PROJECT DEVELOPMENT PHASE SPRINT-III

Date	13 November 2022
TeamID	PNT2022TMID12839
Project Name	Intelligent vehicle damage assessment & cost estimator forinsurance companies.

Import and unzip the dataset

from google.colab import drive drive.mount('/content/drive')

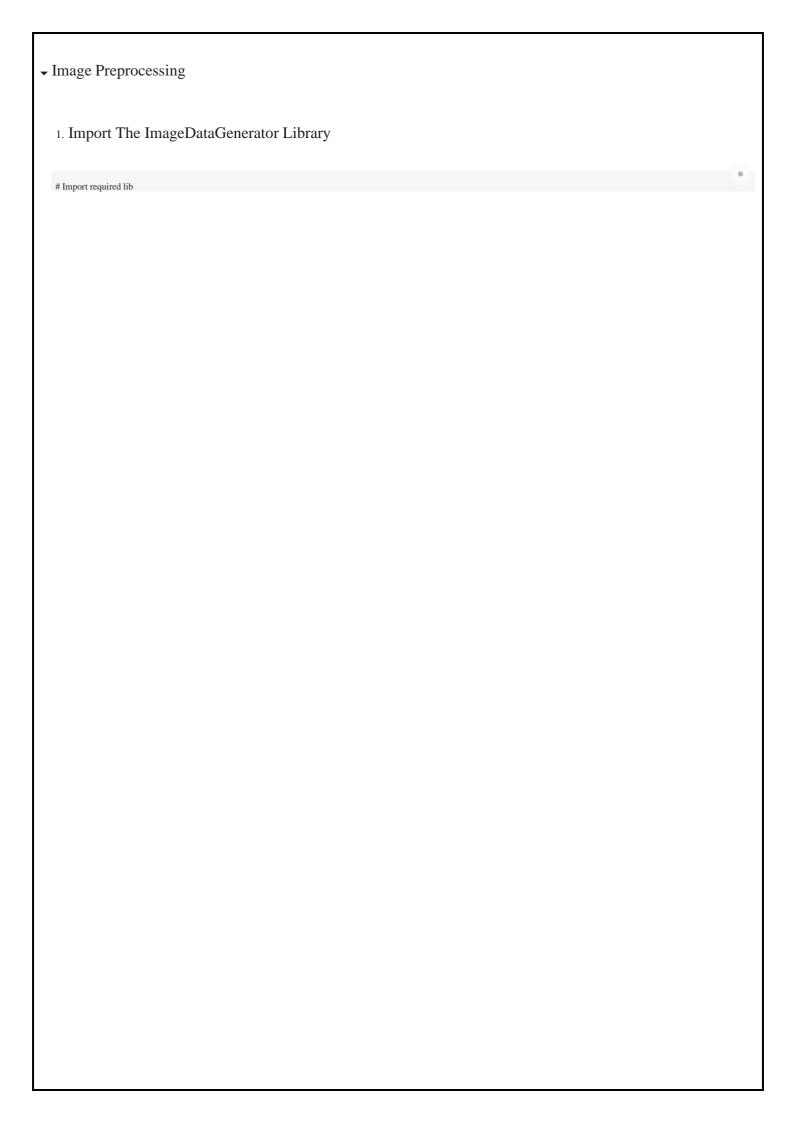
Mounted at /content/drive

#unzip the downloaded dataset
!unzip '/content/drive/MyDrive/damage vehicle.zip'

