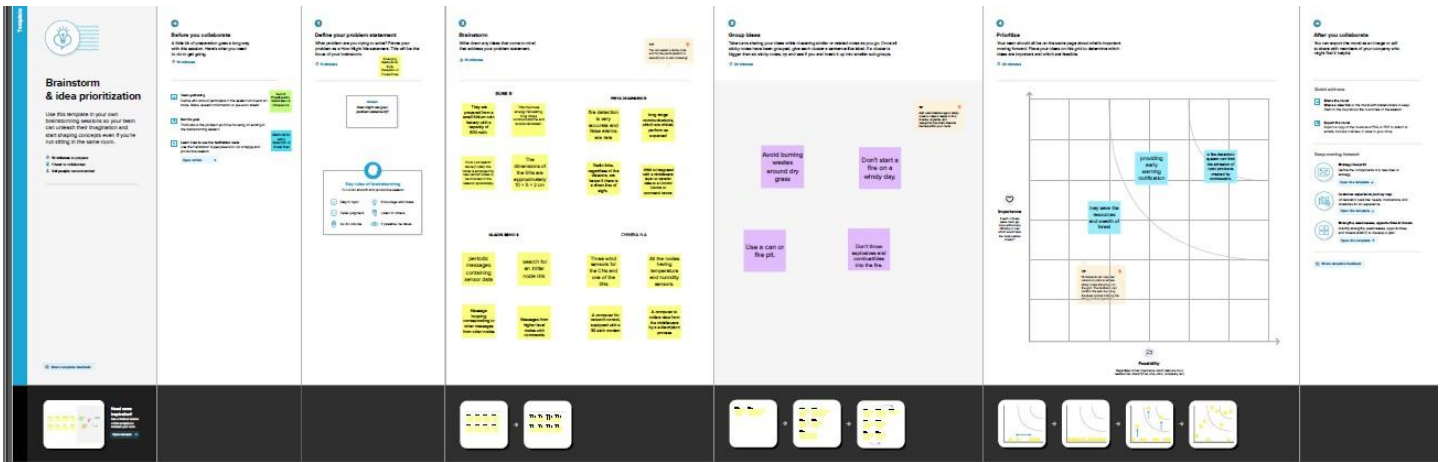
#### 3.1 Empathy Map Canvas:

An empathy map is a collaborative tool teams can use to gain a deeper insight into their customers. Much like a user persona, an empathy map can represent a group of users, such as a customer segment. The empathy map was originally created by Dave Gray and has gained much popularity within the agile community.

- An empathy map is an effective visualization template that helps analyze the behavior and emotions of customers and users. Empathy maps not only detect the behaviors but highlight possible mediums for brands to communicate with their customers in a better way
- Empathy maps can also be used to collect data directly from the users. Used alongside user interviews, survey answers, etc., you can also have a user fill in an empathy map themselves. This often reveals aspects of the user that may have remained unsaid or not thought of.
- Each of the four quadrants comprises a category that helps us delve into the mind of the user. The four empathy map quadrants look at what the user says, thinks, feels, and does.



