Project Development Phase

Sprint-3 Coding (Drowning Detection along with age prediction)

Date	10 November 2022
Team ID	PNT2022TMID51724
Project Name	VirtualEye - Life Guard For Swimming Pools To Detect Active Drowning
Maximum Marks	8 Marks

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app.py:
# import necessary packages
import cylib as cy
from cvlib.object_detection import draw_bbox
import cv2 import time import numpy as np import
math import argparse def getFaceBox(net,
frame,conf_threshold = 0.75):
                               frameOpencvDnn
= frame.copy()
                frameHeight =
frameOpencvDnn.shape[0]
                            frameWidth =
frameOpencvDnn.shape[1]
  blob = cv2.dnn.blobFromImage(frameOpencvDnn,1.0,(300,300),[104, 117, 123], True,
False)
  net.setInput(blob)
detections = net.forward()
bboxes = []
  for i in range(detections.shape[2]):
confidence = detections[0,0,i,2]
                                   if
confidence > conf threshold:
                                    x1 =
int(detections[0,0,i,3]* frameWidth)
                                         v1 =
int(detections[0,0,i,4]* frameHeight)
                                          x^{2} =
int(detections[0,0,i,5]* frameWidth)
                                         v2 =
int(detections[0,0,i,6]* frameHeight)
bboxes.append([x1,y1,x2,y2])
cv2.rectangle(frameOpencvDnn,(x1,y1),(x2,y2),(0,255,0),int(round(frameHeight/150)),8)
  return frameOpencvDnn, bboxes
faceProto = "opencv_face_detector.pbtxt"
faceModel = "opencv_face_detector_uint8.pb"
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ageProto = "age_deploy.prototxt" ageModel
= "age net.caffemodel"
genderProto = "gender_deploy.prototxt"
genderModel = "gender net.caffemodel"
MODEL_MEAN_VALUES = (78.4263377603, 87.7689143744, 114.895847746)
ageList = ['(0-2)', '(4-6)', '(8-12)', '(15-20)', '(21-24)', '(25-32)', '(38-43)', '(48-53)', '(60-100)']
genderList = ['Male', 'Female']
#load the network
ageNet = cv2.dnn.readNet(ageModel,ageProto) genderNet
= cv2.dnn.readNet(genderModel, genderProto) faceNet =
cv2.dnn.readNet(faceModel, faceProto)
# open webcam
webcam = cv2.VideoCapture(0) padding
= 20
if not webcam.isOpened():
print("Could not open webcam")
exit()
t0 = time.time() #gives time in seconds after 1970
#print('t0=',t0)
#variable dcount stands for how many seconds the person has been standing still for
centre0 = np.zeros(2) isDrowning = False
#this loop happens approximately every 1 second, so if a person doesn't move,
#or moves very little for 10seconds, we can say they are drowning
# loop through frames while
webcam.isOpened():
  # read frame from webcam
  status, frame = webcam.read()
  if not status:
    break
  \#small\_frame = cv2.resize(frame,(0,0),fx = 0.5,fy = 0.5)
  # apply object detection
  bbox, label, conf = cv.detect_common_objects(frame, confidence=0.25,
model='yolov3-tiny')
  print(bbox, label, conf)
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if(len(bbox)>0):
bbox0 = bbox[0]
\#centre = np.zeros(s)
    centre = [0,0]
     #for i in range(0, len(bbox)):
        #centre[i] = [(bbox[i][0]+bbox[i][2])/2,(bbox[i][1]+bbox[i][3])/2 ]
    centre = [(bbox0[0]+bbox0[2])/2,(bbox0[1]+bbox0[3])/2]
     #make vertical and horizontal movement variables
hmov = abs(centre[0]-centre0[0])
    vmov = abs(centre[1]-centre0[1])
     #there is still need to tweek the threshold
     #this threshold is for checking how much the centre has moved
    x=time.time()
    threshold = 10
#print("hmov=",hmov)
if(hmov>threshold or vmov>threshold):
       print(x-t0, 'sif')
t0 = time.time()
       isDrowning = False
     else:
                      print(x-t0,
'selse')
              if((time.time() - t0)
> 10):
                  isDrowning =
True
          small_frame = cv2.resize(frame,(0,0),fx = 0.5,fy = 0.5)
         frameFace ,bboxes = getFaceBox(faceNet,small_frame)
if not bboxes:
            print("No face Detected, Checking next frame")
continue
                   for bbox in bboxes:
                                                   face =
small_frame[max(0,bbox[1]padding):min(bbox[3]+padding,f
rame.shape[0]-1),
                 max(0,bbox[0]-padding):min(bbox[2]+padding, frame.shape[1]-1)]
            blob = cv2.dnn.blobFromImage(face, 1.0, (227, 227),
MODEL_MEAN_VALUES, swapRB=False)
            genderNet.setInput(blob)
genderPreds = genderNet.forward()
                                                gender =
genderList[genderPreds[0].argmax()]
            print("Gender: {}, conf = {:.3f}".format(gender, genderPreds[0].max()))
```

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ageNet.setInput(blob)
agePreds = ageNet.forward()
age = ageList[agePreds[0].argmax()]
print("Age Output : {}".format(agePreds))
            print("Age : {}, conf = {:.3f}".format(age, agePreds[0].max()))
            label = "{},{}".format(gender, age)
cv2.putText(frameFace, label, (bbox[0], bbox[1]-10),
cv2.FONT HERSHEY SIMPLEX, 0.8, (0, 255, 255), 2, cv2.LINE AA)
cv2.imshow("Age Gender Demo", frameFace)
          print("time : {:.3f}".format(time.time() - t0))
          #print("Entered in to true")
     #print('bounding box: ', bbox, 'label: ' label ,'confidence: ' conf[0], 'centre: ', centre)
     #print(bbox,label ,conf, centre)
          print('bbox: ', bbox, 'centre:', centre, 'centre0:', centre0)
     print('Is he/she drowning: ', isDrowning)
     #print('End of the program')
     centre0 = centre
       # draw bounding box over detected objects
# draw bounding box over detected objects
     out = draw bbox(frame, bbox, label, conf, write conf=True)
       # display output
     cv2.imshow("Real-time object detection", out)
  # press "Q" to stop
cv2.waitKey(1) \& 0xFF == ord('q'):
     break
# release resources webcam.release()
cv2.destroyAllWindows()
```