Archive: /content/drive/MyDrive/damage vehicle.zip creating: damage vehicle/ creating: damage vehicle/body/ creating: damage vehicle/body/training/ creating: damage vehicle/body/training/00-front/ inflating: damage vehicle/body/training/00-front/0001.jpeg inflating: damage vehicle/body/training/00front/0002.JPEG inflating: damage vehicle/body/training/00-front/0003.JPEG inflating: damage vehicle/body/training/00front/0004.JPEG inflating: damage vehicle/body/training/00-front/0005.JPEG inflating: damage vehicle/body/training/00front/0006.JPEG inflating: damage vehicle/body/training/00-front/0007.JPEG inflating: damage vehicle/body/training/00front/0008.jpeg inflating: damage vehicle/body/training/00-front/0009.JPEG inflating: damage vehicle/body/training/00front/0010.JPEG inflating: damage vehicle/body/training/00-front/0011.JPEG inflating: damage vehicle/body/training/00front/0012.jpeg inflating: damage vehicle/body/training/00-front/0013.JPEG inflating: damage vehicle/body/training/00front/0014.JPEG inflating: damage vehicle/body/training/00-front/0015.JPEG inflating: damage vehicle/body/training/00front/0016.JPEG inflating: damage

vehicle/body/training/00-front/0017 IPEG

inflating: damage vehicle/body/training/00front/0018.JPEG inflating: damage vehicle/body/training/00-front/0019.JPEG inflating: damage vehicle/body/training/00front/0020.jpeg inflating: damage vehicle/body/training/00-front/0021.JPEG inflating: damage vehicle/body/training/00front/0022.JPEG inflating: damage vehicle/body/training/00-front/0023.JPEG inflating: damage vehicle/body/training/00front/0024.JPEG inflating: damage vehicle/body/training/00-front/0025.jpeg inflating: damage vehicle/body/training/00front/0026.JPEG inflating: damage vehicle/body/training/00-front/0027.JPEG inflating: damage vehicle/body/training/00front/0028.JPEG inflating: damage vehicle/body/training/00-front/0029.JPEG inflating: damage vehicle/body/training/00front/0030.JPEG inflating: damage vehicle/body/training/00-front/0031.JPEG inflating: damage vehicle/body/training/00front/0032.JPEG inflating: damage vehicle/body/training/00-front/0033.JPEG inflating: damage vehicle/body/training/00front/0034.JPEG inflating: damage vehicle/body/training/00-front/0035.jpeg inflating: damage vehicle/body/training/00front/0036.JPEG inflating: damage vehicle/body/training/00-front/0037.JPEG inflating: damage vehicle/body/training/00front/0038.JPEG inflating: damage vehicle/body/training/00-front/0039.JPEG inflating: damage vehicle/body/training/00front/0040.JPEG inflating: damage vehicle/body/training/00-front/0041.JPEG inflating: damage vehicle/body/training/00front/0042.JPEG inflating: damage vehicle/body/training/00-front/0043.JPEG inflating: damage vehicle/body/training/00front/0044.JPEG inflating: damage vehicle/body/training/00-front/0045.JPEG inflating: damage vehicle/body/training/00front/0046.jpeg inflating: damage vehicle/body/training/00-front/0047.JPEG inflating: damage vehicle/body/training/00front/0048.JPEG inflating: damage vehicle/body/training/00-front/0049.JPEG inflating: damage vehicle/body/training/00front/0050.JPEG inflating: damage vehicle/body/training/00-front/0051.JPEG inflating: damage vehicle/body/training/00front/0052.JPEG inflating: damage vehicle/body/training/00-front/0053.JPEG



```
from tensorflow.keras.preprocessing.image import ImageDataGenerator
  2. Configure ImageDataGenerator Class
  #Creating augmentation on training variable
  train_datagen =
  ImageDataGenerator(rescale=1./255,
  shear_range = 0.1, zoom_range=0.1,
  horizontal_flip=True)
  # Creating augmentation on testing variable
  test_datagen = ImageDataGenerator(rescale=1./255)
  3. Apply ImageDataGenerator Functionality To Trainset And Testset
  # Passing training data to train variable for body
  xtrain = train_datagen.flow_from_directory('/content/damage vehicle/body/training',
                                      target_size=(224,224),
                                      class mode='categorical',
                                      batch_size=10)
