ASSIGNMENT – IV

TEAM ID: PNT2022TMID07804

Write code and connections in wokwi for ultrasonic sensors.

Whenever distance is less than 100cms send "alert" to ibm cloud and display device recent events.

Code:

```
#include  <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "4yi0vc"
#define DEVICE_TYPE "nodeMcu"
#define DEVICE_ID "Assignment4"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char  authMethod[]  = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
const int echopin=18;
String command;
String data="";


long duration;
float dist;
```

```
void setup()
{
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}

void loop() {
  bool isNearby = dist < 100;
  digitalWrite(led,  isNearby);
  publishData();
  delay(500);
if (!client.loop()) {
    mqttConnect();
  }
}

void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() {
  if (!client.connected()) {
```

```
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
    Serial.print(".");
      delay(500);
    }
    initManagedDevice();
    Serial.println();
  }
}

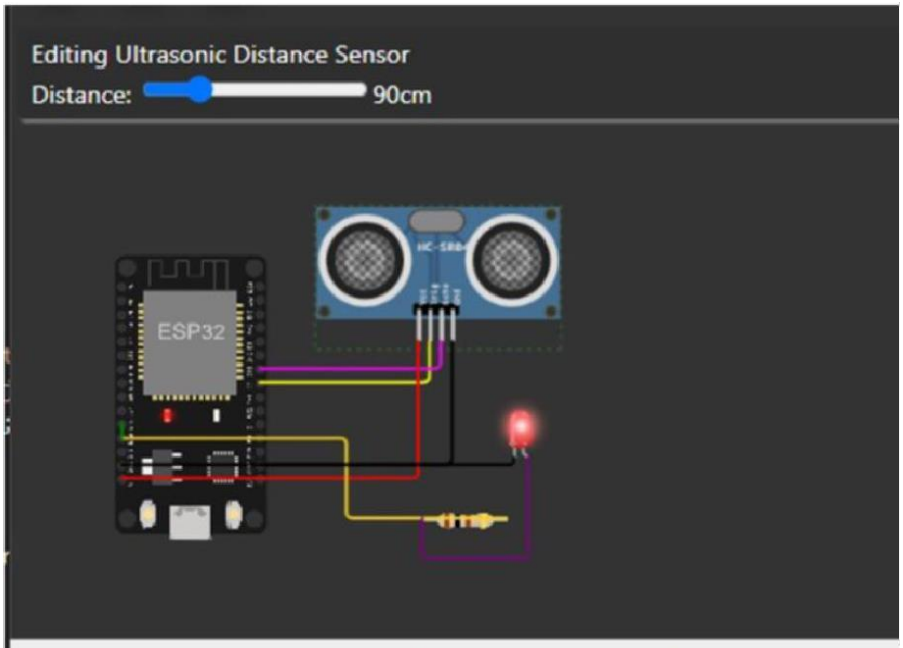
void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
    Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void publishData()
{
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin,HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin,HIGH);
  dist=duration*speed/2;
  if(dist<100){
    String payload = "{\"Normal Distance\":";
    payload += dist;
    payload += "}";
    Serial.print("\n");
```

```
 Serial.print("Sending payload: ");
 Serial.println(payload);
 if (client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish OK");
 }
 }
 if(dist>101 && dist<111){
 String payload = "{\"Alert distance\":";
 payload += dist;
 payload +=  "}";
 Serial.print("\n");
 Serial.print("Sending payload: ");
 Serial.println(payload);
  if(client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
   digitalWrite(led,HIGH);
 }else {
   Serial.println("Publish FAILED");
 }
  }
}
void callback(char* subscribeTopic, byte* payload, unsigned int payloadLength){
Serial.print("callback invoked for topic:");
Serial.println(subscribeTopic);
for(int i=0; i<payloadLength; i++){
dist += (char)payload[i];
}
Serial.println("data:"+ data3);
if(data3=="lighton"){
Serial.println(data3);
digitalWrite(led,HIGH);
```

```
  }
  data3="";
}
```

Output :