## 3.2 Ideation & Brainstorming:

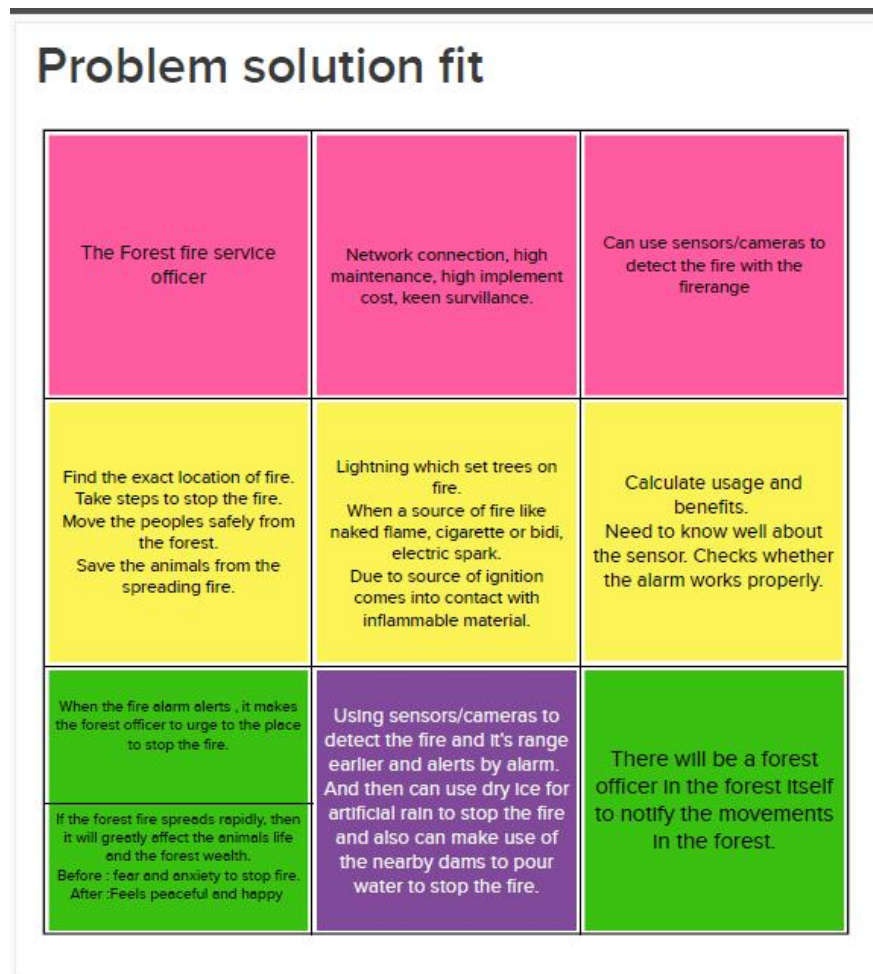


## 3.3 Proposed Solution

S.No.	Parameter	Description
1.	Problem Statement (Problem to be solved)	<p>1.Forest fires are a major environmental issue, creating economic and ecological damage while endangering human lives.</p> <p>2.It is difficult to predict and detect Forest Fire in a sparsely populated forest area.</p> <p>3. So, it is necessary to detect the fire in an early stage to control it.</p>
2.	Idea / Solution description	<p>1.The model will detect forest fires automatically with the help of image processing using deep learning and with the use of satellite image data to observe, detect and report fire events.</p>
3.	Novelty / Uniqueness	<p>When the fire is detected, the station will get a notification via message and an alarm system will be activated automatically to alert the user.</p>
4.	Social Impact / Customer Satisfaction	<p>1. This can reduce the forest fire in the beginning stage, by alerting users.</p> <p>2. The user can also use this as a surveillance</p> <p>3.Camera to monitor the forest.</p>

		Saving the most essential Forest cover.
5.	Business Model (Revenue Model)	<p>1.This application will be available in a subscription-based model.</p> <p>2.Supply chain, power &amp; supply, Fire stations, and government by providing services.</p>
6.	Scalability of the Solution	<p>1.This application can monitor different places simultaneously and can detect fire accurately</p> <p>2.This application can handle a large number of users and data simultaneously.</p>

### 3.4 Problem Solution fit





## **4 REQUIREMENT ANALYSIS**

### **4.1. FUNCTIONAL REQUIREMENT:**

FR No.	Functional Requirement (Epic)	Sub Requirement (Story / Sub-Task)
FR-1	User Registration	Registration through Form Registration through Gmail
FR-2	User Confirmation	Confirmation via Email Confirmation via OTP
FR-3	Accurate model	The model gives accurate results for detection of forest fires.
FR-4	Good hardware	To obtain high quality images to perform real time detection
FR-5	cloud	We need cloud for storage and deploying the application
FR-6	Website	Easy to use and navigate website that send alerts to authorities when forest fire is detected.