      Found 979 images belonging to 3
classes.
  # Passing testing data to test variable for body
  xtest = test_datagen.flow_from_directory('/content/damage vehicle/body/validation',
                                    target_size=(224,224),
                                    class_mode='categorical',
                                    batch size=10)
      Found 171 images belonging to 3
classes.
  # Passing training data to train variable for level
  x_train = train_datagen.flow_from_directory('/content/damage vehicle/level/training',
                                      target_size=(224,224),
                                      class_mode='categorical',
                                      batch size=10)
      Found 979 images belonging to 3
 classes.
  # Passing testing data to test variable for level
  x_test = test_datagen.flow_from_directory('/content/damage vehicle/level/validation',
                                    target_size=(224,224),
                                    class_mode='categorical',
                                    batch_size=10)
      Found 171 images belonging to 3
classes.
```

```
Model Building
→ For Body
  1. Importing The Model Building Libraries
  #Import the library
  from tensorflow.keras.layers import Dense, Flatten, Input
  from tensorflow.keras.models import Model
  from tensorflow.keras.preprocessing import image
  from\ tensorflow. keras. preprocessing. image\ import\ ImageDataGenerator,\ load\_img
  from tensorflow.keras.applications.vgg16 import VGG16, preprocess_input
  from glob import glob
  import numpy as np
  import matplotlib.pyplot as plt
  import tensorflow as tf
  from tensorflow.keras.layers import Input, Lambda,
  Dense, Flatten from tensorflow.keras.models import
  Model
  from tensorflow.keras.applications.vgg16
  import VGG16 from
  tensorflow.keras.applications.vgg19 import
  VGG19 from tensorflow.keras.preprocessing
  import image
  from tensorflow.keras.preprocessing.image import
  ImageDataGenerator,load_img from tensorflow.keras.models
  import Sequential import numpy as np from glob import glob
  2. Loading The Model
  IMAGE\_SIZE = [224, 224]
  train_path = '/content/damage vehicle/body/training'
  valid_path = '/content/damage
  vehicle/body/validation'
  vgg16 = VGG16(input_shape=IMAGE_SIZE + [3], weights='imagenet', include_top=False)
       Downloading data from <a href="https://storage.googleapis.com/tensorflow/keras-">https://storage.googleapis.com/tensorflow/keras-</a>
       applications/vgg16/vgg16_weights_tf_dim_ordering_tf_ke 58889256/58889256
                                                 ====] - 3s Ous/step
  3. Adding Flatten Layer
  for layer in vgg16.layers:
      layer.trainable = False
```

```
folders = glob('/content/damage vehicle/body/training/*')
folders
    ['/content/damage vehicle/body/training/00-front',
     '/content/damage vehicle/body/training/01-rear',
     '/content/damage vehicle/body/training/02-side']
x = Flatten()(vgg16.output)
len(folders)
    3
4. Adding Output Layer
prediction = Dense(len(folders), activation='softmax')(x)
5. Creating A Model Object
model = Model(inputs=vgg16.input, outputs=prediction)
model.summary()
    Model: "model"
    Layer (type) Output Shape Param #
     input_1 (InputLayer) [(None, 224, 224, 3)] 0
     block1_conv1 (Conv2D)
                                 (None, 224,
                                               1792
     224, 64)
     block1_conv2 (Conv2D)
                                 (None, 224,
                                               36928
     224, 64)
     block1_pool (MaxPooling2D) (None, 112, 0
     112, 64)
     block2_conv1 (Conv2D)
                                 (None, 112,
     112, 128)
                                               73856
                                 (None, 112, 112, 128)
     block2_conv2 (Conv2D)
                                                              147584
     block2_pool (MaxPooling2D) (None, 56, 0
     56, 128)
     block3_conv1 (Conv2D)
                                 (None, 56,