1) **When Distance < 100 cm, it will show normal distance.**




```
Sending payload: {"Normal Distance":89.95}
Publish OK

Sending payload: {"Normal Distance":89.95}
Publish OK

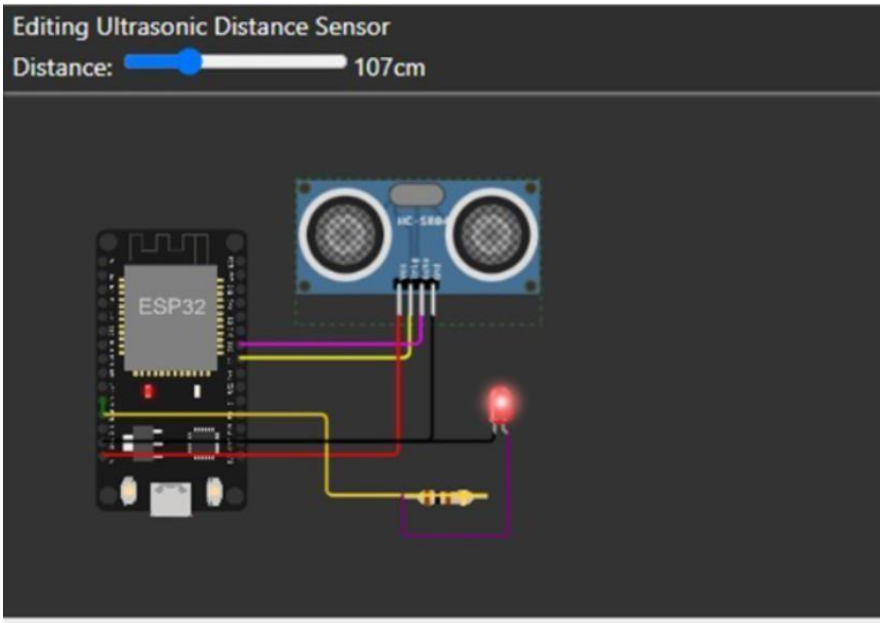
Sending payload: {"Normal Distance":89.95}
Publish OK

Sending payload: {"Normal Distance":89.98}
Publish OK

Sending payload: {"Normal Distance":89.95}
Publish OK

Sending payload: {"Normal Distance":89.95}
Publish OK
```

2)When distance > 100cm <110cm, alert with warning message occurs.




```
Sending payload: {"Alert distance":106.98}
Warning crosses 110cm -- it automaticaly of the loop

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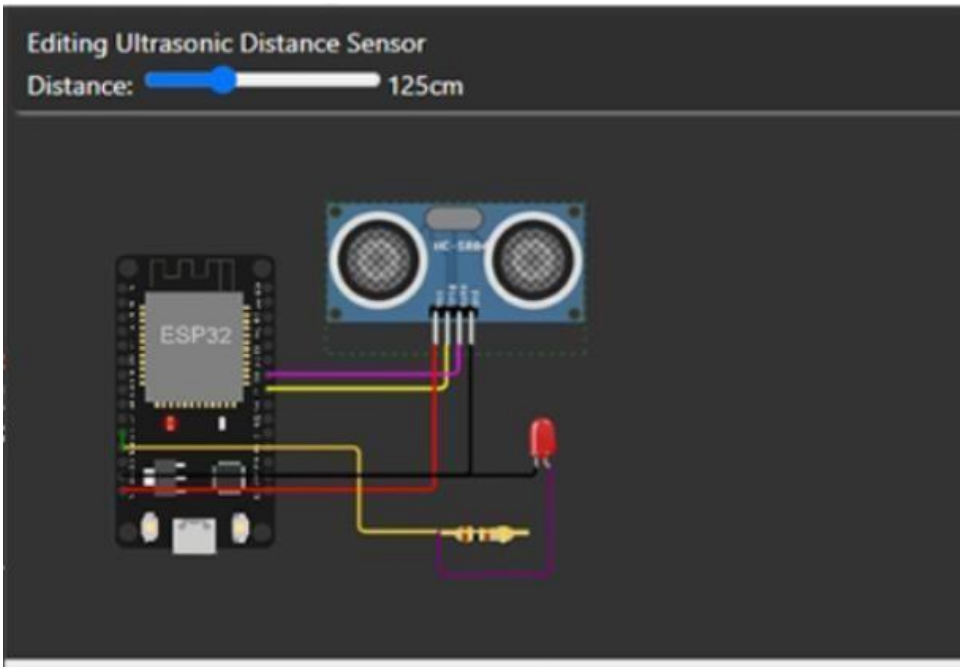
```

3)When distance>110cm, totally moves to iff state.

