SPRINT_2

Team ID	PNT2022TMID13797	
Project Name	Smart Waste Management System for Metropolitan Cities	

AIM:

To create a device for the Cloudant database and IoT Watson Cloud platform. Publish data on the IoT Watson Cloud platform, such as bin weight and bin status values(level). Store user information in the Cloudant database, including user name, password, and Gmail. Using a local Node-RED application, to design the workflow for IoT contexts.

COMPONENTS:

S.NO	COMPONENTS	QUANTITY
1	Ultrasonic sensor	2
2	Servo motor	1
3	ESP32 Microcontroller	1
4	HX711 Load Cell	1
5	LCD 16*2 Display	1

DESCRIPTION:

The below code will display the status of both bin level and bin load for a single smart bin. The status of the bin level is shown in the 16*2 LCD display. The data obtained from the sensors is then published to the lot Watson Cloud Platform The sensor data can be visually depicted using node-red application.

CODE:

```
#include <ESP32Servo.h>
#include <LiquidCrystal_I2C.h>
#include <HX711.h>
#define DATA_PIN 12
#define CLOCK_PIN 14
#include <WiFi.h>
#include <PubSubClient.h>
WiFiClient wifiClient;
#define ORG "uuyxja"
#define DEVICE_TYPE "NodeMcu"
```

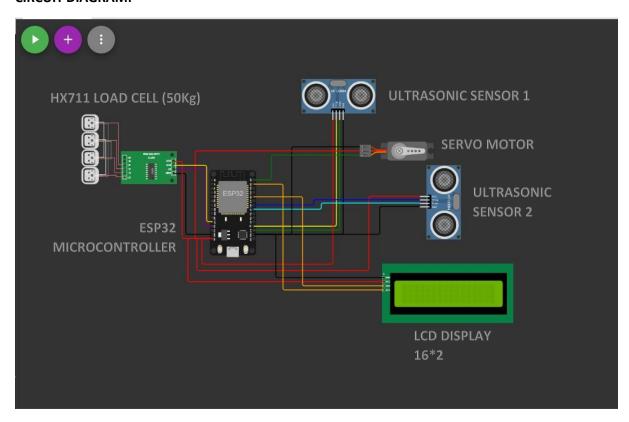
```
#define DEVICE_ID "12345"
#define TOKEN "23323850"
#define speed 0.034
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char topic[] ="iot-2/cmd/home/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
PubSubClient client(server, 1883, wifiClient);
void publishData();
const int trigpin=2;
const int echopin=15;
String command;
String data="";
long duration;
float dist;
LiquidCrystal_I2C LCD = LiquidCrystal_I2C(0x27, 16, 2);
Servo servo;
int trigPin1 = 2;
int echoPin1 = 15;
int trigPin2 = 18;
int echoPin2 = 5;
int duration1;
int distance1;
int duration2;
int distance2;
void setup()
Serial.begin(115200);
LCD.begin(16,2);
LCD.init();
LCD.backlight();
LCD.clear();
servo.attach(23);
Serial.begin(115200);
pinMode(trigPin1, OUTPUT);
pinMode(echoPin1, INPUT);
pinMode(trigPin2, OUTPUT);
pinMode(echoPin2, INPUT);
wifiConnect();
mqttConnect();
void loop() {
publishData();
delay(500);
if (!client.loop()) {
 mqttConnect();
```

```
void wifiConnect() {
Serial.print("Connecting to ");
Serial.print("Wifi");
WiFi.begin("Wokwi-GUEST", "", 6);
 while (WiFi.status() !=WL_CONNECTED) {
    delay(500);
    Serial.print(".");
Serial.print("WiFi connected, IP address: ");
Serial.println(WiFi.localIP());
void mqttConnect() {
   if(!client.connected())
     Serial.print("Reconnecting MQTT client to ");
     Serial.println(server);
     while (!client.connect(clientId, authMethod, token)) {
       Serial.print(".");
       delay(500);
       initManagedDevice();
       Serial.println();
void initManagedDevice() {
   if(client.subscribe(topic)) {
     Serial.println(client.subscribe(topic));
     Serial.println("subscribe to cmd OK");
else {
  Serial.println("subscribe to cmd FAILED"); }
void publishData()
  digitalWrite(trigPin1, LOW);
  delayMicroseconds(2);
  digitalWrite(trigPin1, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigPin1, LOW);
  duration1 = pulseIn(echoPin1, HIGH);
  distance1= duration1*0.034/2;
  delay(100);
  digitalWrite(trigPin2, LOW);
  delayMicroseconds(2);
  digitalWrite(trigPin2, HIGH);
  delayMicroseconds(10);
```