                                              295168
     56, 256)
```

```
block3_conv2 (Conv2D)
                                (None, 56,
                                             590080
     56, 256)
     block3_conv3 (Conv2D)
                                (None, 56,
                                             590080
     56, 256)
     block3_pool (MaxPooling2D) (None, 28,
                                             0
     28, 256)
    block4_conv1 (Conv2D)
                                (None, 28,
                                             1180160
     28, 512)
     block4_conv2 (Conv2D)
                                (None, 28,
                                             2359808
     28, 512)
     block4_conv3 (Conv2D)
                                (None, 28,
                                             2359808
     28, 512)
     block4_pool (MaxPooling2D) (None, 14,
     14, 512)
     block5_conv1 (Conv2D)
                                (None, 14,
                                             2359808
     14, 512)
    block5_conv2 (Conv2D)
                                (None, 14,
                                             2359808
     14, 512)
    block5_conv3 (Conv2D)
                                (None,
                                             2359808
    14, 14, 512)
    block5_pool (MaxPooling2D) (None, 7, 7, 0
     512)
                          flatten (Flatten)
           (None, 25088)
                                             0
     dense (Dense)
                         (None, 3)
                                             75267
                          ===== Total params: 14,789,955
    Trainable params: 75,267
    Non-trainable params: 14,714,688
6. Configure The Learning Process
model.compile(
 loss='categorical_crossentropy',
 optimizer='adam',
 metrics=['accuracy']
7. Train The Model
r = model.fit_generator(
 xtrain,
 validation_data=xtest,
 epochs=25,
```

```
steps_per_epoch=len(xtrain),
validation_steps=len(xtest)
)
 /usr/local/lib/python3.7/dist-packages/ipykernel launcher.py:6: UserWarning: `Model.fit generator` is
 deprecated and will be
 Epoch 1/25
 val loss: 1.2900 - val accuracy:
 Epoch 2/25
 val_loss: 0.8665 - val_accuracy:
 Epoch 3/25
 val_loss: 1.3260 - val_accuracy:
 Epoch 4/25
 val_loss: 0.9842 - val_accuracy:
 Epoch 5/25
 val_loss: 0.9397 - val_accuracy:
 Epoch 6/25
 val_loss: 0.9892 - val_accuracy:
 Epoch 7/25
 val_loss: 1.0052 - val_accuracy:
 Epoch 8/25
 val_loss: 1.1693 - val_accuracy:
 Epoch 9/25
 val_loss: 1.0058 - val_accuracy:
 Epoch 10/25
 98/98 [===========
                =======] - 13s 128ms/step - loss: 0.1184 - accuracy: 0.9591 -
 val_loss: 1.0620 - val_accuracy:
 Epoch 11/25
 val_loss: 1.1219 - val_accuracy:
 Epoch 12/25
 val_loss: 1.0284 - val_accuracy:
 Epoch 13/25
 val_loss: 1.1153 - val_accuracy:
 Epoch 14/25
 val_loss: 1.1033 - val_accuracy:
 Epoch 15/25
```

```
val_loss: 1.0730 - val_accuracy:
  Epoch 16/25
  val_loss: 1.1225 - val_accuracy:
  Epoch 17/25
  98/98 [======
                        ======] - 13s 129ms/step - loss: 0.0609 - accuracy: 0.9918 -
  val_loss: 1.2937 - val_accuracy:
  Epoch 18/25
  98/98 [======
                      =======] - 13s 128ms/step - loss: 0.0998 - accuracy: 0.9714 -
  val_loss: 1.1754 - val_accuracy:
  Epoch 19/25
  98/98 [======
                        ======] - 13s 128ms/step - loss: 0.0728 - accuracy: 0.9847 -
  val_loss: 1.5074 - val_accuracy:
  Epoch 20/25
  98/98 [=======
                      =======] - 13s 129ms/step - loss: 0.0972 - accuracy: 0.9714 -
  val_loss: 1.4684 - val_accuracy:
  Epoch 21/25
  val_loss: 1.4215 - val_accuracy:
  Epoch 22/25
  val_loss: 1.4772 - val_accuracy:
  Epoch 23/25
  val_loss: 1.4306 - val_accuracy:
  Epoch 24/25
  val_loss: 1.4562 - val_accuracy:
  Epoch 25/25
  98/98 [=====
                        =======] - 13s 129ms/step - loss: 0.1692 - accuracy: 0.9387 -
  val_loss: 1.6805 - val_accuracy:
8. Save The Model
from tensorflow.keras.models import load model
model.save('/content/damage vehicle/Model/body.h5')
```