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Warning crosses 110cm -- it automaticaly of the loop
```

IBM Cloud Output:

Recent Events

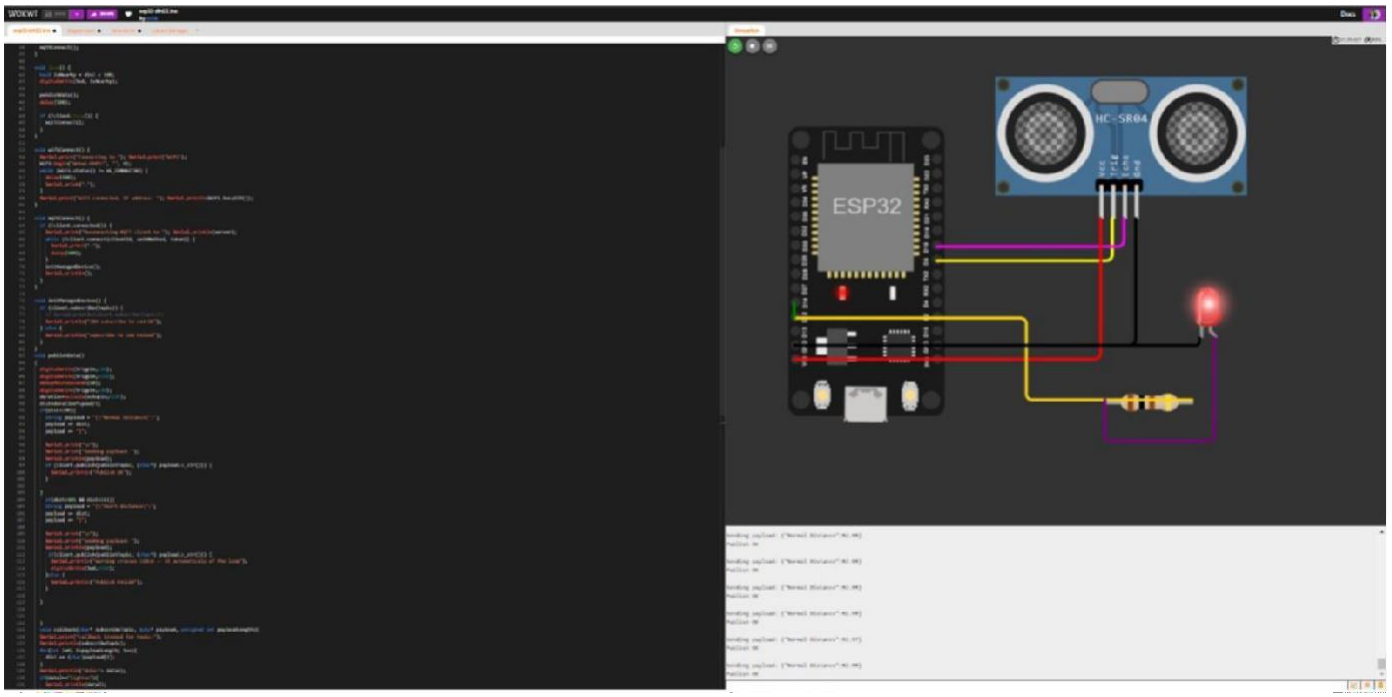
The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	{"Normal Distance":89.95}	json	a few seconds ago
Data	{"Normal Distance":89.95}	json	a few seconds ago
Data	{"Normal Distance":89.95}	json	a few seconds ago
Data	{"Normal Distance":89.95}	json	a few seconds ago
Data	{"Normal Distance":89.95}	json	a few seconds ago

Recent Events

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	{"Alert distance":106.98}	json	a few seconds ago
Data	{"Alert distance":107.03}	json	a few seconds ago
Data	{"Alert distance":106.98}	json	a few seconds ago
Data	{"Alert distance":106.98}	json	a few seconds ago
Data	{"Alert distance":106.98}	json	a few seconds ago



Recent Events

The recent events listed show the live stream of data that is coming and going from this device.

Event	Value	Format	Last Received
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago
Data	{"Normal Distance":92.99}	json	a few seconds ago