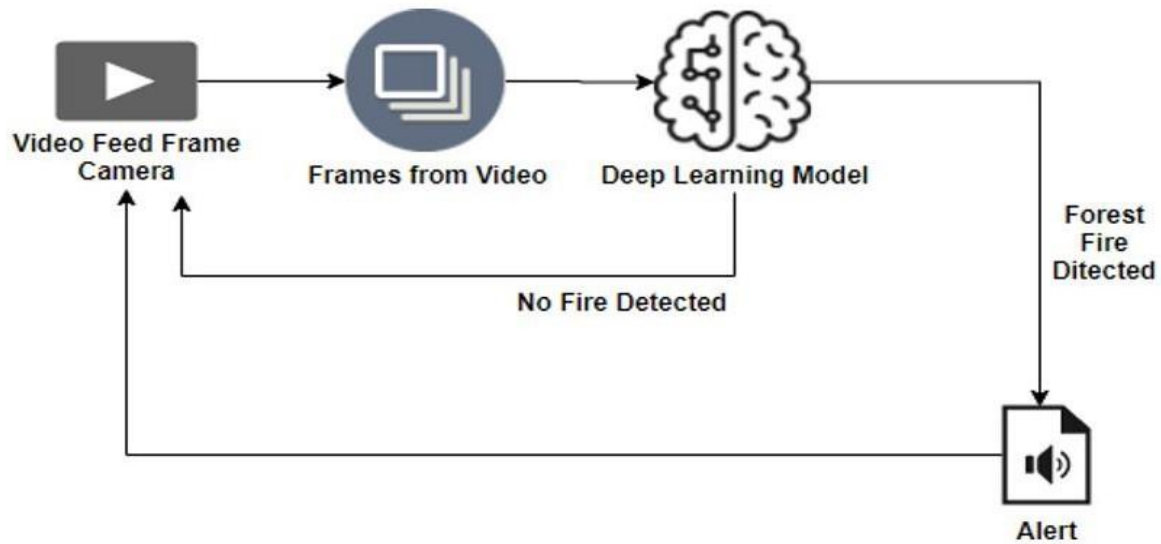
### **4.2 Non-Functional requirements:**

FR No.	Non-Functional Requirement	Description
NFR-1	Usability	The interface will be easy to use and very user friendly and can be used by anyone.
NFR-2	Security	The application will be secure and safe to use.

NFR-3	<b>Reliability</b>	It will be taken care such that the application only produces highly accurate results and will accurately detect forest fires.
NFR-4	<b>Performance</b>	The model will perform detection in few seconds.
NFR-5	<b>Availability</b>	It will be available 24/7 will minimal downtime to continuously monitor
NFR-6	<b>Scalability</b>	The project is highly scalable and can be scaled up to monitor and detect forest fires in large forest or can also be scaled down to monitor and detect forest fires in particular areas alone

## **5.PROJECT DESIGN**

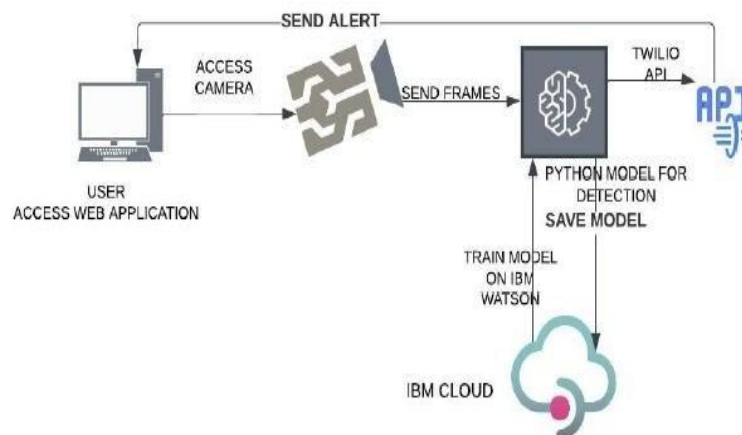
### **5.1 Data Flow Diagrams:**



A Data Flow Diagram (DFD) is a traditional visual representation of the information flows within a system. A neat and clear DFD can depict the right amount of the system requirement graphically. It shows how data enters and leaves the system, what changes the information, and where data is stored

- It is difficult to predict and detect Forest Fire in a sparsely populated forest area.
- It is more difficult if the prediction is done using ground-based methods like Camera or Video-Based approach.
- Satellites can be an important source of data prior to and also during the Fire due to its reliability and efficiency.
- The various real-time forest fire detection and prediction approaches, with the goal of informing the local fire authorities.
- If the fire is not detected ,it will send the result to the frame camera.if the forest fire will detected the alert will go to the video feed frame camera.

## **5.2 Solution & Technical Architecture:**



Solution architecture is a complex process – with many sub-processes – that bridges the gap between business problems and technology solutions. Its goals are to:

- Find the best tech solution to solve existing business problems.

