Assignment 4: Ultra sonic sensor

Program:

```
#include <WiFi.h>
#include <WiFiClient.h>
#include <PubSubClient.h>
const char* ssid = "Wokwi-GUEST";
const char* password = "";
#define ORG "4fvguz"
#define DEVICE_TYPE "ESP32"
#define DEVICE ID "ultrasonic sensor"
#define TOKEN "12345678"
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char pubTopic[] = "iot-2/evt/status1/fmt/json";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient wifiClient;
PubSubClient client(server, 1883, NULL, wifiClient);
#define ECHO PIN 13
#define TRIG_PIN 12
#define LED_BUILTIN 5
#define DHT PIN 15
void setup()
 Serial.begin(115200);
 pinMode(LED_BUILTIN, OUTPUT);
```

```
pinMode(TRIG_PIN, OUTPUT);
  pinMode(ECHO_PIN, INPUT);
  Serial.print("Connecting to ");
  Serial.print(ssid);
 WiFi.begin(ssid, password);
 while (WiFi.status() != WL CONNECTED)
   delay(500);
    Serial.print(".");
  Serial.println("");
  Serial.print("WiFi connected, IP address: ");
  Serial.println(WiFi.localIP());
 if (!client.connected())
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!client.connect(clientId, authMethod, token))
      Serial.print(".");
      delay(500);
    Serial.println("Bluemix connected");
float readDistanceCM() {
  digitalWrite(TRIG PIN, LOW);
  delayMicroseconds(2);
  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);
 int duration = pulseIn(ECHO_PIN, HIGH);
  return duration * 0.034 / 2;
void loop() {
  float distance = readDistanceCM();
 bool isNearby = distance < 100;</pre>
 digitalWrite(LED_BUILTIN, isNearby);
```

```
Serial.print("Measured distance: ");
Serial.println(readDistanceCM());

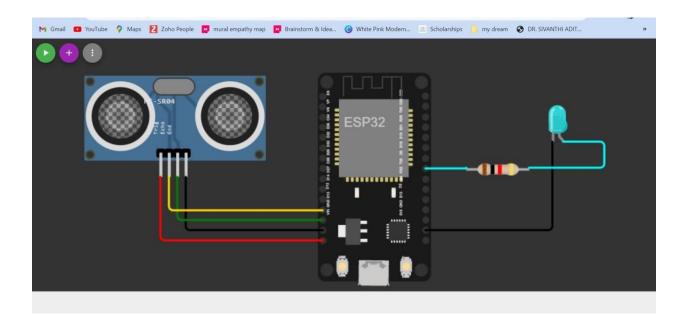
if(distance<100)
{
    String payload = "{\"d\":{\"Name\":\"" DEVICE_ID "\"";
        payload += ",\"Distance\":";
        payload += distance;
        payload += "}}";

    Serial.print("Sending value: ");
    Serial.println(payload);

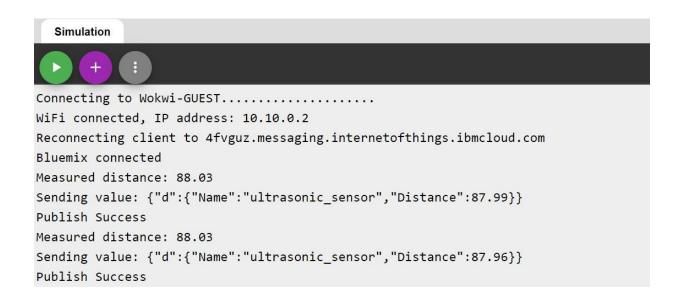
    if (client.publish(pubTopic, (char*) payload.c_str()))
    {
        Serial.println("Publish Success");
    }
    else
    {
        Serial.println("Publish Failed");
    }
}

delay(100);
}</pre>
```

Connections:



Output:



IBM Cloud:

