## **Assignment -4**

Assignment Date	25 October 2022
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Maximum Marks	2 Marks

## Question-1:

Write code and connections in wokwi for ultrasonic sensors. Whenever distance is less than 100 cms send alert to ibm cloud & display in device recent events. Upload document with wokwi share link and images of ibm colud.

## Solution:

```
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
String data3;
#define ORG "ldetbq"
#define DEVICE_TYPE "Raja"
#define DEVICE_ID "Raja123"
#define TOKEN "123456789"
#define speed 0.034
#define led 14
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Raja/fmt/json";
char topic[] = "iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=5;
const int echopin=18;
String command;
String data="";
long duration;
float dist;
```

```
void setup()
  Serial.begin(115200);
  pinMode(led, OUTPUT);
  pinMode(trigpin, OUTPUT);
  pinMode(echopin, INPUT);
  wifiConnect();
  mqttConnect();
}
void loop() {
  bool isNearby = dist < 100;</pre>
  digitalWrite(led, isNearby);
  publishData();
  delay(500);
  if (!client.loop()) {
    mqttConnect();
  }
}
void wifiConnect() {
  Serial.print("Connecting to "); Serial.print("Wifi");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  }
  Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
}
void mqttConnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting MQTT client to "); Serial.println(server);
    while (!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
    initManagedDevice();
    Serial.println();
  }
}
void initManagedDevice() {
  if (client.subscribe(topic)) {
    // Serial.println(client.subscribe(topic));
```

```
Serial.println("IBM subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
  }
}
void publishData()
  digitalWrite(trigpin,LOW);
  digitalWrite(trigpin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigpin,LOW);
  duration=pulseIn(echopin, HIGH);
  dist=duration*speed/2;
  if(dist<100){
    String payload = "{\"Normal Distance\":";
    payload += dist;
    payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if (client.publish(publishTopic, (char*) payload.c_str())) {
     Serial.println("Publish OK");
    }
  }
    if(dist>101 && dist<111){</pre>
    String payload = "{\"Alert distance\":";
    payload += dist;
    payload += "}";
    Serial.print("\n");
    Serial.print("Sending payload: ");
    Serial.println(payload);
    if(client.publish(publishTopic, (char*) payload.c_str())) {
      Serial.println("Warning crosses 110cm -- it automaticaly of the loop");
      digitalWrite(led,HIGH);
    }else {
      Serial.println("Publish FAILED");
    }
  }
  void callback(char* subscribeTopic, byte* payload, unsigned int
payloadLength){
  Serial.print("callback invoked for topic:");
```

```
Serial.println(subscribeTopic);
for(int i=0; i<payloadLength; i++){
    dist += (char)payload[i];
}
Serial.println("data:"+ data3);
if(data3=="lighton"){
    Serial.println(data3);
    digitalWrite(led,HIGH);
}
data3="";
}</pre>
```

## **OUTPUT:**