- Describe the structure, characteristics, behavior, and other aspects of the software to project stakeholders.
- Define features, development phases, and solution requirements.
- Provide specifications according to which the solution is defined, managed, and delivered.

**Table-1 : Components & Technologies:**

S. No	Component	Description	Technology
1.	User Interface	User interacts with application through Web UI	Python flask/ HTML ,CSS
2.	Application Logic-1	To capture video and convert to frames	Python – opencv, YOLO
3.	Application Logic-2	To develop model with accurate detection results	CNN, IBM Watson
4.	Cloud Database	Database Service on Cloud	IBM DB2, IBM Cloudant etc.
5.	External API-1	Dataset is split into training and testing and used to train the model	Dataset from cloud storage,Database
6.	Machine Learning Model	Machine learning model is used to detect forest fires	Jupyter notebook.
7.	Infrastructure (Server / Cloud)	Application is deployment on Cloud	IBM Cloud Foundry, Kubernetes.

**Table-2: Application Characteristics:**

S. No	Characteristics	Description	Technology
1.	Open-Source Frameworks	Python flask, Jupyter notebook	Used to develop python model and web UI
2.	Security Implementations	The application will have utmost security	e.g.SHA-256, Encryptions, IAM Controls
3.	Scalable Architecture	The project is highly scalable. A three tier architecture will be used	Web server- python Django, flask/html css Application server – anaconda, IBM Watson. Database server- IBM DB
4.	Availability	Load balancing will be done and application will be available 99% of time	IBM load balancer
5.	Performance	IBM CDN will be used to increase performance	IBM Content Delivery Network

### **5.3 User Stories:**

User Type	Functional Requirement (Epic)	User Story Number	User Story / Task	Acceptance criteria	Priority	Release
Customer (web user)	Registration	USN-1	As a user, I can register for the application by entering my email, password, and confirming my password.	I can access my account / dashboard	High	Sprint-1
		USN-2	As a user, I will receive confirmation email once I have registered for the application	I can receive confirmation email & click confirm	High	Sprint-2
	Login	USN-3	As a user, I can register for the application through Gmail single sign on	Registration successful	Medium	Sprint-2
		USN-4	As a user, I can log into the application by entering email & password	Login successful	High	Sprint-1
	Dashboard	USN-5	As a user, I receive notification if any fire is detected	I can receive the notification if I'm the control service	High	Sprint-1
Administrator		USN-1	Admin is able to manage and maintain database	IBM Watson stores all the data	High	Sprint-1

## **6. PROJECT PLANNING & SCHEDULING**

The definition of a sprint is a dedicated period of time in which a set amount of work will be completed on a project. It's part of the agile methodology, and an Agile project will be broken down into a number of sprints, each sprint taking the project closer to completion.

### **6.1 Sprint Planning & Estimation:**

<b>Sprint</b>	<b>Functional Requirement (Epic)</b>	<b>User Story Number</b>	<b>User Story / Task</b>	<b>Story Points</b>	<b>Priority</b>	<b>Team Members</b>
Sprint-1	Image Processing	USN-1	The system should process the image to identify the fire if it occurs.	10	High	Srijanani M Punitha M
Sprint-1		USN-2	The information should be accurate and it would be	10	High	Surega k Swetha R

			given correctly as per the trained information in the knowledge base.			
Sprint-2	Video Processing	USN-3	The real information should be processed with the help of CNN to detect the fire	10	High	Srijanani M Surega K
Sprint-2		USN-4	The video processing should also calculate the fire Spread range and give the real time data.	10	High	Punitha M Swetha R
Sprint-3	Alerting	USN-5	After detecting the fire by the image processing technique, the alarm would be alerted.	10	High	Srijanani M Punitha M
Sprint-4	Location tracking	USN-6	The exact location of the fire occurrence should be alerted via the GPS location tracker embedded in it.	20	High	Surega k Swetha R



Sprint-3	Sending Information	USN-7	The alarm alert would confirm the occurrence of fire	5	High	SRIJANA NI M PUNITHA M
Sprint-3		USN-8	The exact location of fire and the fire spread range should be sent to the nearby Fire Station.	15	High	Surega K Swetha R