9. Test The Model

from tensorflow.keras.models import load_model import cv2

from skimage.transform import resize

model = load_model('/content/damage vehicle/Model/body.h5')

```
def detect(frame):
  img = cv2.resize(frame,(224,224))
  img = cv2.cvtColor(img,cv2.COLOR_BGR2RGB)
  if(np.max(img)>1):
    img = img/255.0
  img = np.array([img])
  prediction = model.predict(img)
  label = ["front","rear","side"]
  preds =
  label[np.argmax(prediction)]
  return preds
import numpy as np
data = "/content/damage vehicle/body/training/00-
front/0002.JPEG" image = cv2.imread(data)
print(detect(image))
    1/1 [======
    - 0s 148ms/step front
Model Building
For Level
1. Importing The Model Building Libraries B
import tensorflow as tf
from tensorflow.keras.layers import Input, Lambda,
Dense, Flatten from tensorflow.keras.models import
Model from tensorflow.keras.applications.vgg16
import VGG16 from
tensorflow.keras.applications.vgg19 import VGG19
from tensorflow.keras.preprocessing import image
from tensorflow.keras.preprocessing.image import
ImageDataGenerator,load_img from tensorflow.keras.models
import Sequential import numpy as np from glob import glob
2. Loading The Model
IMAGE\_SIZE = [224, 224]
train_path = '/content/damage vehicle/level/training'
valid_path = '/content/damage
vehicle/level/validation'
```

```
vgg16 = VGG16(input_shape=IMAGE_SIZE + [3], weights='imagenet', include_top=False)
3. Adding Flatten Layer
for layer in vgg16.layers:
   layer.trainable = False
folders = glob('/content/damage vehicle/level/training/*')
folders
    ['/content/damage vehicle/level/training/03-severe',
     '/content/damage vehicle/level/training/02-moderate',
     '/content/damage vehicle/level/training/01-minor']
x = Flatten()(vgg16.output)
len(folders)
    3
4. Adding Output Layer
prediction = Dense(len(folders), activation='softmax')(x)
5. Creating A Model Object
model = Model(inputs=vgg16.input, outputs=prediction)
model.summary()
    Model: "model_1"
     Layer (type) Output Shape Param #
     input_2 (InputLayer) [(None, 224, 224, 3)]0
     block1_conv1 (Conv2D)
                                  (None, 224,
     224, 64)
                                 (None, 224, 36928
     block1_conv2 (Conv2D)
     224, 64)
     block1_pool (MaxPooling2D) (None, 112, 0
     112, 64)
```

block2_conv1 (Conv2D) 112, 128)	(None, 112,	73856
block2_conv2 (Conv2D)	(None, 112,	
112, 128)		147584
block2_pool (MaxPooling2 56, 128)	D) (None, 56,	0
block3_conv1 (Conv2D) 56, 256)	(None, 56,	295168
block3_conv2 (Conv2D) 56, 256)	(None, 56,	590080
block3_conv3 (Conv2D) 56, 256)	(None, 56,	590080
block3_pool (MaxPooling2 28, 256)	D) (None, 28,	0
block4_conv1 (Conv2D) 28, 512)	(None, 28,	1180160
block4_conv2 (Conv2D) 28, 512)	(None, 28,	2359808
block4_conv3 (Conv2D) 28, 512)	(None, 28,	2359808
block4_pool (MaxPooling2 14, 512)	(D) (None, 14,	0
block5_conv1 (Conv2D) 14, 512)	(None, 14,	2359808
block5_conv2 (Conv2D) 14, 512)	(None, 14,	2359808
block5_conv3 (Conv2D) 14, 14, 512)	(None,	2359808
block5_pool (MaxPooling2 512)	(D) (None, 7, 7,	, 0
flatten 1 (Flatten)		0
dense_1 (Dense) (None, 3)		75267

