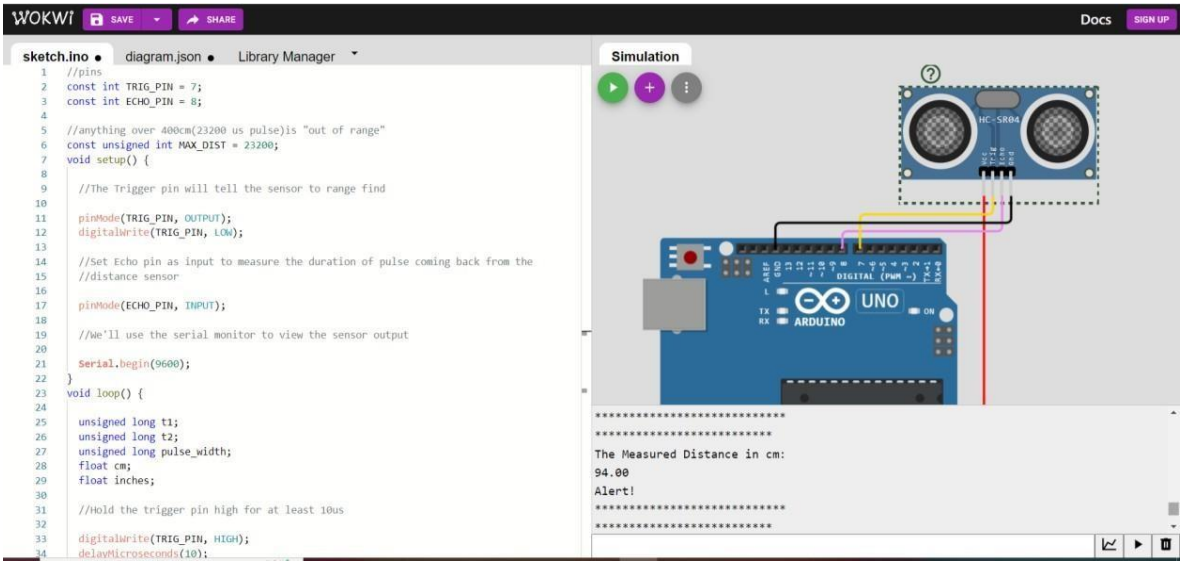
ASSIGNMENT-4

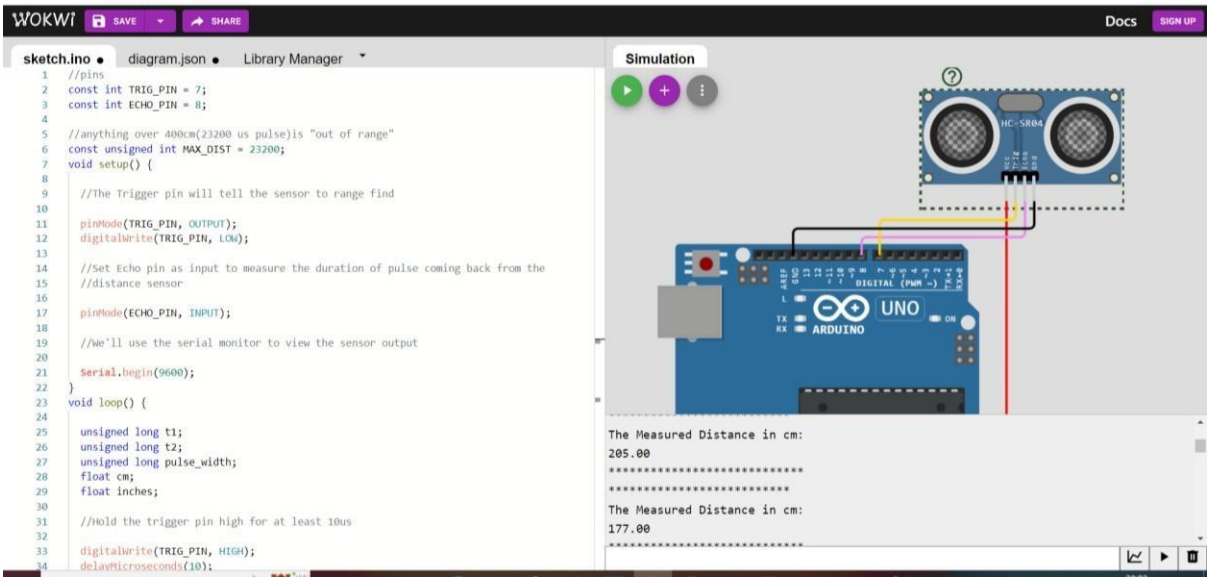
PROJECT TITLE: IOT Based Safety Gadget For Child Safety Monitoring And Notification

