ASSIGNMENT-4

Date	28October2022
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MaximumMarks	2 Marks

Question1:

Write code and connections in work for ultrasonic sensor. Whenever distance is lessthan

100cmssend"alert"toibmcloudanddisplayindevicerecentevents.

```
#include <PubSubClient.h>//library for MQtt
#define ORG "4hn@jp"//IBM ORGANITION ID
#define DEVICE_TYPE "ULTRASON"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "DISTANCEDETECT"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "wuo5s7PR)ZSegVk&Rx"//Token
String data3;
float dist;
//------ Customise the above values ------

char server[] = ORG ".messaging.internetofthings.ibmcloud.com";// Server Name

char publishTopic[] = "iot-2/evt/Data/fmt/json";// topic name and type of event perform and format in which data to be send

char subscribetopic[] = "iot-2/cmd/test/fmt/String";// cmd REPRESENT command type AND COMMAND IS TEST OF FORMAT STRING

char authwethod[] = "use-token-auth";// authentication method

char token[] = TOKEH;

char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;//client id
   Wificlient wificlient; // creating the instance for wificlient
PubSubClient client(server, 1883, callback ,wificlient); //calling the predefined client id by passing parameter like server id,portand wificredential
  int trig = 5;
int echo = 18;
```

```
esp32-blink.ino
                 diagram.json •
                                   libraries.txt •
                                                 Library Manager *
       pinMode(trig,OUTPUT);
       pinMode(echo,INPUT);
       pinMode(LED, OUTPUT);
       delay(10);
       wificonnect();
       mqttconnect();
       void loop()// Recursive Function
        digitalWrite(trig,LOW);
         digitalWrite(trig,HIGH);
         delayMicroseconds(10);
         digitalWrite(trig,LOW);
         float dur = pulseIn(echo,HIGH);
         float dist = (dur * 0.0343)/2;
         Serial.print ("Distancein cm");
         Serial.println(dist);
         PublishData(dist);
         delay(1000);
         if (!client.loop()) {
           mqttconnect();
       void PublishData(float dist) {
         mqttconnect();//function call for connecting to ibm
```

```
| creating the String in in form JSon to update the data to ibm cloud
| '/'
| String object;
| if (dist <100) |
| digitalWrite(LED,HIGH);
| Serial.println("object is near");
| object = "Near";
| }
| else | {
| digitalWrite(LED,LOW);
| Serial.println("no object found");
| object = "No";
| 84 | }
| String payload = "{\"distance\":";
| payload += dist;
| payload += dist;
| payload += "\"";
| payload += object;
| payload += "\"";
| payload += "\"";
| Serial.print("sending payload: ");
| Serial.println(payload);
```

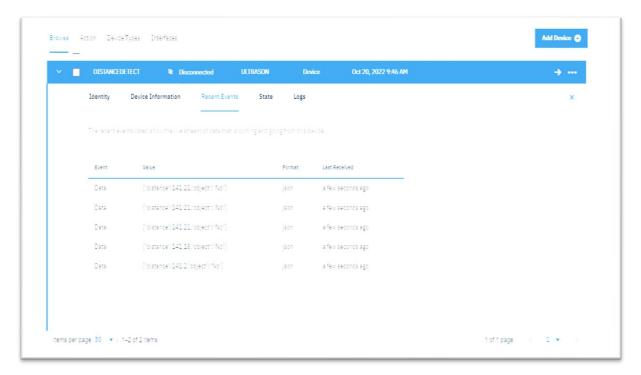
```
esp32-blink.ino •
                   diagram.json •
                                    libraries.txt •
                                                    Library Manager
          WiFi.begin("Wokwi-GUEST", "", 6);//passing the wifi credentials to establish the connection
          while (WiFi.status() != WL CONNECTED) {
            delay(500);
            Serial.print(".");
         Serial.println("");
Serial.println("WiFi connected");
          Serial.println("IP address: ");
         Serial.println(WiFi.localIP());
        void initManagedDevice() {
         if (client.subscribe(subscribetopic)) {
            Serial.println((subscribetopic));
            Serial.println("subscribe to cmd OK");
           Serial.println("subscribe to cmd FAILED");
       void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
          Serial.print("callback invoked for topic: ");
 148
          Serial.println(subscribetopic);
          for (int i = 0; i < payloadLength; i++) {</pre>
            data3 += (char)payload[i];
```

```
esp32-blink.Ino diagram.json libraries.bt Library Manager void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)

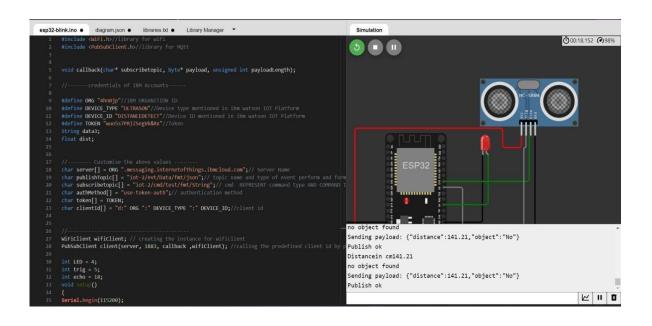
| Void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)

| Serial.print("callback invoked for topic: ");
| Serial.println(subscribetopic);
| for (int i = 0; i < payloadLength; i++) {
| //Serial.println((char)payload[i]);
| data3 += (char)payload[i];
| // //Serial.println("data: "+ data3);
| // serial.println("data: "+ data3);
| // serial.println(data3);
| // serial.println(data3);
| // serial.println(data3);
| // else
| // else
| // else
| // serial.println(data3);
| // digitalwrite(LED,LOW);
| // digitalwrite(LED,LOW);
| // digitalwrite(LED,LOW);
| // digitalwrite(LED,LOW);
| // else
| // // else
| //
```

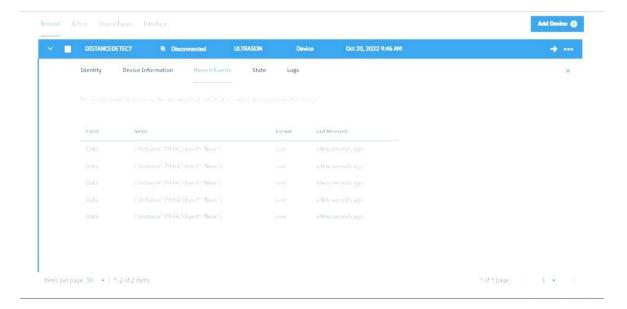
OUTPUT:



DatasendtotheIBMclouddevicewhentheobjecticsfar



Datas ent to the IBMC loud Device when the object is near



Whenobjecticsneartotheultrasonicsensor