## **6.2 Sprint Delivery Schedule:**

### **Project Tracker, Velocity & Burndown Chart:**

<b>Sprint</b>	<b>Total Story Points</b>	<b>Duration</b>	<b>Sprint Start Date</b>	<b>Sprint End Date (Planned)</b>	<b>Story Points Completed (as on Planned End Date)</b>	<b>Sprint Release Date (Actual)</b>
Sprint-1	20	8 Days	27-10-2022	3-11-2022	20	3-11-2022
Sprint-2	20	8 Days	5-11-2022	12-11-2022	20	12-11-2022
Sprint-3	30	8 Days	14-11-2022	21-11-2022	30	21-11-2022
Sprint-4	20	8 Days	23-11-2022	30-11-2022	20	30-11-2022

### **Velocity:**

. Let's calculate the team's average velocity (AV) per iteration unit (story points per day).

$$\begin{aligned}
 \text{AV} &= \text{Velocity} / \text{Sprint Duration} \\
 &= 20 / 8
 \end{aligned}$$

$$= 2.5$$

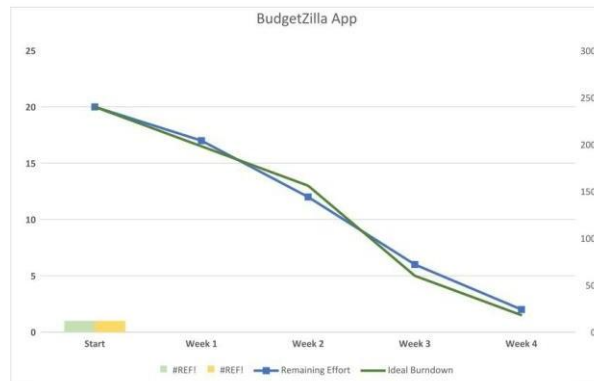
$$AV = 30 / 8$$

$$= 3.75$$

### Burndown Chart:

X-axis - Days

Y-axis - Story Points



### 1.3

JIRA has categorized reports in four levels, which are –

- Agile
- Issue Analysis
- Forecast & Management
- Others

### Reports from JIRA:

## **7.CODING & SOLUTIONING (Explain the features added in the project along with code)**

### **7.1 Feature 1:**

! pip install tensorflow

! pip install opencv-python

! pip install opencv-contrib-python

import tensorflow as tf

import numpy as np

from tensorflow import keras

import cv2

```

import cv2
from tensorflow.keras.preprocessing.image import ImageDataGenerator
from tensorflow.keras.preprocessing import image
train=ImageDataGenerator(rescale=1./255,
                        shear_range=0.2,
                        rotation_range=180,
                        zoom_range=0.2,
                        horizontal_flip=True)
train = ImageDataGenerator(rescale=1/255)
test = ImageDataGenerator(rescale=1/255)
train_dataset = train.flow_from_directory("/content/drive/MyDrive/Dataset/train_set",
                        target_size=(128,128),
                        batch_size = 32,
                        class_mode = 'binary' )
test_dataset = test.flow_from_directory("/content/drive/MyDrive/Dataset/test_set",
                        target_size=(128,128),
                        batch_size = 32,
                        class_mode = 'binary' )

test_dataset.class_indices

#to define linear initialisation import sequential
from keras.models import Sequential
#to add layer import Dense
from keras.layers import Dense
#to create convolution kernel import convolution2D
from keras.layers import Convolution2D
#import Maxpooling layer