Total params: 14,789,955 Trainable params: 75,267

Non-trainable params: 14,714,688

6. Configure The Learning Process

model.compile(

loss='categorical_crossentropy',

```
optimizer='adam',
metrics=['accuracy']
7. Train The Model
r = model.fit_generator(
x_train,
validation_data=x_test,
epochs=25,
steps_per_epoch=len(x_train),
validation_steps=len(x_test)
)
 /usr/local/lib/python3.7/dist-packages/ipykernel_launcher.py:6: UserWarning: `Model.fit_generator` is
  deprecated and will be
 Epoch 1/25
  val_loss: 1.1559 - val_accuracy:
  Epoch 2/25
  val_loss: 0.9643 - val_accuracy:
  Epoch 3/25
  val_loss: 1.5663 - val_accuracy:
  Epoch 4/25
  98/98 [=====
                  =======] - 13s 128ms/step - loss: 0.5277 - accuracy: 0.7865 -
  val_loss: 1.6003 - val_accuracy:
  Epoch 5/25
  val_loss: 1.1925 - val_accuracy:
  Epoch 6/25
  val loss: 1.0354 - val accuracy:
  Epoch 7/25
  val_loss: 1.2155 - val_accuracy:
  Epoch 8/25
  val_loss: 1.0902 - val_accuracy:
  Epoch 9/25
  val_loss: 1.1282 - val_accuracy:
  Epoch 10/25
  val_loss: 1.1311 - val_accuracy:
  Epoch 11/25
  val_loss: 1.1538 - val_accuracy:
```

```
Epoch 12/25
val_loss: 1.2209 - val_accuracy:
Epoch 13/25
val_loss: 1.2545 - val_accuracy:
Epoch 14/25
val_loss: 1.1609 - val_accuracy:
Epoch 15/25
val_loss: 1.1688 - val_accuracy:
Epoch 16/25
val_loss: 1.1850 - val_accuracy:
Epoch 17/25
val_loss: 1.1884 - val_accuracy:
Epoch 18/25
val_loss: 1.2897 - val_accuracy:
Epoch 19/25
val_loss: 1.2499 - val_accuracy:
Epoch 20/25
val_loss: 1.2801 - val_accuracy:
Epoch 21/25
val_loss: 1.2366 - val_accuracy:
Epoch 22/25
val_loss: 1.2901 - val_accuracy:
Epoch 23/25
val_loss: 1.2697 - val_accuracy:
Epoch 24/25
val_loss: 1.4214 - val_accuracy:
Epoch 25/25
val_loss: 1.4219 - val_accuracy:
```

8. Save The Model

from tensorflow.keras.models import load_model

```
model.save('/content/damage vehicle/Model/level.h5')
9. Test The Model
from tensorflow.keras.models import
load_model import cv2
from skimage.transform import resize
model = load_model('/content/damage vehicle/Model/level.h5')
def detect(frame):
  img = cv2.resize(frame,(224,224))
  img = cv2.cvtColor(img,cv2.COLOR_BGR2RGB)
  if(np.max(img)>1):
    img = img/255.0
  img = np.array([img])
  prediction =
  model.predict(img) label =
  ["minor","moderate","severe"]
  preds =
  label[np.argmax(prediction)]
  return preds
import numpy as np
data = "/content/damage vehicle/level/validation/01-
minor/0005.JPEG" image = cv2.imread(data)
print(detect(image))
    - 0s 142ms/step minor
```

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