EMERGING METHODS FOR EARLY DETECTION OF FOREST FIRES

VIDEO ANALYSIS

OPEN CV FOR VIDEO PROCESSING

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Project Name	Emerging Methods for Early Detection of Forest Fires

Importing The ImageDataGenerator Library import keras from keras.preprocessing.image import ImageDataGenerator Define the parameters/arguments for ImageDataGenerator class train_datagen=ImageDataGenerator(rescale=1./255,shear_range=0.2,rot ati on_range=180,zoom_range=0.2, horizontal_flip=True) test_datagen=ImageDataGenerator(rescale=1./255) Applying ImageDataGenerator functionality to trainset x_train=train_datagen.flow_from_directory(r'/content/drive/MyDri

```
v e/ Dataset/train set', target size=(128,128), batch size=32,
class mode='binary')
Found 436 images belonging to 2 classes.
Applying ImageDataGenerator functionality to testset
x test=test datagen.flow from directory(r'/content/drive/MyDrive
/ Dataset/test set', target size=(128,128), batch size=32,
class mode='binary')
Found 121 images belonging to 2 classes.
Import model building libraries
#To define Linear initialisation import Sequential
from keras.models import Sequential #To add
layers import Dense from keras.layers import
Dense
#To create Convolution kernel import Convolution2D
from keras.layers import Convolution2D
#import Maxpooling layer
from keras.layers import MaxPooling2D
#import flatten layer from
keras.layers import Flatten
import warnings
warnings.filterwarnings('ignore'
```

Initializing the model

model=Sequential()

Add CNN Layer

```
model.add(Convolution2D(32, (3,3),input shape=(128,128,3),activation='relu'))
```

```
#add maxpooling layer
```

```
model.add(MaxPooling2D(pool size=(2,2)))
#add flatten layer
model.add(Flatten()) Add Hidden
Layer
#add hidden layer model.add(Dense(150,activation='relu'))
#add output layer
model.add(Dense(1,activation='sigmoid')
Configure the learning process
model.compile(loss='binary crossentropy',optimizer="adam",metrics=["
ac curacy"])
Train
                            the
                                                      model
model.fit generator(x train, steps per epoch=14, epochs=10, validati
on da ta=x test, validation steps=4)
Epoch 1/10
14/14 [======] - 97s 7s/step - loss:
1.3060 - accuracy: 0.7775 - val loss: 0.5513 -
val accuracy: 0.8512
Epoch 2/10
14/14 [======] - 26s 2s/step - loss:
0.3178 - accuracy: 0.8807 - val loss: 0.1299 -
val accuracy: 0.9421
Epoch 3/10
14/14 [======] - 26s 2s/step - loss:
0.2226 - accuracy: 0.9106 - val loss: 0.1311 -
val accuracy: 0.9421
Epoch 4/10
```

14/14 [======] - 31s 2s/step - loss:

```
0.1836 - accuracy: 0.9174 - val_loss: 0.1129 -
 val accuracy: 0.9339
 Epoch 5/10
 14/14 [======] - 30s 2s/step - loss:
 0.1675 -
 accuracy: 0.9243 - val loss: 0.0925 - val accuracy: 0.9669
 Epoch 6/10
 14/14 [=======] - 26s 2s/step - loss:
 0.1884 - accuracy: 0.9289 - val loss: 0.1287 -
 val accuracy: 0.9339
 Epoch 7/10
 14/14 [======] - 28s 2s/step - loss:
 0.1724 - accuracy: 0.9335 - val loss: 0.0926 -
 val accuracy: 0.9752
 Epoch 8/10
 14/14 [=====] - 26s 2s/step - loss:
 0.1510 - accuracy: 0.9404 - val loss: 0.0757 -
 val accuracy: 0.9752 Epoch 9/10
14/14 [=======] - 26s
                                                    0.173 -
2s/step - loss:
                                                     2
accuracy: 0.9174 - val loss: 0.0537 - val_accuracy: 0.9835
Epoch 10/10
14/14 [======] - 26s
                                                    0.154 -
2s/step - loss:
                                                     6
 accuracy: 0.9312 - val loss: 0.0573 - val accuracy: 0.9835
 <keras.callbacks.History at 0x7f05d66a9c90>
```

Save The Model

model.save("forest1.h5")

Predictions

```
#import load model
from keras.model from
 keras.models import
load model #import
 image class from keras
from tensorflow.keras.preprocessing import image #import
 numpy import numpy as np #import cv2 import cv2
 #load the saved model model =
 load model("forest1.h5")
 img=image.load img(r'/content/drive/MyDrive/Dataset/
te st set/forest/
 0.48007200 1530881924 final forest.jpg')
 x=image.img to array(img) res =
 cv2.resize(x, dsize=(128, 128),
 interpolation=cv2.INTER CUBIC)
 #expand the image shape
 x=np.expand di ms(res,axis=0)
 pred= model.predict(x)
 1/1 [=====
 126ms/step pred
 array([[0.]],
dtype=float32) OpenCV
 For Video Processing
pip install twilio
Looking in indexes: https://pypi.org/simple, https://us-
python.pkg.dev/colab-wheels/public/simple/
Requirement already satisfied: twilio in
/usr/local/lib/python3.7/dist-packages (7.15.1)
```

Requirement already satisfied: pytz in /usr/local/lib/python3.7/distpackages (from twilio) (2022.5) Requirement already satisfied: requests>=2.0.0 in /usr/local/lib/python3.7/dist-packages (from twilio) (2.23.0) Requirement already satisfied: PyJWT<3.0.0,>=2.0.0 in /usr/local/lib/python3.7/dist-packages (from twilio) (2.6.0) Requirement satisfied: urllib3!=1.25.0,!=1.25.1,<1.26,>=1.21.1 already /usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio) (1.24.3)Requirement already satisfied: certifi>=2017.4.17 in /usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio) (2022.9.24)Requirement already satisfied: idna<3,>=2.5 in /usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio) (2.10)Requirement already satisfied: chardet<4,>=3.0.2 in /usr/local/lib/python3.7/dist-packages (from requests>=2.0.0->twilio) (3.0.4)pip install playsound Looking in indexes: https://pypi.org/simple, https://uspython.pkg.dev/colab-wheels/public/simple/ Requirement already satisfied: playsound in /usr/local/lib/python3.7/dist-packages (1.3.0) #import opency library import cv2 #import *numpy* import numpy as np

image #import load_model from keras
from keras.models import load_model
#import client from twilio API from
twilio.rest import Client

#import image function from keras
from keras.preprocessing import

#import playsound package from playsound import playsound

WARNING:playsound:playsound is relying on another python subprocess. Please use 'pip install pygobject' if you want playsound to run more efficiently.

#load the saved model
model=load_model("forest1.h
5") #define video
video=cv2.VideoCapture(0) #define
the features name=['forest','with
fire']