```

```
from keras.layers import MaxPooling2D
#import flatten layer
from keras.layers import Flatten
import warnings
warnings.filterwarnings('ignore')
model = Sequential()
#add convolutional layer
model.add(Convolution2D(32,(3,3),input_shape=(128,128,3),activation='relu'))
#add maxpooling layer
model.add(MaxPooling2D(pool_size=(2,2)))
#add flatten layer
model.add(Flatten())
model.add(Dense(150,activation='relu'))

model.add(Dense(1,activation='sigmoid'))
model.compile(loss = 'binary_crossentropy',
              optimizer = "adam",
              metrics = ["accuracy"])

model.fit_generator(x_train,steps_per_epoch=14,epochs=5,validation_data=x_test,
validation_steps=4)

model.save("/content/drive/MyDrive/archive(1)/forest1.h5")

predictions = model.predict(test_dataset)
predictions = np.round(predictions)
predictions
print(len(predictions))
#import load_model from keras.model
from keras.models import load_model
```

```

#import image class from keras
import tensorflow as tf
from tensorflow.keras.preprocessing import image
#import numpy
import numpy as np
#import cv2
import cv2

#load the saved model
model = load_model("/content/drive/MyDrive/archive(1)/forest1.h5")
def predictImage(filename):
    img1 = image.load_img(filename,target_size=(128,128))
    Y = image.img_to_array(img1)
    X = np.expand_dims(Y,axis=0)
    val = model.predict(X)
    print(val)
    if val == 1:
        print(" fire")
    elif val == 0:
        print("no fire")
predictImage("/content/drive/MyDrive/Dataset/test_set/with fire/19464620_401.jpg")

```

## 7.2 Feature 2

```

!pip install tensorflow
!pip install opencv-python
!pip install opencv-contrib-python

```

```

import tensorflow as tf
import numpy as np
from tensorflow import keras
import os
import cv2
from tensorflow.keras.preprocessing.image import ImageDataGenerator
from tensorflow.keras.preprocessing import image
train=ImageDataGenerator(rescale=1./255,
                        shear_range=0.2,
                        rotation_range=180,
                        zoom_range=0.2,
                        horizontal_flip=True)
train = ImageDataGenerator(rescale=1/255)
test = ImageDataGenerator(rescale=1/255)
train_dataset = train.flow_from_directory("/content/drive/MyDrive/Dataset/train_set",
                                         target_size=(128,128),
                                         batch_size = 32,
                                         class_mode = 'binary' )
test_dataset = test.flow_from_directory("/content/drive/MyDrive/Dataset/test_set",
                                         target_size=(128,128),
                                         batch_size = 32,
                                         class_mode = 'binary' )
test_dataset.class_indices
#to define linear initialisation import sequential
from keras.models import Sequential

```

```

predictions = np.round(predictions)
predictions
print(len(predictions))
#import load_model from keras.model
from keras.models import load_model
#import image class from keras
import tensorflow as tf
from tensorflow.keras.preprocessing import image
#import numpy
import numpy as np
#import cv2
import cv2
#load the saved model
model = load_model("/content/drive/MyDrive/archive(1)/forest1.h5")
def predictImage(filename):
    img1 = image.load_img(filename,target_size=(128,128))
    Y = image.img_to_array(img1)
    X = np.expand_dims(Y,axis=0)
    val = model.predict(X)
    print(val)
    if val == 1:
        print(" fire")
    elif val == 0:
        print("no fire")
predictImage("/content/drive/MyDrive/Dataset/test_set/with fire/19464620_40
1.jpg")
pip install twilio

```



```
pip install playsound
#import opencv librariy
import cv2
#import numpy
import numpy as np
#import image function from keras
from keras.preprocessing import image
#import load_model from keras
from keras.models import load_model
#import client from twilio API
from twilio.rest import Client
#imort playsound package
from playsound import playsound
#load the saved model
model = load_model(r'/content/drive/MyDrive/archive(1)/forest1.h5')
#define video
video = cv2.VideoCapture('/content/Fighting Fire with Fire _ Explained in 30 Seco
nds.mp4')
#define the features
name = ['forest','with forest']
account_sid='ACfb4e6d0e7b0d25def63044919f1b96e3'
auth_token='f9ae4fc4a617a527da8672e97eeb2d8'
client=Client(account_sid,auth_token)
message=client.messages \
.create(
    body='Forest Fire is detected, stay alert',
    from_='+1 302 248 4366',
```

```

        to='+91 99400 12164'
    )
    print(message.sid)
    pip install pygobject
    def message(val):
        if val==1:
            from twilio.rest import Client
            print('Forest fire')
            account_sid='ACfb4e6d0e7b0d25def63044919f1b96e3'
            auth_token='f9ae4fc4a617a527da8672e97eefb2d8'
            client=Client(account_sid,auth_token)
            message=client.messages \
                .create(
                    body='forest fire is detected, stay alert',
                    #use twilio free number
                    from_='+1 302 248 4366',
                    #to number
                    to='+91 99400 12164')
            print(message.sid)
            print("Fire detected")
            print("SMS Sent!")
        elif val==0:
            print('No Fire')
    from matplotlib import pyplot as plt
    #import load model from keras.model
    from keras.models import load_model
    #import image from keras

```

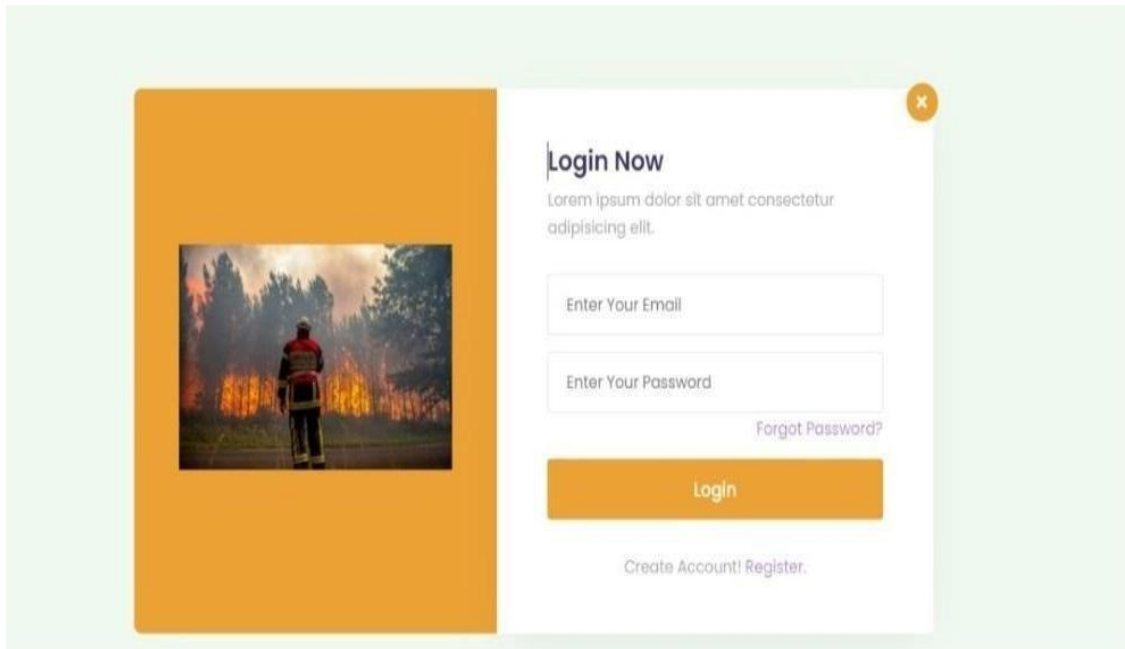
```
from tensorflow.keras.preprocessing import image
img1 = image.load_img('/content/drive/MyDrive/Dataset/test_set/with fire/Wild_fires.jpg',target_size=(128,128))
Y = image.img_to_array(img1)
x = np.expand_dims(Y,axis=0)
val = model.predict(x)
plt.imshow(img1)
plt.show()
message(val)

img2 = image.load_img('/content/drive/MyDrive/Dataset/test_set/forest/1200px_Mountainarea.jpg',target_size=(128,128))
Y = image.img_to_array(img2)
x = np.expand_dims(Y,axis=0)
val = model.predict(x)
plt.imshow(img2)
plt.show()
message(val)
```

## **8.TESTING:**

Test cases help guide the tester through a sequence of steps to validate whether a software application is free of bugs, and working as required by the end-user. Learning how to write test cases for software requires basic writing skills, an attention to detail, and a good understanding of the application under test (AUT).

### **8.1 Test Cases:**



## 8.2 User Acceptance Testing:

```
Console 1/A x
1/1 [=====] - 0s 62ms/step
[[4.243551e-22]]
1/1 [=====] - 0s 53ms/step
No Danger
1/1 [=====] - 0s 63ms/step
[[7.634438e-22]]
1/1 [=====] - 0s 62ms/step
No Danger
1/1 [=====] - 0s 47ms/step
[[1.]]
1/1 [=====] - 0s 47ms/step
SM1df163cc8f6d8ec6d683d249bd9e8616
Fire Detected
SMS sent
1/1 [=====] - 0s 47ms/step
[[0.0001815]]

IPython Console History
LSB Python: ready  conda: base (Python 3.9.13)  Line 20, Col 1  ASCII  CRLF  RW  Mem 87%
```

## **9.RESULT**

### **9.1 Performance Metrics:**



### **10. Advantages & Disadvantages:**

#### **Advantages:**

- Avoid Smoke Inhalation. The most important reason is perhaps the only one you really need.
- Early Detection. The earlier a fire is detected, the faster it will be that firefighters will respond.
- Insurance Discounts.
- 24/7 Monitoring.
- Easy & Affordable.

#### **Disadvantages:**

- The system is essentially useless if the batteries aren't charged, since it won't work properly.
- There is a bit of a burden to business owners to always remember to keep the batteries fresh so the system operates properly when you need it most.

## **11.CONCLUSION**

This project will help in early detection of forest fire and the prevention. It also involves the risk factor of analyzing the drone images of affected areas using machine learning algorithm which overcomes the existing project. This system detects the fire conditions in a short time before any fire accidents spreads over the forest area. The scope of using video frames in the detection of fire using machine learning is challenging as well as innovative. If this system with less error rate can be implemented at a large scale like in big factories, houses, forests, it is possible to prevent damage and loss due to random fire accidents by making use of the Surveillance System.

## **12.FUTURE SCOPE:**

Future Scope In future, we are planning to install smart water tank system in dense forest where reachability of resources and firefighters is difficult. In addition to that we will be updating the system with more features and reliability. We will also include a high pitch sound system that will keep away the animals from the site of fire. The proposed system can be developed to more advanced system by integrating wireless sensors with CCTV for added protection and precision. The algorithm shows great promise in adapting to various environment.

## **13.APPENDIX:**

### **Source Code:**

```
#import opencv librariy
import cv2
#import numpy
import numpy as np
#import image function from keras
from keras.preprocessing import image
#import load_model from keras
```

```

from keras.models import load_model
#import client from twilio API
from twilio.rest import Client
#imort playsound package
from playsound import playsound
#load the saved model
model = load_model(r'forest1.h5')
#define video
video = cv2.VideoCapture(0)
#define the features
name = ['forest','with forest']
account_sid = 'AC557b4c7a685d072baa73125f61031af3'
auth_token = 'a59cd5e5fdiddcc9ab008273557f8f78'
client = Client(account_sid, auth_token)
message = client.messages \
.create(
body='Forest fire is detected , stay alert',
from_='+14247991869',
to='+918940722793'
)
print(message.sid)
#import opencv library
import cv2

```

```
#import numpy
import numpy as np
#import images and load_model function from keras
from keras_preprocessing import image
from keras.models import load_model
#import client from twilio API
from twilio.rest import Client
#import playsound package
from playsound import playsound
#load the saved model
model = load_model(r'forest1.h5')
video = cv2.VideoCapture(0)
name = ['forest','with fire']
while(1):

    success, frame=video.read() cv2.imwrite("image.jpg",frame)
    img=image.load_img("image.jpg",target_size=(128,128,3))
    x=image.img_to_array(img)
    x=np.expand_dims(x,axis=0)
    pred=model.predict(x)
    p=pred[0]
    print(pred)
    ##cv2.putText(frame,"predicted class= "+str(name[p]), (100,100),
```



```
## cv2.FONT_HERSHEY_SIMPLEX, 1, (0,0,0), 1)
pred=model.predict(x)

if pred[0]==1:

    account_sid = 'AC557b4c7a685d072baa73125f61031af3'
    auth_token = 'a59cd5e5fdiddcc9ab008273557f8f78'
    client = Client(account_sid, auth_token)
    message=client.messages\
    .create(
```

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```
body='Forest Fire is Detected, stay alert',
from_='+14247991869',to='+918940722793')
print(message.sid)
print('Fire Detected')
print('SMS sent')
playsound(r'C:\Users\My\Downloads\buzzer.mp3')
else:
    print("No Danger")
    cv2.imshow("image",frame)
    if cv2.waitKey(1) & 0xFF ==ord('a'):
        break
    video.release
```

cv2.destroyAllWindows()

**Github Link :**

<https://github.com/IBM-EPBL/IBM-Project-36330-1660294290>