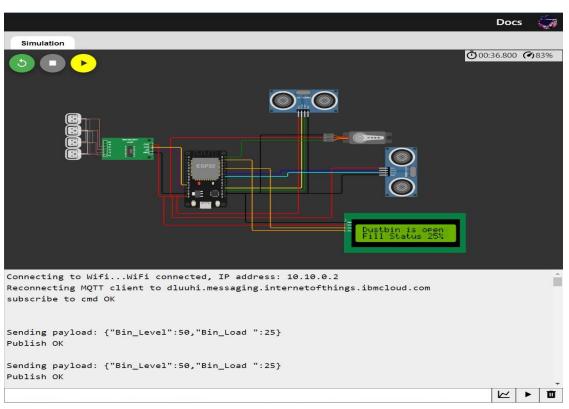
```
digitalWrite(trigPin2, LOW);
duration2 = pulseIn(echoPin2, HIGH);
distance2= duration2*0.034/2;
delay(100);
LCD.setCursor(0,1);
LCD.print("Fill Status ");
if(distance2>300 && distance2<=400){</pre>
  LCD.setCursor(12,1);
  LCD.print("25% ");
  String payload = "{\"Bin_Level\":";payload += "25";payload += ",\"Bin_Load
  payload += "12.5";
  payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
    } else {
      Serial.println("Publish FAILED");
else if(distance2 > 200 && distance2<= 299){</pre>
  LCD.setCursor(12,1);
  LCD.print("50%");
  String payload = "{\"Bin_Level\":";payload += "50";payload += ",\"Bin_Load
  payload += "25";payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
    Serial.println("Publish OK");
    } else {
      Serial.println("Publish FAILED");
      }
else if(distance2 >50 && distance2<=199){</pre>
  LCD.setCursor(12,1);
  LCD.print("75%");
  String payload = "{\"Bin_Level\":";payload += "75";payload += ",\"Bin_Load
  payload += "37.5";payload += "}";
  Serial.print("\n");
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
```

```
Serial.println("Publish OK");
     } else {
       Serial.println("Publish FAILED");
 }
 else{
   LCD.setCursor(12,1);
   LCD.print("100%");
   String payload = "{\"Bin_Level\":";
   payload += "100";payload += ",\"Weight \":"; payload += "50";payload +=
"}";
   Serial.print("Sending payload: ");
   Serial.println(payload);
   if (client.publish(publishTopic, (char*) payload.c_str())) {
     Serial.println("Publish OK");
     } else {
       Serial.println("Publish FAILED");
 if(distance1<=50){</pre>
   LCD.setCursor(0,0);
   LCD.print("Dustbin is open ");
   servo.write(90);
 else{
   LCD.setCursor(0,0);
   LCD.print("Dustbin is close ");
   servo.write(0);
```

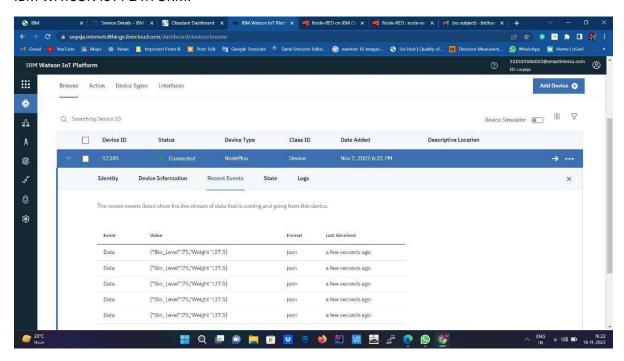
CIRCUIT DIAGRAM:



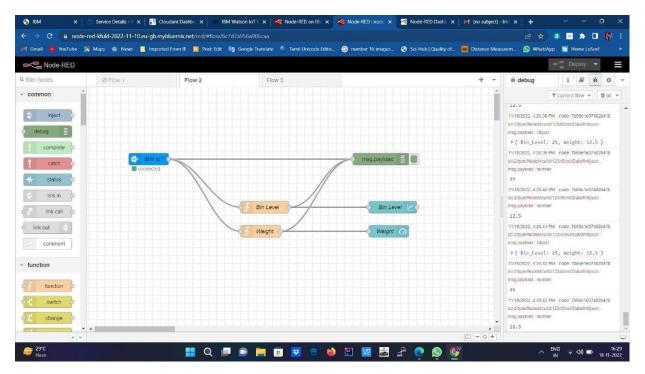
OUTPUT:



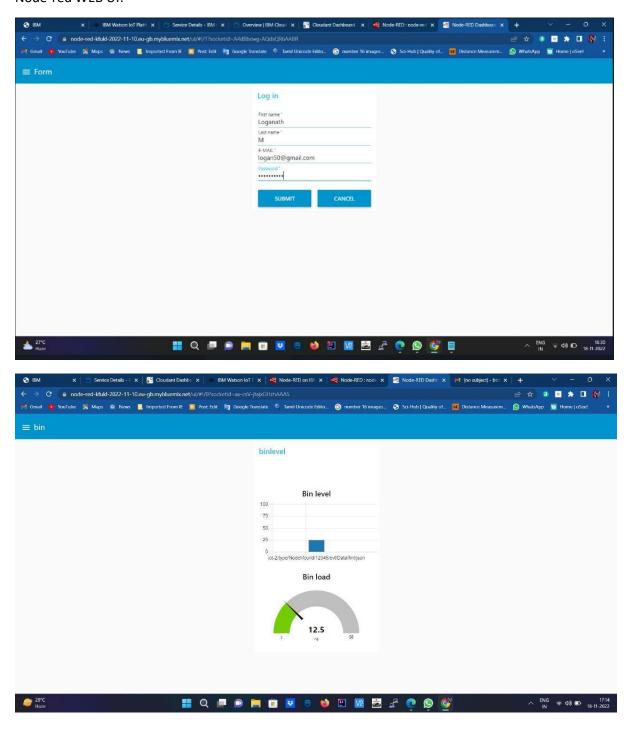
IBM WATSON IOT PLATFORM:



Node-red workflow:



Node-red WEB UI:



CLOUDANT DATABASE:

