Assignment -4

Assignment Date	29 October 2022	
Student Name	Jasmine S	
Student Roll Number	910419104006	
Maximum Marks	2 Marks	

Question-1:

Write code and connections in wokwi for ultrasonic sensors. Whenever distance is less than 100 cms send alert to ibm cloud & display in device recent events. Upload document with wokwi share link and images of ibm colud.

Solution:

```
#include <WiFi.h>
#include < PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "87tg7u"
#define DEVICE_TYPE "Jasmine"
#define DEVICE_ID "Jasmine123"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Jas/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
```

const int trigpin=5;

```
const int echopin=18;
String command;
String data="";
long duration;
float dist;
void setup()
{
Serial.begin(115200);
 pinMode(led, OUTPUT);
 pinMode(trigpin, OUTPUT);
 pinMode(echopin, INPUT);
wifiConnect();
mqttConnect();
}
void loop() {
bool isNearby = dist < 100;
digitalWrite(led, isNearby);
 publishData();
 delay(500);
 if (!client.loop()) {
  mqttConnect();
}
}
```

```
void wifiConnect() {
 Serial.print("Connecting to "); Serial.print("Wifi");
 WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() != WL_CONNECTED) {
  delay(500);
  Serial.print(".");
 }
 Serial.print("WiFi connected, IP address: "); Serial.println(WiFi.localIP());
}
void mqttConnect() {
 if (!client.connected()) {
  Serial.print("Reconnecting MQTT client to "); Serial.println(server);
  while (!client.connect(clientId, authMethod, token)) {
   Serial.print(".");
   delay(500);
  }
  initManagedDevice();
  Serial.println();
 }
}
void initManagedDevice() {
 if (client.subscribe(topic)) {
  // Serial.println(client.subscribe(topic));
  Serial.println("IBM subscribe to cmd OK");
 } else {
  Serial.println("subscribe to cmd FAILED");
 }
}
void publishData()
```

```
{
 digitalWrite(trigpin,LOW);
 digitalWrite(trigpin,HIGH);
 delayMicroseconds(10);
 digitalWrite(trigpin,LOW);
 duration=pulseIn(echopin,HIGH);
 dist=duration*speed/2;
 if(dist<100){
  String payload = "{\"Normal Distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish OK");
  }
 }
  if(dist>101 && dist<111){
  String payload = "{\"Alert distance\":";
  payload += dist;
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
   if(client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
   digitalWrite(led,HIGH);
```

```
}else {
    Serial.println("Publish FAILED");
}
```

Output:



