

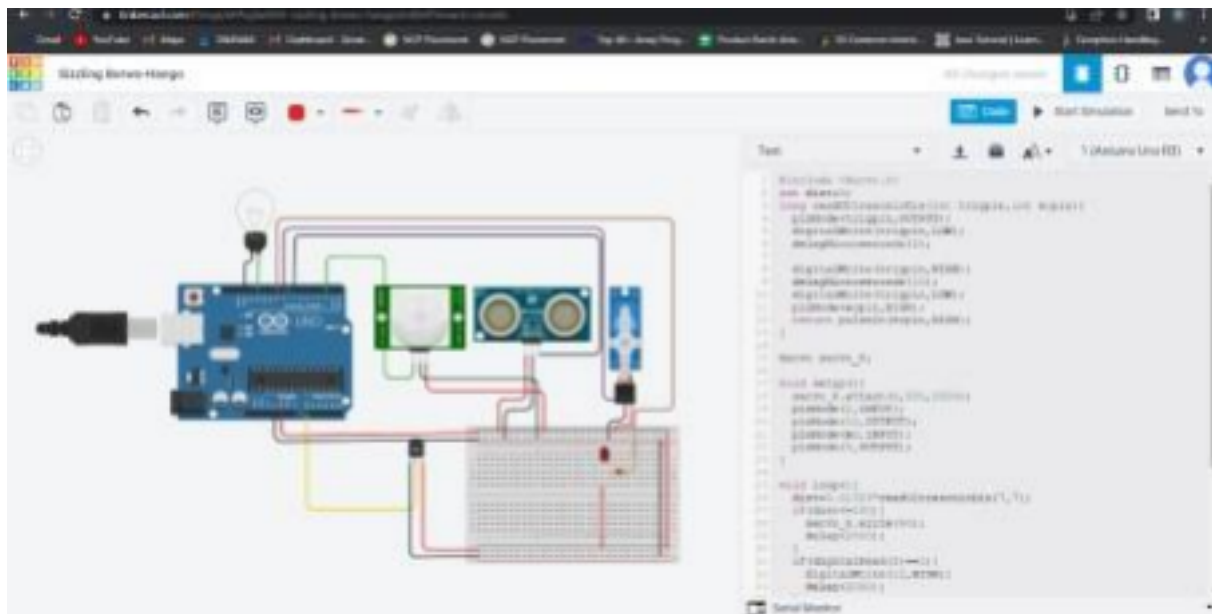
## ASSIGNMENT-1

P.THINAKARAN

73151921058

K.S.R. COLLEGE OF ENGINEERING

Screenshot :



Code:

```
#include <Servo.h>

int dist=0; long readUltrasonicDis(int
trigpin,int ecpin){
pinMode(trigpin,OUTPUT);
digitalWrite(trigpin,LOW);
delayMicroseconds(2);

digitalWrite(trigpin,HIGH);
delayMicroseconds(10);
digitalWrite(trigpin,LOW);
```

```
pinMode(ecpin,HIGH);  
return pulseIn(ecpin,HIGH);
```

```
}  
Servo servo_8;
```

```
void setup(){  
servo_8.attach(8,500,2500)  
; pinMode(2,INPUT);  
pinMode(12,OUTPUT);  
pinMode(A0,INPUT);  
pinMode(9,OUTPUT);  
}
```

```
void loop(){  
dist=0.01723*readUltrasonicDis(7,7)  
; if(dist<=100){ servo_8.write(90);  
delay(2000);  
} if(digitalRead(2)==1){  
digitalWrite(12,HIGH);  
delay(2000);  
} else{  
digitalWrite(12,LOW);  
delay(2000);  
}  
if(analogRead(A0)>200){  
digitalWrite(9,HIGH);  
delay(2000);  
}
```

```
else{  
digitalWrite(9,LOW);  
delay(2000)  
  
; }  
  
}
```