TEAM ID: PNT2022TMID12112

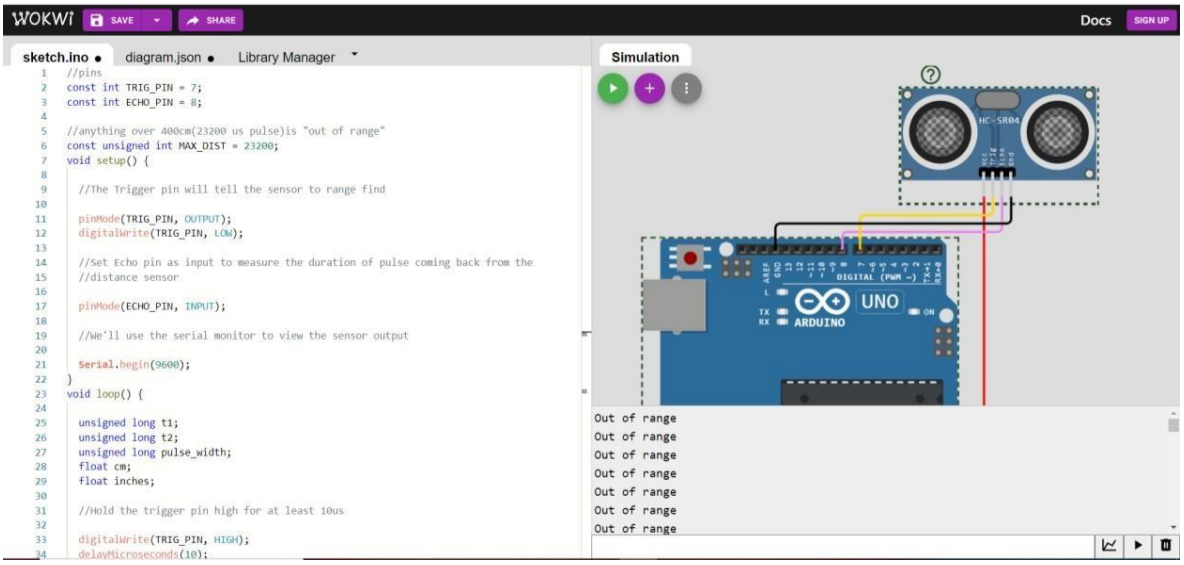
CASE 1: Distance less than 100cm ➔ It Alerts



CASE 2: Distance more than 100cm ➔ It won't Alert



CASE 3: Beyond limits ➔ Out of Range



CODING:

```
//pins
const int TRIG_PIN = 7;
const int ECHO_PIN = 8;

//anything over 400cm(23200 us pulse)is "out of range"
const unsigned int MAX_DIST = 23200;
void setup() {

  //The Trigger pin will tell the sensor to range find

  pinMode(TRIG_PIN, OUTPUT);
  digitalWrite(TRIG_PIN, LOW);

  //Set Echo pin as input to measure the duration of pulse coming back from
the
  //distance sensor

  pinMode(ECHO_PIN, INPUT);

  //We'll use the serial monitor to view the sensor output

  Serial.begin(9600);
}
void loop() {

  unsigned long t1;
  unsigned long t2;
  unsigned long pulse_width;
  float cm;
  float inches;

  //Hold the trigger pin high for at least 10us

  digitalWrite(TRIG_PIN, HIGH);
  delayMicroseconds(10);
  digitalWrite(TRIG_PIN, LOW);

  //wait for pulse on echo pin

  while (digitalRead(ECHO_PIN) == 0);

  //Measure how long the echo pin was held high (pulse width)
  //note the micros()counter will overflow after -70min
```

```
  t1 = micros();
  while (digitalRead(ECHO_PIN) == 1);
  t2 = micros();
  pulse_width = t2 - t1;

  //calculate distance in centimeters and inches. The constantsare found in
the
  //datasheet,and calculated from the assumed speed of sound in air at sea
level(-340m/s)

  cm = pulse_width / 58;
  inches = pulse_width / 148.0;

  //print out results

  if (pulse_width > MAX_DIST) {

    Serial.println("Out of range");
  }
  else
  {
    Serial.println("**************************");
    Serial. println("The Measured Distance in cm:");
    Serial.println(cm);

    if (cm < 100)
    {
      //while (true)
      {
        Serial.println("Alert!");
      }
    }
    Serial.println("**************************");
  }

  //wait at least 1000ms before next measurement

  delay(1000);
}
```

CIRCUIT: