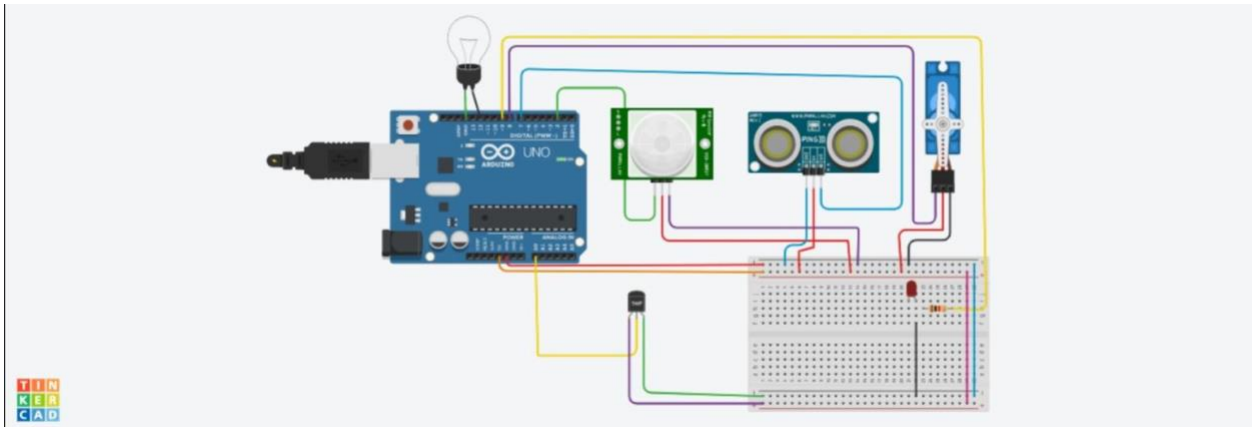


## SMART HOME AUTOMATION SYSTEM USING ARDUINO IN IOT



### COMPOENTS:

- ULTRASONIC DISTANCE SENSOR
- BULB
- RESISTOR
- LED
- BREADBOARD SMALL
- ARDUINO UNO
- PIR SENSOR
- MICRO SERVO
- TEMPARATURE SENSOR (TMP30)

Circuit design Smashing Hillar W x +

tinkercad.com/things/TROScBvtlyf-smashing-hillar-waasa/editel?tenant=circuits

Smashing Hillar-Waasa

All changes saved

Code Start Simulation Send To

Blocks 1 (Arduino Uno R3)

- Output
- Input
- Notation
- Control
- Math
- Variables

Serial Monitor

Smashing Hillar ...png smashing hillar wa...ino Show all x

89°F Mostly clear

ENG IN 2:31 22.09.2022

#### **CODING:**

```
#include <Servo.h>
```

```
Int dish = 0;
```

```
Long readUltrasonicDistance(int triggerPin, int echoPin)
```

```
{
```

```
    pinMode(triggerPin, OUTPUT); // Clear the trigger
```

```
    digitalWrite(triggerPin, LOW);
```

```
    delayMicroseconds(2);
```

```
    // Sets the trigger pin to HIGH state for 10 microseconds
```

```
    digitalWrite(triggerPin, HIGH);
```

```
    delayMicroseconds(10);
```

```
    digitalWrite(triggerPin, LOW);
```

```
    pinMode(echoPin, INPUT);
```

```
    // Reads the echo pin, and returns the sound wave travel time in microseconds
```

```
    Return pulseIn(echoPin, HIGH);
```

```
}
```

```
Servo servo_8;
```

```
Void setup()
```

```
{
```

```
    Servo_8.attach(8, 500, 2500);
```

```
    pinMode(2, INPUT);
```

```
    pinMode(12, OUTPUT);
```

```
    pinMode(A0, INPUT);
```

```
    pinMode(9, OUTPUT);
```

```
}
```

```
Void loop()
```

```
{
```

```
    Dish = 0.01723 * readUltrasonicDistance(7, 7);
```

```
    If (dish <= 100) {
```

```
Servo_8.write(90);  
Delay(1000); // Wait for 1000 millisecond(s)  
} else {  
    Servo_8.write(0);  
    Delay(1000); // Wait for 1000 millisecond(s)  
    If (digitalRead(2) == 1) {  
        digitalWrite(12, HIGH);  
        delay(1000); // Wait for 1000 millisecond(s)  
    } else {  
        digitalWrite(12, LOW);  
        delay(1000); // Wait for 1000 millisecond(s)  
        if (analogRead(A0) >= 300) {  
            digitalWrite(9, HIGH);  
            delay(1000); // Wait for 1000 millisecond(s)  
        } else {  
            digitalWrite(9, LOW);  
            delay(1000); // Wait for 1000 millisecond(s)  
        }  
    }  
}  
Delay(1000); // Wait for 1000 millisecond(s)  
}
```